

AD-A107 481

ARMY PROJECT MANAGER FOR TRAINING DEVICES ORLANDO FL
SIMULATED TANK ANTI-ARMOR GUNNERY SYSTEM (STA65).(U)

F/G 19/5

NOV 81 A MARSHALL, B SHAW, H TOWLE

UNCLASSIFIED

PM TRADE-RE-U010

NL -

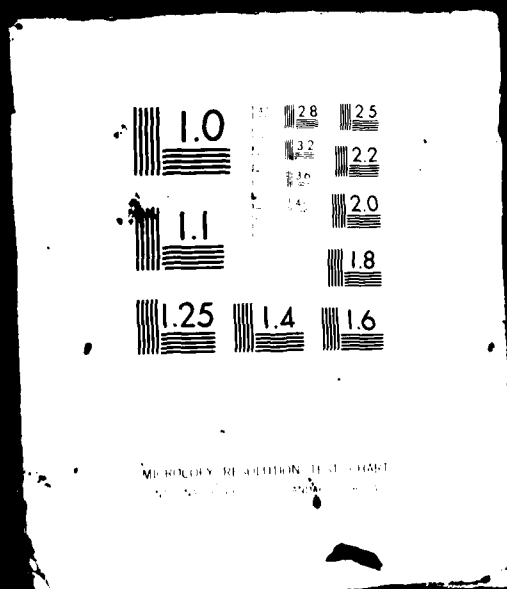
1-2
AD-A107 481



1 OF 2

AD-

A107481



LEVEL II

(2)

**SIMULATED TANK
ANTI-ARMOR GUNNERY SYSTEM
(STAGS-D)**

AD A107481

BY Albert Marshall
Dr. Herbert Towle
Bon Shaw
Gary Bond
George Siragusa



DTIC
ELECTE
NOV 18 1981
S **D**
E

DRAGON TRAINER

PREPARED FOR

**U.S. ARMY PROJECT MANAGER FOR TRAINING DEVICES
NAVAL TRAINING EQUIPMENT CENTER (NTEC)
ORLANDO, FLORIDA 32813**

BY

**ADVANCED SIMULATION CONCEPTS LABORATORY
SIMULATION TECHNOLOGY BRANCH**

NOVEMBER 1981

This document has been approved
for public release and sale; its
distribution is unlimited.

01 11 16 025

DTIC FILE COPY

REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER PM-TRADE - RE - 0010	2. GOVT ACCESSION NO. AD A107481	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) Simulated Tank Anti-Armor Gunnery System (STAGS).		5. TYPE OF REPORT & PERIOD COVERED Interim Report.
7. AUTHOR(s) Albert Marshall, Bon Shaw, Dr. Herbert/Towle, George Siragusa and Gary Bond		6. PERFORMING ORG. REPORT NUMBER
9. PERFORMING ORGANIZATION NAME AND ADDRESS Naval Training Equipment Center N-73 Orlando, FL 32813		8. CONTRACT OR GRANT NUMBER(s) Project 1785
11. CONTROLLING OFFICE NAME AND ADDRESS (305/646-5771) U. S. Army (DRCPM-TND-RE) Project Manager for Training Devices, Orlando, FL		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS 62727A230
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)		12. REPORT DATE October 1981
		13. NUMBER OF PAGES 2813
		15. SECURITY CLASS. (of this report) Unclassified
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report) Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18. SUPPLEMENTARY NOTES		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) Trainer DRAGON Multiprocessor Infantry Missile Anti-Armor Microprocessor Anti-Tank TOW		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) This report describes a missile flight simulator research model developed to train DRAGON gunners. It is also being adapted to a variety of similar anti-armor weapons. The system employs a terrain board with enemy armored vehicles moving in a variety of attack scenarios. When the gunner fires the missile, hears computer generated rocket sounds and experiences the weight loss, recoil and smoke of the missile launch. When the smoke clears, he views the missile in the sight as well as the target. The gunner's aiming error is measured		

DD FORM 1 JAN 73 1473

EDITION OF 1 NOV 65 IS OBSOLETE
S/N 0102-014-6601

SECURITY CLASSIFICATION OF THIS PAGE (When Data Entered)

20. using a micro-processor-controlled diode matrix array. The matrix detector senses an IR emitting diode which is located on the miniature target. The flight equations of motion for the missile are solved by a 16 bit microprocessor every 0.02 seconds in each axis using gunner aiming error, target position, gravity, drag and side thruster accelerations as inputs. A second coordinated 16 bit processor controls a display that plots both vertical and horizontal aiming error for analysis of the gunner's performance by an instructor. Experienced DRAGON gunners have tested the system and attested to the realism and training potential

SUMMARY

The Simulated Tank and Anti-Armor Gunnery Systems (STAGS) is an electro-optic based, multiprocessor controlled, training device that enables training of DRAGON gunners at a reasonable cost. In a short period of time a gunner can be subjected to a variety of target scenarios and his performance can be analyzed in real-time by an instructor. When the trainee fires the training device he hears the initial explosion of the rocket motor. He experiences a weight loss due to the simulated rocket exiting the tube as well as a recoil force. Momentarily his view in the sight is obscured by simulated smoke. The trainee must overcome such launch transients and smoothly track the target and ignore the simulated missile which he can see in his sight. Thruster rocket firing sounds are included as well as the final hit or ground impact explosions. A visual indication of missile impact is also inserted into the gunners sight.

During missile flight the instructor can monitor two displays. These displays show:

- (1) The gunner's sight picture, the DRAGON missile's location, and
- (2) a plot of gunner aiming error versus time and the gunner error tracking limit envelopes. Thruster firings are annotated on the display.

This system uses a 16 bit microprocessor to solve the flight equations every 0.02 seconds in each axis using the gunner's aiming error, target position, gravity, drag and thruster rocket acceleration as inputs. The solution also incorporates the dynamic performance of the tracker.

A prototype model was constructed by the Advanced Simulations Concepts Laboratory, Naval Training Equipment Center, Orlando, Florida for the U.S. Army Project Manager for Training Devices (PM TRADE) and the U.S. Marine Corps.

This model has been successfully evaluated by experienced DRAGON gunner teams from both the U.S. Army and U.S. Marine Corps.

Demonstrations and evaluations are planned during FY 82 using this device. Expansion of the device to include TOW is also planned.

The PM TRADE Project Manager is A. Boudreaux. The authors wish to thank him for the helpful assistance he gave during this program.

Accession No.	
NTIS	
DTIC	
USDA	
JA	
X	
A	

TABLE OF CONTENTS

	PAGE NUMBER
I. Introduction-----	1
II. System Description-----	7
III. System Design-----	15
A. Electro Optics Subsystem-----	15
B. Multiprocessor Subsystem-----	17
C. Computer Graphics and Video Subsystem-----	22
D. Computer Generated Sound System-----	30
E. Miniature Target Board-----	35
F. Weight Loss and Recoil Mechanism-----	39
G. Pull Down Measurement and Reticule Insertion-----	39
IV. Conclusions-----	44
Appendix	
A. DRAGON Flight Simulation Equations-----	A-1
B. Multiprocessor Main Programs-----	B-1
C. Computer Graphics and Video Subsystem Program-----	C-1
D. Computer Generated Sound System Programs-----	D-1

LIST OF ILLUSTRATIONS

PAGE NUMBER

I-1	DRAGON System	3
I-2	Student Station and Instructors Console	4
I-3	Instructor Console	5
I-4	Terrain Board and Target	6
II-1	System Block Diagram	8
II-2	Data Print-Out (Hit)-Six Graphs	9-11
II-3	Data Print-Out (Miss)-Six Graphs	12-14
III-1	Electro Optic Subsystem Block Diagram	17
III-2	Simulation Block Diagram	19
III-3	Horizontal Plane Geometry	20
III-4	Multiprocessor Subsystem	23
III-5	Computer Graphics and Video Subsystem	25
III-6	Dragon Gunner's Sight System	27
III-7	RG-512 Functional Block Diagram	29
III-8	Sound System Functional Block Diagram	32
III-9	Sound System Schematic	33
III-10	Stepper Motor Controller (Position Measurement)	34
III-11	Stepper Motor Controller (CY-512 Interface)	36
III-12	Stepper Motor Drivers	37
III-13	Turret Controller	38
III-14	Recoil and Weight Loss Circuit	40
III-15	Pull Down Measurement Circuit	41
III-16	Reticle Insertion Circuit	43
A-1	Simulation Block Diagram	A-3
A-2	Horizontal Plane Geometry	A-4
A-3	Dragon Launch Sequence Time Line	A-5
A-4	Gunner Error Limits	A-7

SECTION I

INTRODUCTION

Training in the firing of modern anti-armor weapons is expensive. Each live round costs thousands of dollars.

This report describes a system that uses advanced electro-optics and micro-processor technology to enable training of DRAGON gunners at a reasonable cost.

The DRAGON is a command-to-line-of-sight guided missile system. Fired from a recoilless launcher, the missile is tracked optically and guided automatically to the target by electrical impulses transmitted via a wire link. Firing the DRAGON missile is accomplished by depressing the safety and squeezing the trigger. No other action is required of the gunner except to keep the sight cross hairs on the target. However, to score a hit the trainee must overcome many perturbations that can spoil his track.

When the trainee fires the training device he hears the initial explosion of the rocket motor. He experiences a simulated weight loss due to the rocket exiting the tube as well as a recoil force. Momentarily he is blinded in the sight by simulated smoke. The trainee must overcome such launch transients. He must smoothly track the target and ignore the simulated missile which he can see in his sight. Thruster rocket firing sounds are included as well as the final hit or ground impact explosions. A visual indication of hit is also inserted into the gunner's sight.

During missile flight the instructor can monitor two displays. These displays show:

- (1) The gunner's sight picture and the DRAGON's location.
- (2) Plots of gunner aiming error in azimuth and elevation versus time and the gunner error tracking limit envelopes. Thruster firings are annotated on the display and the number of thruster firings, actual versus ideal are recorded.
- (3) The instructor can recall four additional plots after the mission is over: gunner aiming error and missile location in azimuth versus time; gunner aiming error and missile location in elevation versus time.

This system uses a 16 bit microprocessor to solve the flight equations every 0.02 seconds in each axis using the gunner's aiming error, target position, gravity, drag and thruster rocket acceleration as inputs. The solution also incorporates the dynamic performance of the DRAGON tracker.

Key features of the system are summarized below.

- . Target hit or miss determined by solving DRAGON flight equations in real time
- . Smoke obscuration

- . Recoil
- . Weight Loss
- . Missile superimposed on gunner's view of scenario
- . Sounds - thruster firing, launch, hit and miss explosions, gyro wind-up
- . Gunner aiming errors versus time displayed in real time
- . Missile position versus time which can be recalled along with gunner aiming errors in azimuth and elevation for analysis
- . Expensive tank target and special range is not required for training
- . Number of thruster rocket firing's ideal versus actual displayed
- . Portable
- . Record and play back capability
- . Can operate with and without an instructor
- . Can be used to simulate night firings with a thermal sight
- . Gunner's pull down force on DRAGON launcher, and eye piece pressure is indicated
- . Variety of target speeds and motions simulated
- . Trainer flies like real missile because of computation of flight parameters

Photographs of the system are shown in Figure I-1 through I-4 and illustrate the student station, instructors console, and the terrain board.

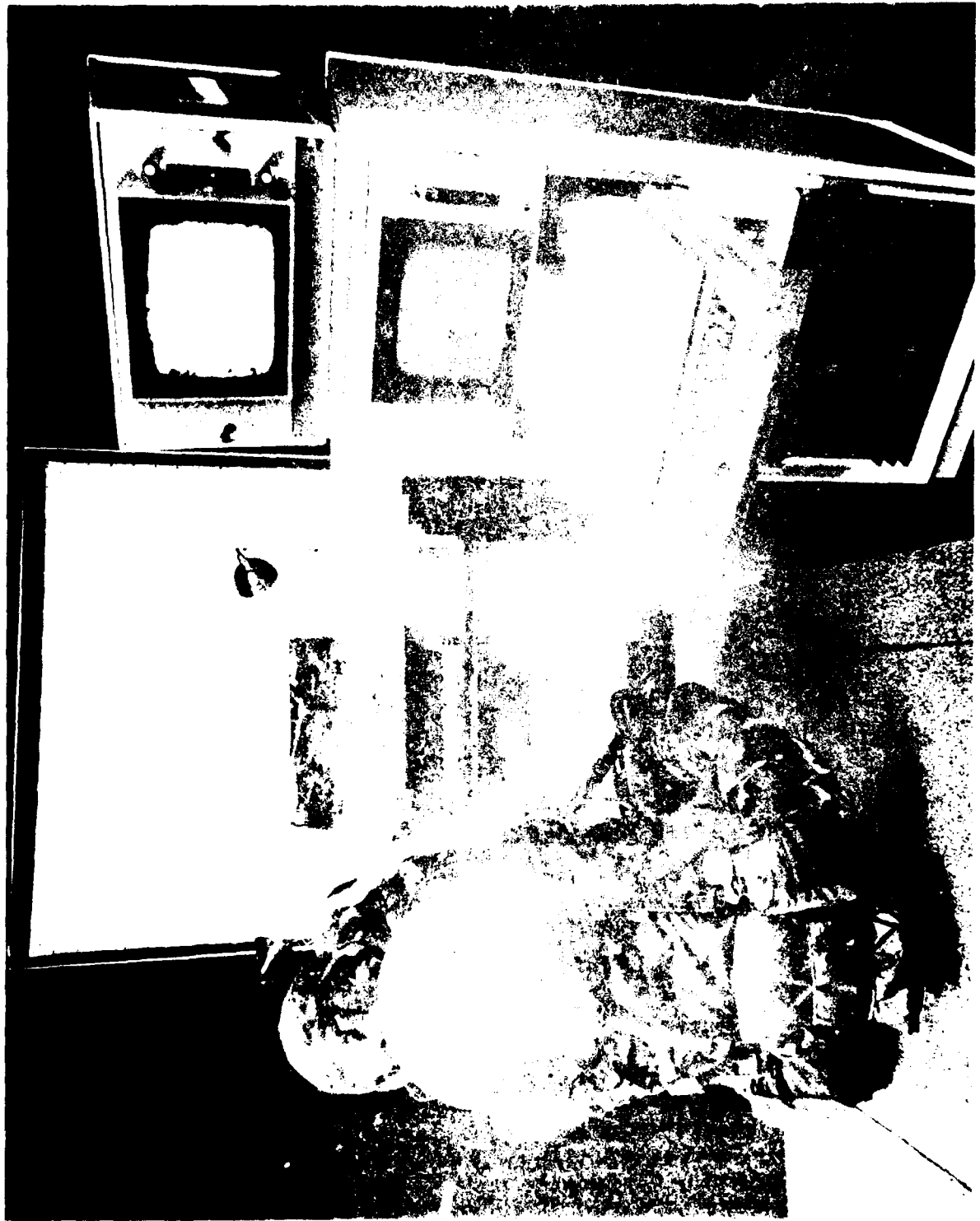


FIGURE I-1 DRAGON SYSTEM



FIGURE 1-2: UDEF TAT AND GTRU R'S 'SELF

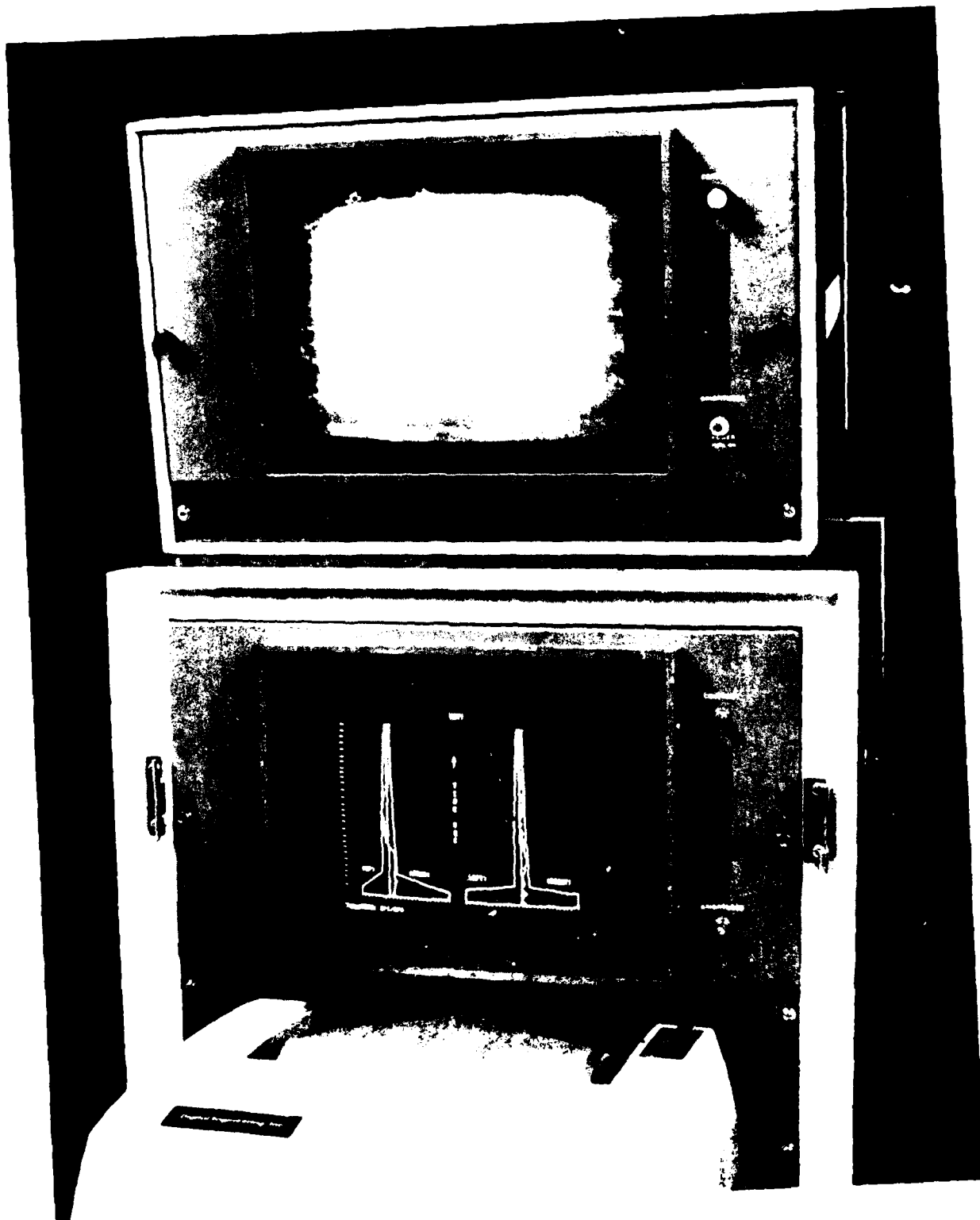


FIGURE 1-4 INSTRUCTOR CONSOLE



SECTION II

SYSTEM DESCRIPTION

The system block diagram is shown in Figure II-1.

Targets in this system are 1/120 miniature models. Model targets were chosen because they have better resolution than either computer generated imagery or a movie display. DRAGON utilizes a 6X sighting scope. In other weapons even higher power sighting scopes are utilized, thus demanding a high resolution visual scenario.

Models are moved on a terrain board using a stepper motor under the control of a single chip microprocessor. The engagement scenario is stored in the Personnel Interface Processor (PIP) and is selected on the instructor's console by an input terminal. The stored scenario program contains the tank target's velocities, directions and range. Scenario data are provided to the DRAGON Flight Simulator Processor (DFS). At the center of mass of the scaled target is an Infrared Emitting Diode (IRED). Located in the DRAGON launch tube is a photo diode array camera to sense the IRED. The IRED is invisible to the human eye. This 100 x 100 matrix camera is boresighted to the gunner's sight telescope and used to determine the gunner's aiming error (GAE) which is input to the DRAGON Flight Simulator processor. This processor solves the DRAGON flight equations and provides DRAGON status to the Personnel Interface Processor (PIP). The PIP controls the graphics units which inserts the missile, smoke, explosion, etc., into the gunner's sight. This processor also controls the Gunner Aiming Error (GAE) display on the Instructor's Console. This display plots GAE versus time, in real time. The DRAGON Flight Simulator Processor produces launch and target explosions, thruster rocket firings and gyro noises. The thruster rocket firings are delayed to allow for the speed of sound versus the visual phenomena of the rocket firing which is optically inserted in the DRAGON gunner's sight. Rocket thruster noises are attenuated as a function of distance.

A closed circuit TV (CCTV) is located on the DRAGON tube and boresighted to the gunner's 6X sight. The Gunner's Sight Picture Display is located on the instructor's console. The DRAGON rocket as seen by the trainee is also mixed into the gunner's sight picture visual display.

An indicator on the instructor's console indicates the amount of pulldown pressure on the launcher tube. Automatic computer controlled boresight is also incorporated.

Data print-outs for both a hit and miss training session are shown in Figures II-2 and II-3. Note that the rocket thruster firings are annotated on the left hand margin with dashes indicating the firing of a thruster rocket pair. Time between thruster firings are a function of the rate of change of gunner aiming error.

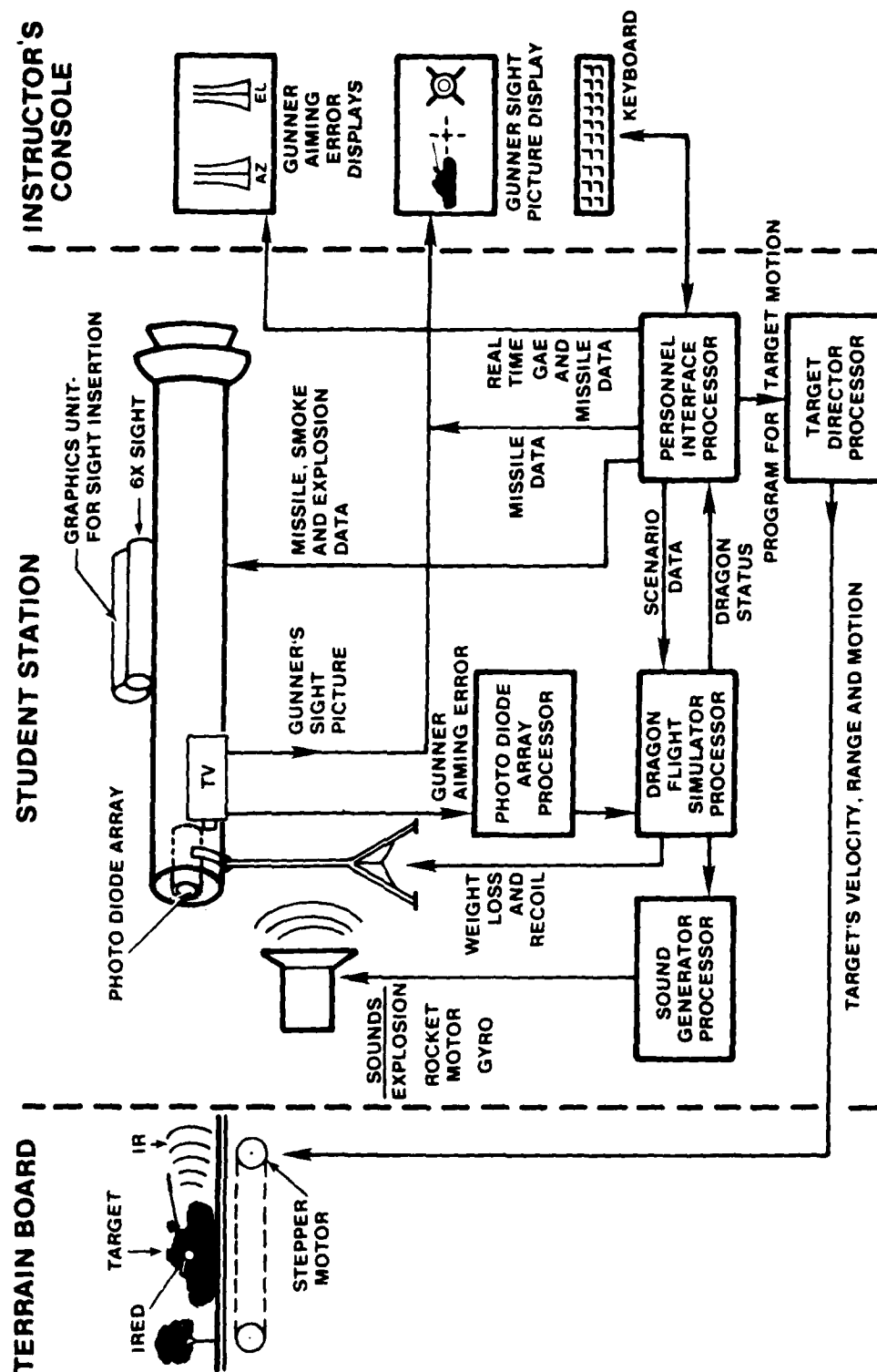


FIGURE 11-1 SYSTEM BLOCK DIAGRAM

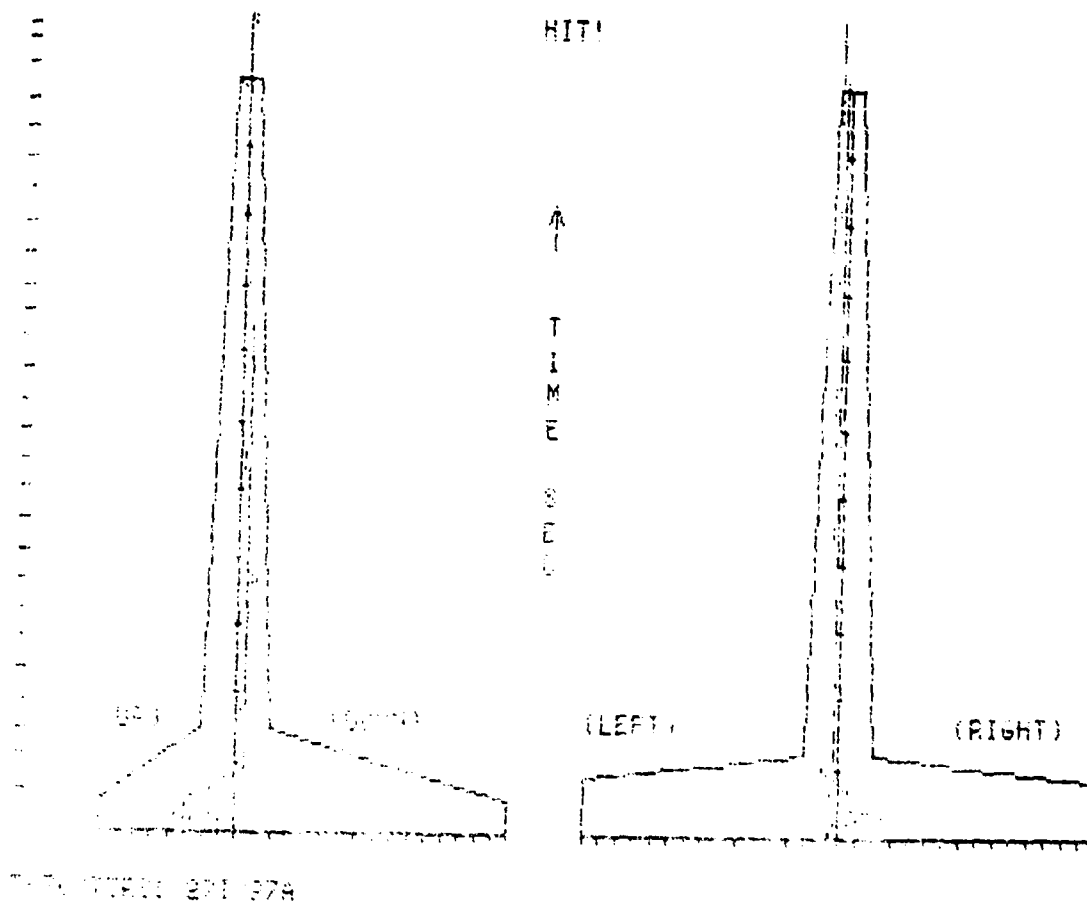


FIGURE II-2 (1 of 3)

GAE vs Time

(Vertical & Horizontal Planes)

- HIT

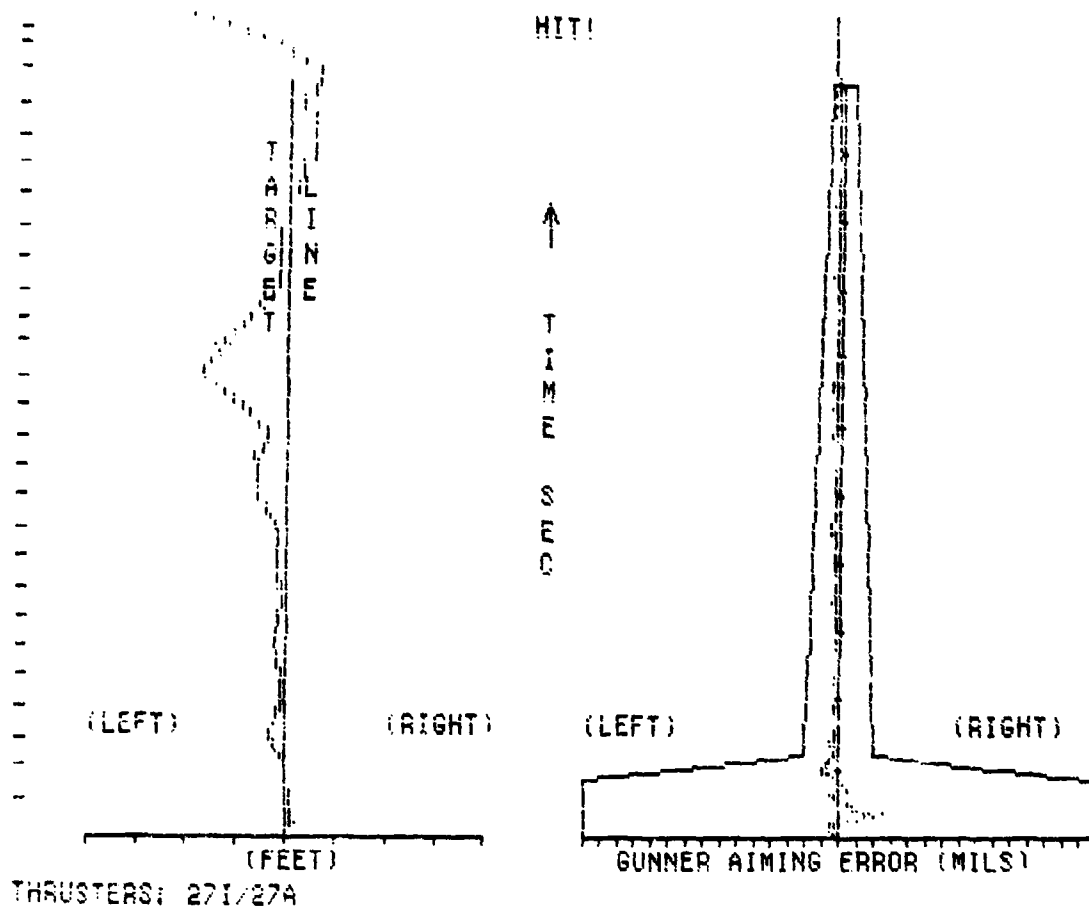


FIGURE II-2 (2 of 3) Missile Location GAE vs Time
 vs
 Time (Horizontal Plane) (Horizontal Plane)
 - HIT

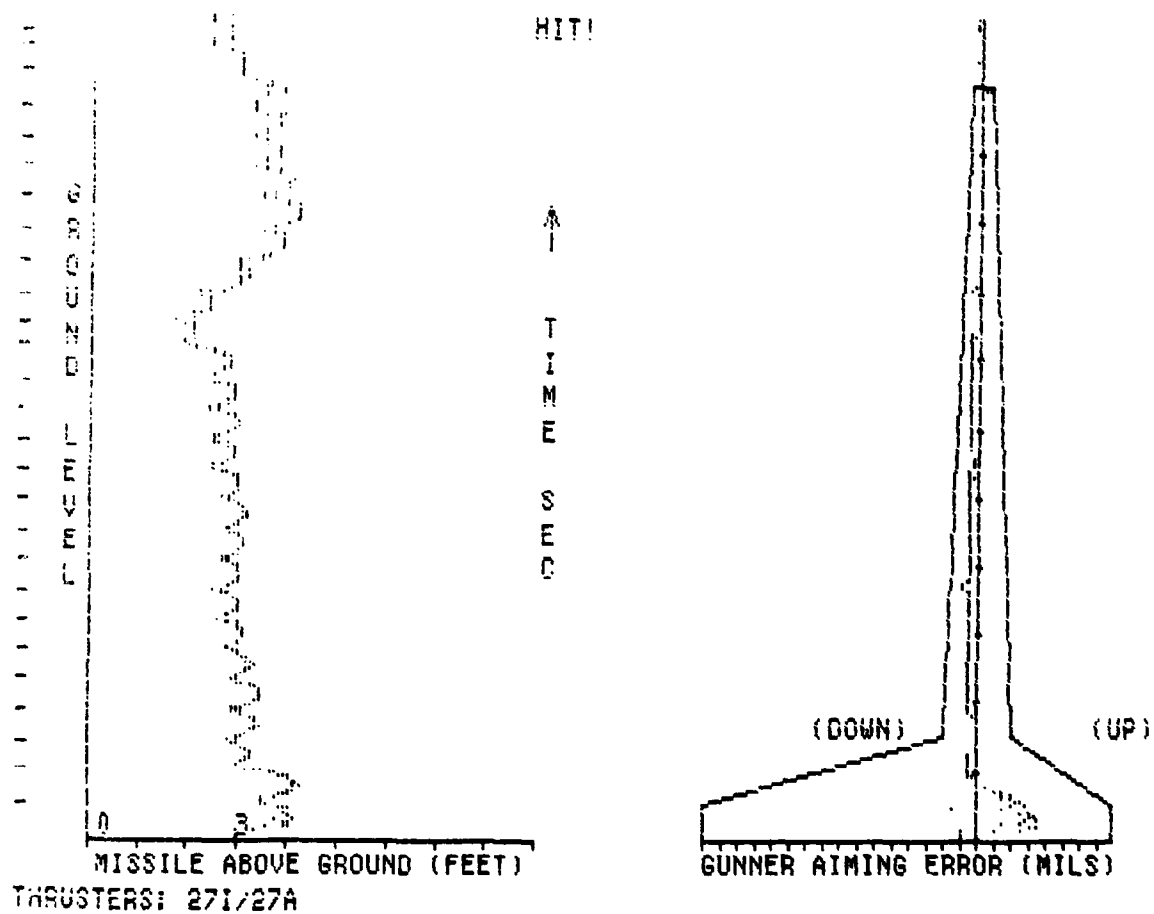


FIGURE II-2 (3 of 3) Missile Location GAE vs Time
 vs
 Time (Vertical Plane) (Vertical Plane)
 -HIT

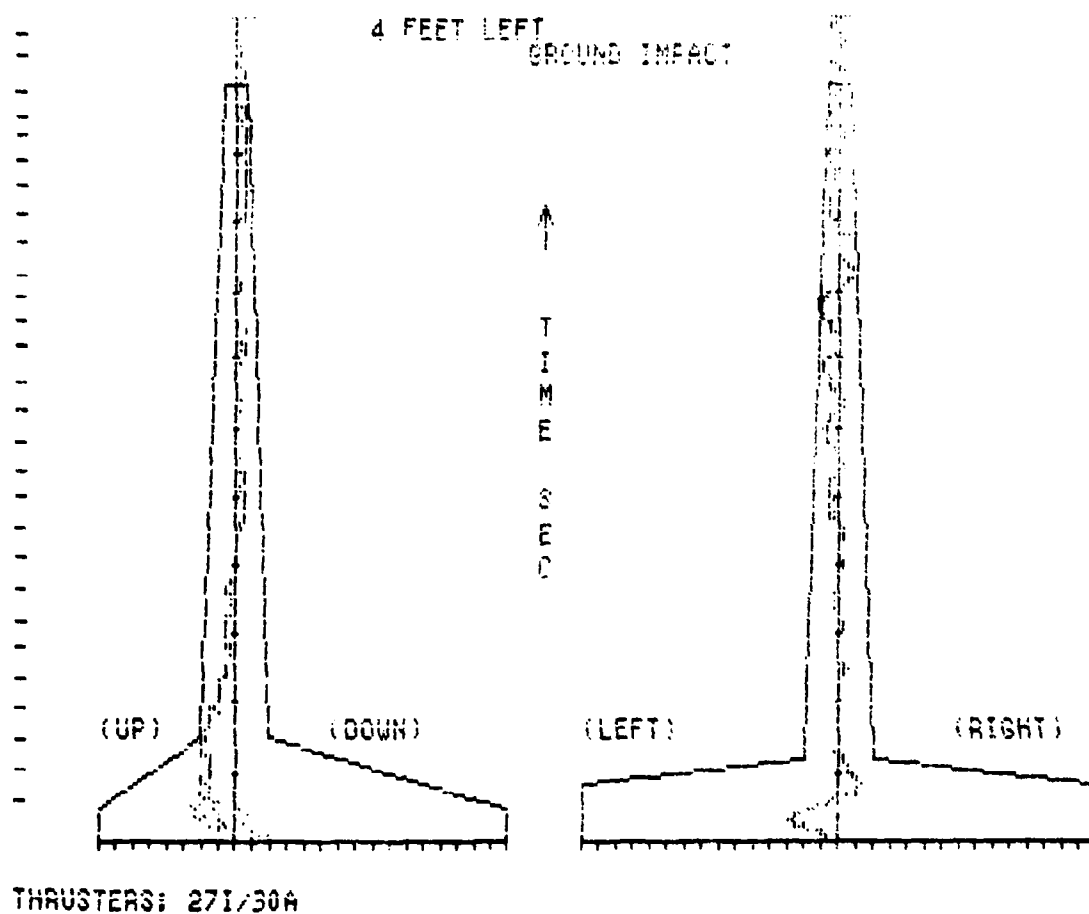


FIGURE II-3 (1 of 3)

GAE vs Time

(Vertical & Horizontal Planes)

-MISS

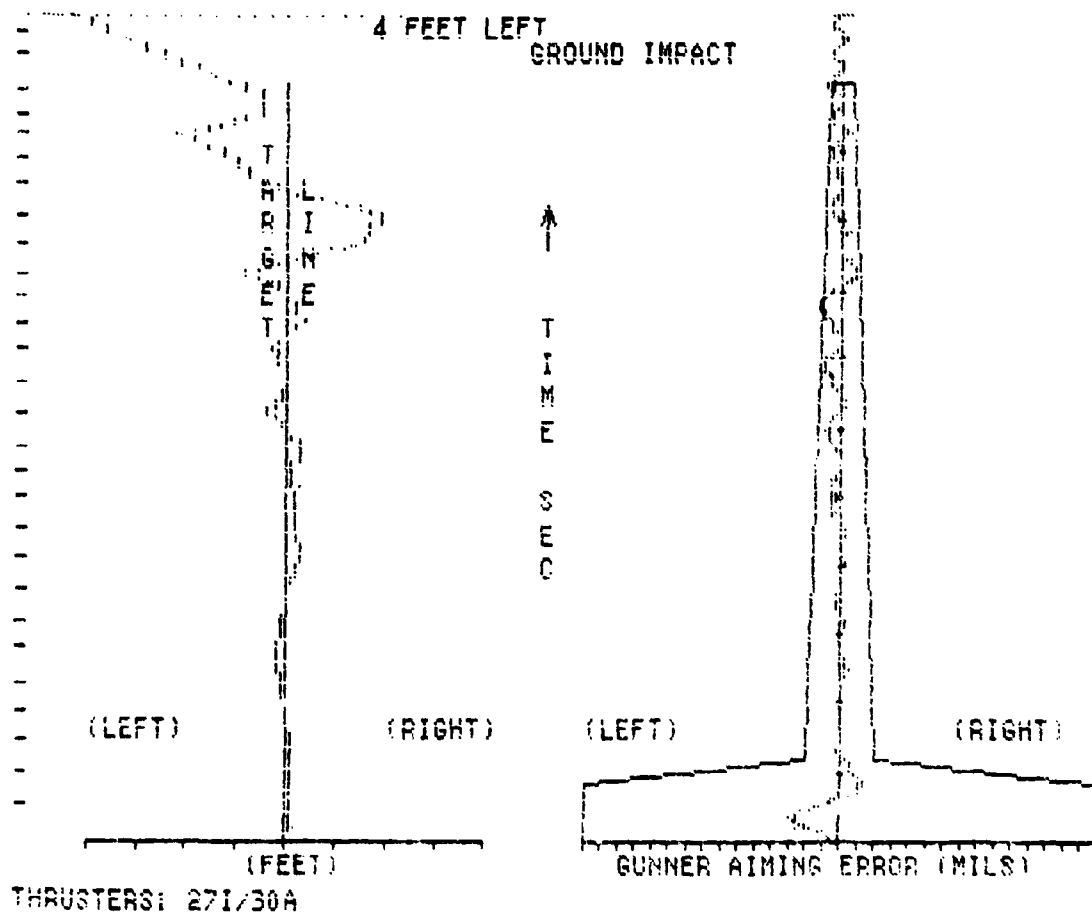


FIGURE II-3 (2 of 3) Missile Location GAE vs Time
 vs
 Time (Horizontal Plane) (Horizontal Plane)

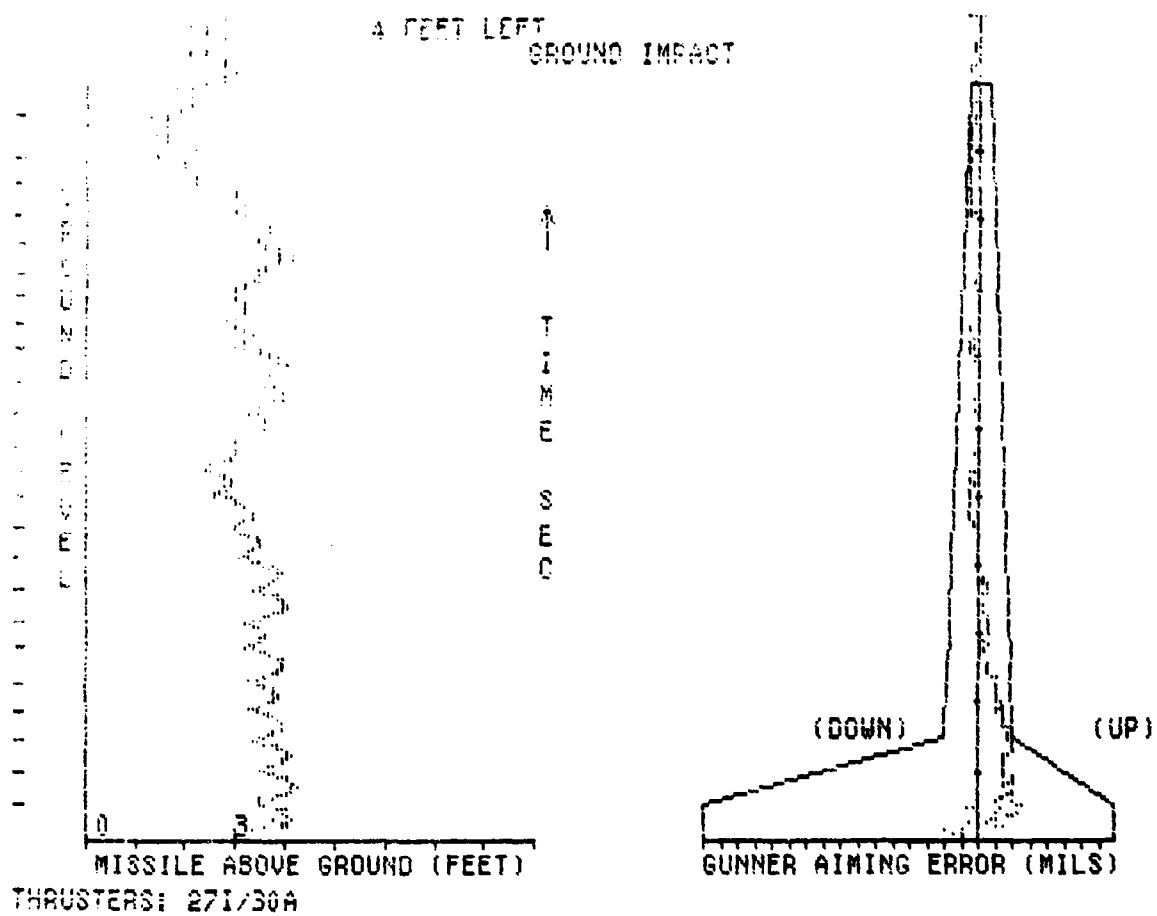


FIGURE II-3 (3 of 3)

Missile Location

GAE vs Time

vs

Time (Vertical Plane)

(Vertical Plane)

- MISS

SECTION III

SYSTEM DESIGN

A. Electro-Optics Subsystem

In order to solve the DRAGON flight equations several input parameters are required. These parameters are:

- (a) trigger pull
- (b) target position and range
- (c) gunner aiming error

The STAGS measures the gunner aiming error with respect to a selected aim point on the miniature tank target, using the electro-optics subsystem.

Gunner aiming errors are determined by sensing the IRED on the target using a 100 x 100 matrix solid-state camera. The IRED is invisible to the human eye.

Solid-state imaging cameras are functionally similar to videcon type TV cameras, but with the added advantages of greater geometric accuracy, extended spectral range, higher sensitivity and scan rates, digital output, small size, low voltage and power requirements and the ruggedness and reliability of solid-state design.

The sensor is a solid-state photodiode array matrix having 10,000 pixels (100 x 100). The choice of lens determines the field viewed by the matrix camera. Using a 125 mm focal length lens and a target model distance of 22 feet, we have a field of view (FOV), of 1.05 feet or 48 milliradians. This FOV will accommodate the maximum excursions allowed for DRAGON, i.e., 32 mr horizontal and 22 mr vertical.

For a 1.05 ft FOV one pixel represents 0.126 inches on the terrain board.

Since the array is square the lengths in the X and Y axes are identical. The magnification, M, of the camera is the ratio of the FOV to the length of the array:

$$M = \frac{\text{FOV}}{\text{Array Length}}$$

where the array length is = 0.24 in. (0.60 cm total width/height) in both X and Y.

$$M = \frac{1.05 \times 12}{0.24} = 52.5$$

The static resolution is the array element spacing imaged into the object plane.

$$\text{Resolution} = \text{Magnification} \times \text{element spacing}$$

Resolution = $52.5 \times .0024 \text{ in.} = 0.126 \text{ inches}$

This is equivalent to $\pm 7.5 \text{ in.}$ resolution on a real world tank at the scaled range of 2,640 feet.

If a longer focal length lens is used the FOV is decreased and the resolution is improved.

Accuracy also depends on: image sharpness, contrast, vibration or movement of the object, light level and threshold setting of the camera.

The camera used is blemish free.

An IRED is located on the scaled model target and the center of the IRED's energy is calculated to determine hit location.

Because the IRED produces uniform illumination, the threshold setting on the camera can be adjusted to a fixed level, thus eliminating background interference.

The data from the photodiode array is electronically scanned to produce a sampled-and-held video output signal. The amplitude of each pixel is proportional to the incident light intensity integrated over the interval of one frame period. The camera essentially detects light to dark transitions of the digital area. The scene present on the camera is a light circle on a dark background. Transition data from the camera, stored as a digital line-by-line picture of the array, is handled by an interface unit. The DRAGON Flight Simulator Processor determines the GAE, from the transition data.

The electro-optic subsystem consists of the following equipments. (See Figure III-1)

Reticon MC 520 Camera

Reticon RS 520 Controller

Reticon RSB-6020 Interface Board

Nikon Zoom Lens (set at 125mm)

The RSB-6020 directly couples Reticon imaging cameras to Intel SBC/Multibus systems.

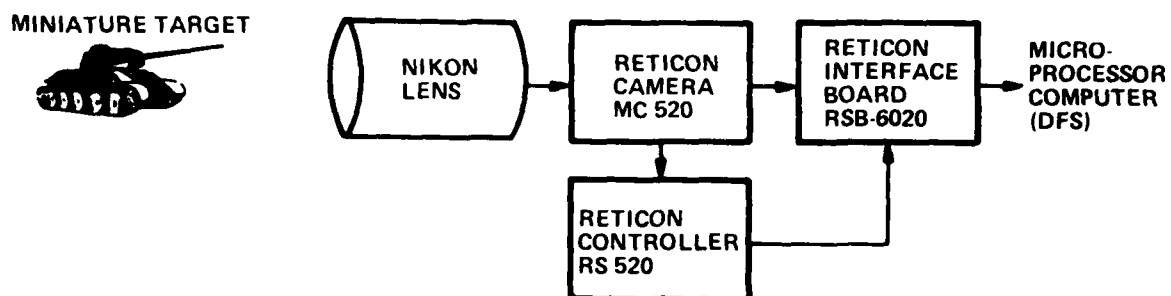


FIGURE III-1 ELECTRO-OPTIC SUBSYSTEM BLOCK DIAGRAM

B. Multiprocessor Subsystem

The multiprocessor subsystem includes six units with five being housed in the system chassis. The principal function of each of the separate units is:

- (a) Personnel Interface Processing (PIP)
- (b) DRAGON Flight Simulation (DFS)
- (c) Sound Generation (SG)
- (d) Target Control (TC)
- (e) TV Display (TVD)
- (f) Photodiode Array Processing (PAP)

System I/O is processed by the PIP, which is covered in the Computer Graphics and Video Subsystem Section.

Target control is detailed in the section Miniature Target Board.

The present section provides a description of the DRAGON Flight Simulator and the Photodiode Array Processor.

1. DRAGON Flight Simulator

The McDonnell Douglas Astronautics Company, Titusville Division, under Contract N61339-80-M-3518 provided a set of simplified equations and a computer program that approximate the DRAGON missile flight as directed by the gunner. (See Appendix A)

Six-degree-of-freedom equations are required to express the complete missile dynamics. Solutions of such equations were examined and simplified as much as possible by McDonnell while still maintaining a statistically accurate representation of weapon performance. Some of the simplifying assumptions were:

- (1) Missile dynamics should be represented by a point mass solution,
- (2) Small angle approximations to be used,
- (3) The effect of tracker sampling on missile trajectory while in the linear field of view may be neglected.

The six-degree-of-freedom equations thus modified were exercised and compared to results obtained from the complete equations of motion. Modification to the thrust level and guidance parameters were made to tailor the trajectory to the more exact results. Sufficient comparative analysis was conducted to assure that the simplified equations gave acceptable results over a range of crossing and stationary target conditions and with a variety of gunner aiming errors.

Figure III-2 is the DRAGON simulation block diagram. The variables correspond with those of Figure III-3 which defines the important horizontal angles. These, and a similar set of vertical angles, were used in the McDonnell "BASIC" program which iterates the differential equations of motion using a "Delta Time" of 20 milliseconds. Thus a 10 second missile flight requires the generation of 500 solutions of the equations of motion.

The BASIC program was rewritten for an Intel Microprocessor Development (MDS) System (see Appendix A). The resulting program, while able to reproduce the McDonnell results, required several minutes to complete the 500 solutions for a simulated 10 second missile flight. It was, therefore, unsuitable for real time training.

An investigation of other floating-point-math techniques usable with Intel SBC-86/12, 8086, computers showed that real-time solutions of the missile flight could not be accomplished without using an 8087 coprocessor. The unavailability of the 8087 at that time made it necessary to abandon the convenience of FP-math and recast the equations using integer arithmetic. This required close attention to the choice of suitable units for the variables because of the limited range of integer numbers: (-32,767, +32,767). Down-range distances, for example, are expressed in 2-inch units; 1000 meters (39,370 inches) being considered to be 19,685 "Down-range" units. Cross-range units are 0.05 inches for distances and 0.1 milliradians for angles. Unit selection for all variables is a compromise between the conflicting requirements of the desire to display variables over a wide range and the need to reduce quantization distortion while not exceeding the allowable integer range. Many comparisons between the integer and BASIC

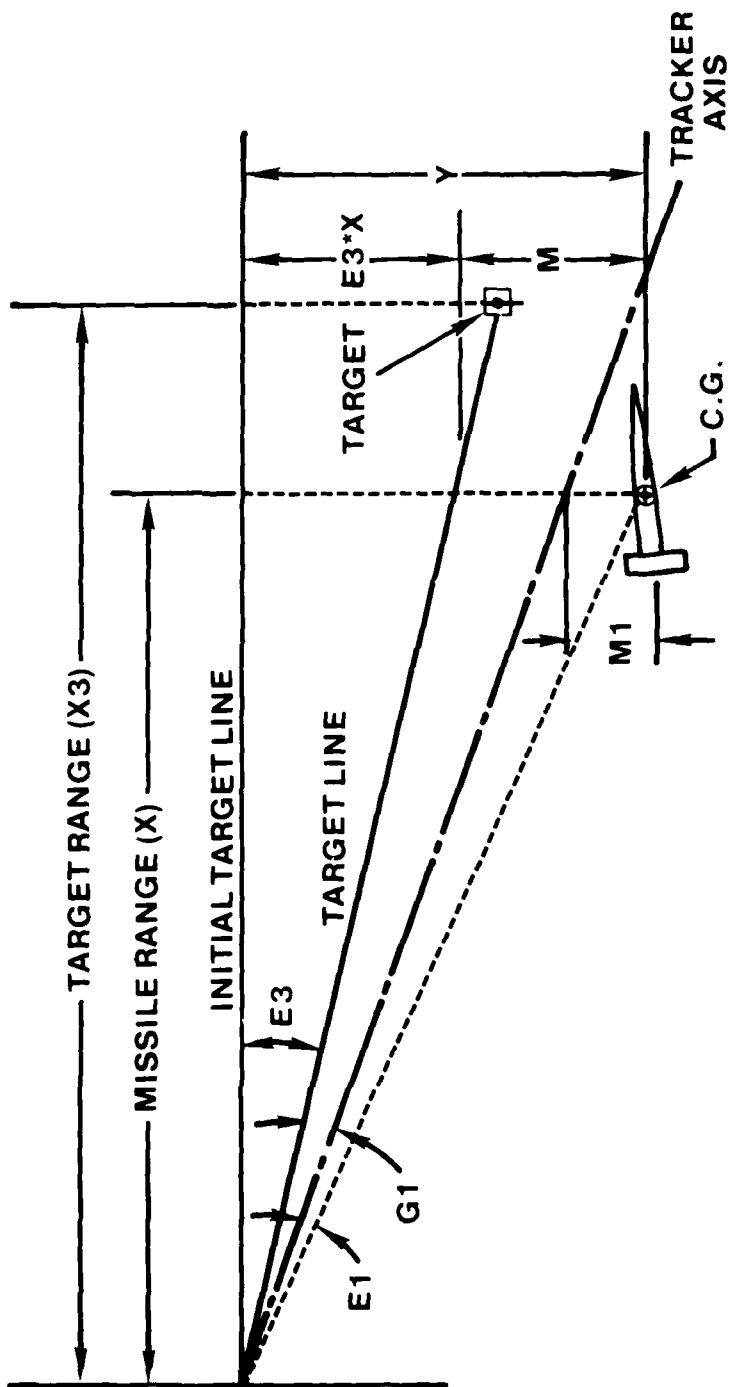


FIGURE III-3 HORIZONTAL PLANE GEOMETRY

program results have verified that good approximations to the DRAGON Flight characteristics are provided using integer arithmetic. Comments by experienced DRAGON gunners also support the validity of the approximations.

The DRAGON Flight Simulation Program includes five modules:

- (1) Main-DRAGON-Module: A "Driver" module which calls other modules.
- (2) DRAGON-Utility: Includes a number of start-up and other general procedures.
- (3) DRAGON Flight Module: Includes the integer math missile dynamics, provides missile location information to the PIP, stores location data for possible reprise, and does the initialization of flight variables.
- (4) DRAGON IR: Analyses the IR-spot data array provided by the following module.
- (5) DRAGON XF: Transfers line-by-line data provided by the photo-detector line array processor into a complete picture array.

The first three modules are written in PLM 86; an Intel high level programming language. The last two are in 8086 assembly language. Total program code require slightly over 4K of ROM memory. Variable memory requires about 1K of RAM. The above programs are in Appendix B.

As noted previously, the program is located on an Intel SBC 86/12 board. This board, along with four others are housed in an Intel SBC 86/12 system chassis which provides eight card slots, power supply and ventilation. Cards within the chassis can communicate via the multibus motherboard. An SBC 86/12 provides dual-port RAM which can be accessed by both the on-and-off board processors. Missile position data resulting from the solution of the missile equations of motion are transferred to the PIP via the multibus for further processing and output. Data status bits are also read and written across the multibus as required.

Target motion is provided by the TC unit as described in the section on Miniature Modelboard. It is programmed via a stepper motor controller into which the desired target maneuver is input from a suitable menu located in program memory of the PIP. Target information needed by the DFS is transferred from the TC via the multibus.

The DFS also provides control signals to the sound generator for side-thruster pops, launch and impact explosions. It also provides signals for weight loss in response to trigger pull.

2. Photodiode Array Processor

Line scan data from the 100 x 100 photodiode array are initially stored in a set of ping-pong memories on a Reticon RSB 6020 board housed within the system chassis and attached to the multibus. Data are alternately read into ping or pong memory under control of a clock located within the Reticon RS 520. Data within the memory units give the location of light level transitions and indicates light-dark or dark-light transitions. The stored data also indicates when the last scan line is read.

After initialization, a last-line flag is output across the multibus to the DFS which causes the DRAGON XF program to begin the transfer of data from each line of the next 100 x 100 photodiode array frame to the SBC 86/12. The data read-out is then halted by the next occurrence of the last-line flag. The next 100 x 100 frame data are ignored during the analysis of the transferred frame data. New frame data analysis results are provided every other frame.

The frame rate of the Reticon camera is 100 frames per second so new IR-spot position data are provided 50 times a second or with a 20 millisecond period. Occurrence of the last-line flag acts as the master system clock with all data processing starting with its assertion.

Figure III-4 illustrates the various devices controlled by the multi-processor subsystem.

An automatic zeroing method has been incorporated to ease day to day boresighting of the gunner sight to the miniature targets. Zeroing is accomplished by supporting the DRAGON launcher on its resting stand and aiming the scope crosshairs at the desired aim point (Recoil and weight loss off). A Control B (CTRL B) is input from the console and the DRAGON trigger is squeezed. The computer will "read" the first frame of data from the Reticon 100 x 100 matrix camera and use this aim point for its reference boresight.

Subsequent firing will use the new boresight until the zeroing procedure is repeated or the computer is turned off.

C. Computer Graphics and Video Systems

The DRAGON computer graphic visual presentation is prepared by the Personnel Interface Processor. In addition to this processor a computer graphics board, a phase-locked-loop sync board, and an EIA composite sync generator are used. Figure III-5 shows the complete graphics and the video subsystem.

Computer generated graphics provide two major functions:

(1) Real-time video graphics are generated for the gunner sight. These graphics include a simulated missile which include thruster firings, smoke obscuration during initial launch and a final explosion.

(2) Real-time graphics are generated for the instructor which indicate both vertical and horizontal gunner aiming errors. Also, for follow up analysis, graphics may be presented for gunner aiming error versus time and missile position versus time.

Gunner's sight real-time computer graphics are generated on a Matrox 256 x 256 x 4 graphics board. Sixteen levels of gray scale provide for a full range of visual intensity which allows for smoke generation which varies from fully transparent to completely opaque in sixteen levels. The Matrox RGB-256 is a graphics imaging system in which a complete gray scale capability has been integrated onto a single printed circuit board. The card includes built-in NTSC (American) and PAL (European) gray scale encoder which can provide up to 16 shades of gray. The encoders permit the RGB-256 to directly drive standard

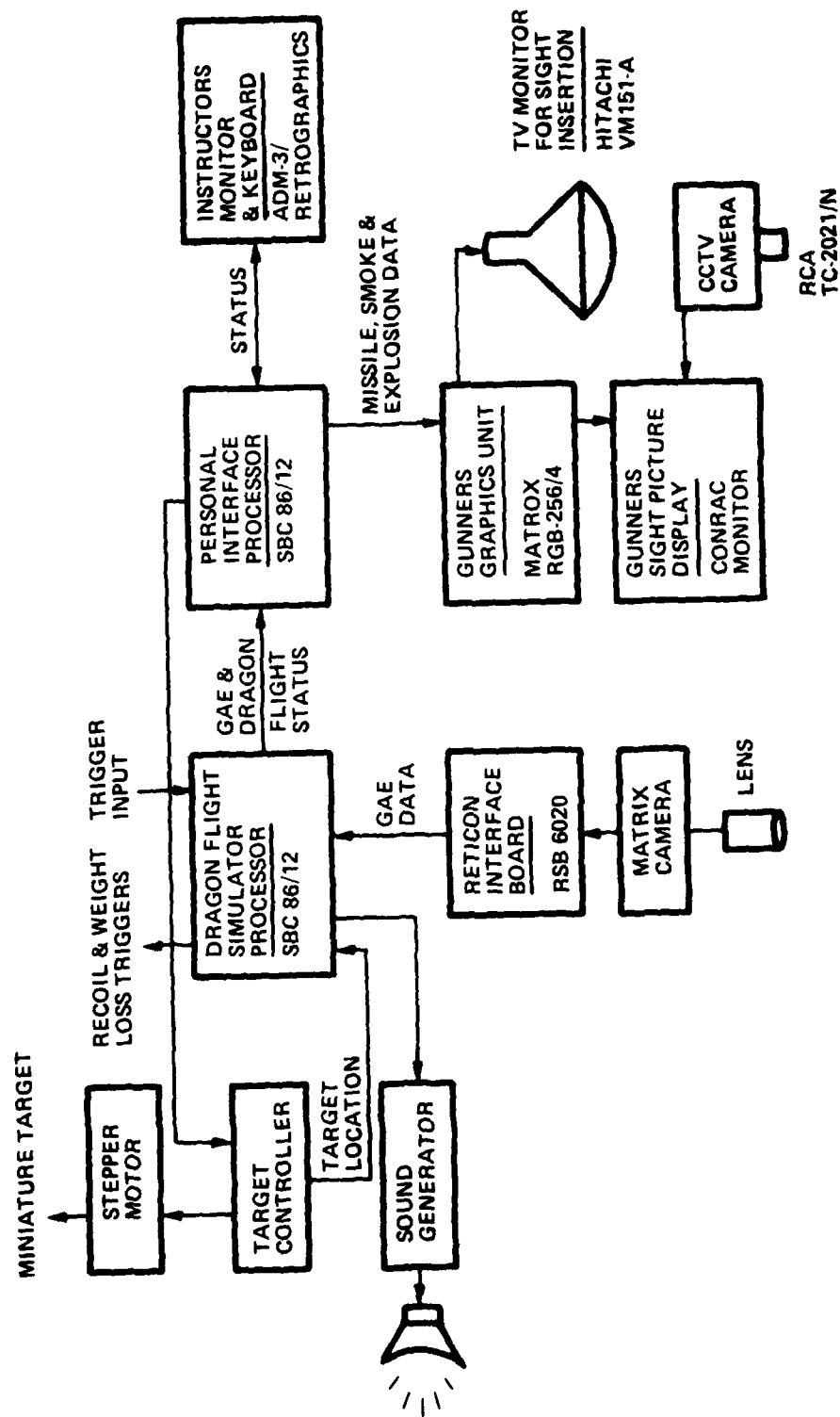


FIGURE III-4 MULTIPROCESSOR SUBSYSTEM

low cost black and white TV monitors on a single 75 ohm cable. It features the industry standard Intel Multibus which makes it directly plug compatible with all Intel single board computers.

Real-time video graphics are generated by the Personnel Interface Processor (PIP). The PIP receives gunner aiming error information from the DRAGON Flight Simulator (DFS) as well as missile angle from the line of sight of the gunner to the missile position (angle E1 from Figure III-3). The gunner aiming error is used to position the final explosion (hit or miss) in the DRAGON sight. The angle E1 is used to position the missile in the DRAGON sight.

Gunner Graphics:

DRAGON sight graphic missile simulation is accomplished by first deriving the missile position from the Angle E1. Second, the size of the missile is determined by the elapsed time since the missile launch. Third, the brilliance of the missile is determined by the elapsed time since launch and if a thruster is being fired.

The size of the missile shrinks from 10 pixels down to 1 pixel from launch to maximum range. The brilliance decays from a level of ten (with fifteen being most brilliant) to a level of zero at minimum range.

An octagon was selected as the simulated missile shape as this can be quickly calculated for real-time graphics. This shape appears mostly as a circular area to the DRAGON gunner.

Smoke is simulated in the DRAGON sight by modulating the background level, i.e., overall gray scale setting of the entire graphic video insertion in the gunner sight. It is possible to tell the RGB-256 graphics board to "erase" to any given gray scale level between zero and fifteen, with zero being black (transparent) in the gunner sight and fifteen being white (opaque). The levels of background are modulated with time to effect a smoke simulation. A typical smoke simulation might consist of starting from level zero rising to level fifteen, dropping to level eight, back up to fifteen, down to four, up to eight and down to zero during a period of one to two seconds.

The final explosion of the missile and/or tank is simulated at the end of the DRAGON flight and inserted, via the RGB-256 graphics board, into the gunner sight. The explosion is a series of geometric star shapes indicating either a hit or miss. The PIP uses the missile-to-aim-point information to position the explosion wherever the missile was as it impacted the target or ground. A ground explosion is similar to a target explosion; however, it differs by only exploding in an upward sense. Thus the DRAGON gunner has visual feedback through his sight indicating hit and miss. The computer generated graphics are passed directly to the gunner's sight through a Hitachi VM151A, one and a quarter inch, closed circuit television (CCTV) monitor. The optical arrangement is shown in Figure III-6. The television screen appears at infinity along with the viewed scene through the 6x scope. The CCTV is mounted inside the DRAGON IR tracker housing and electronics for the CCTV are located where the IR tracker electronics are normally located at the bottom of the tracking head.

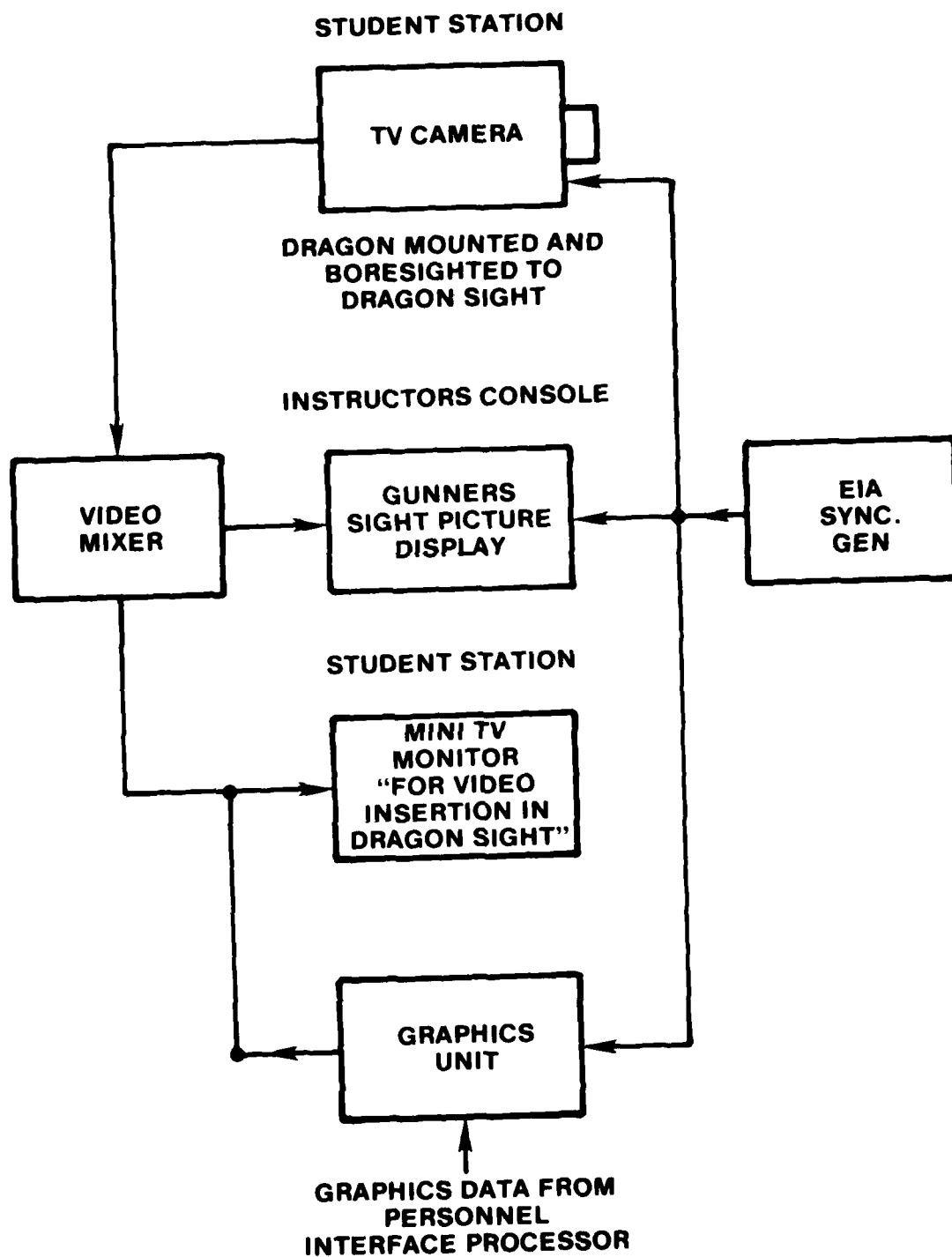


FIGURE III-5 COMPUTER GRAPHICS AND VIDEO SUBSYSTEM

Instructor Console Graphics

The instructor console graphics subsystem is composed of two units, a television representation of the gunner's sight picture and a graphical plot of gunner aiming error versus time and/or gunner aiming error versus missile position.

The television representation of the gunner's sight is accomplished by mixing the gunner's sight TV camera, which is boresighted to the 6x gunner sight, with the video graphics presented to the gunner's sight. The composite picture presents to the instructor an image of the gunner's sight which includes the target, rocket, smoke, crosshairs and final explosion.

The instructor's television representation of the DRAGON gunner's sight picture and computer graphic missile, smoke, crosshairs and explosion simulation is combined from three sources.

The model board target and terrain is looked at by a closed circuit television (CCTV) camera which is mounted outboard on the DRAGON launcher tube. This camera is zeroed to the gunners 6x scope and has the same field of view as the scope. The camera used is an RCA TC-2021/N with a NUVICON camera tube and a 135mm f3.5 still camera lens. This camera was chosen for its small size and low weight.

Secondly, a video mixer combines the CCTV image with the Matrox RGB-256 computer graphics. The combination of CCTV video and computer graphics is then a representative visual image of the gunner sight picture except for the crosshairs.

Crosshairs are added, to complete the instructor sight picture display, by passing the video presentation through an electronic crosshair generator. The crosshairs are adjustable in position and width.

The graphical plot of the gunner aiming error (GAE) versus time for both horizontal and vertical error are presented in real-time during the missile flight. The graphs indicate the actual gunner aiming error during the flight as well as the limits for a 95% probability of hit performance. The guidance rocket thruster firings are shown when they are fired as well as a final actual count of the thrusters fired versus the ideal number of thrusters that would have been fired for a given target distance with perfect aim. At the end of a flight, displayed results show the miss distance, in feet, where the missile passed the target. If the missile struck the ground before passing the target, a message is displayed stating "ground impact" as well as the remaining distance to the target when grounded. If a hit is scored a hit message is displayed to mark the event.

After a missile flight a reprise of the flight may be called. A horizontal reprise replays the horizontal GAE and the horizontal missile position versus time. Likewise the vertical reprise replays the vertical GAE and the vertical missile position versus time. The reprises indicate all the hit/miss summaries of the first real-time plot.

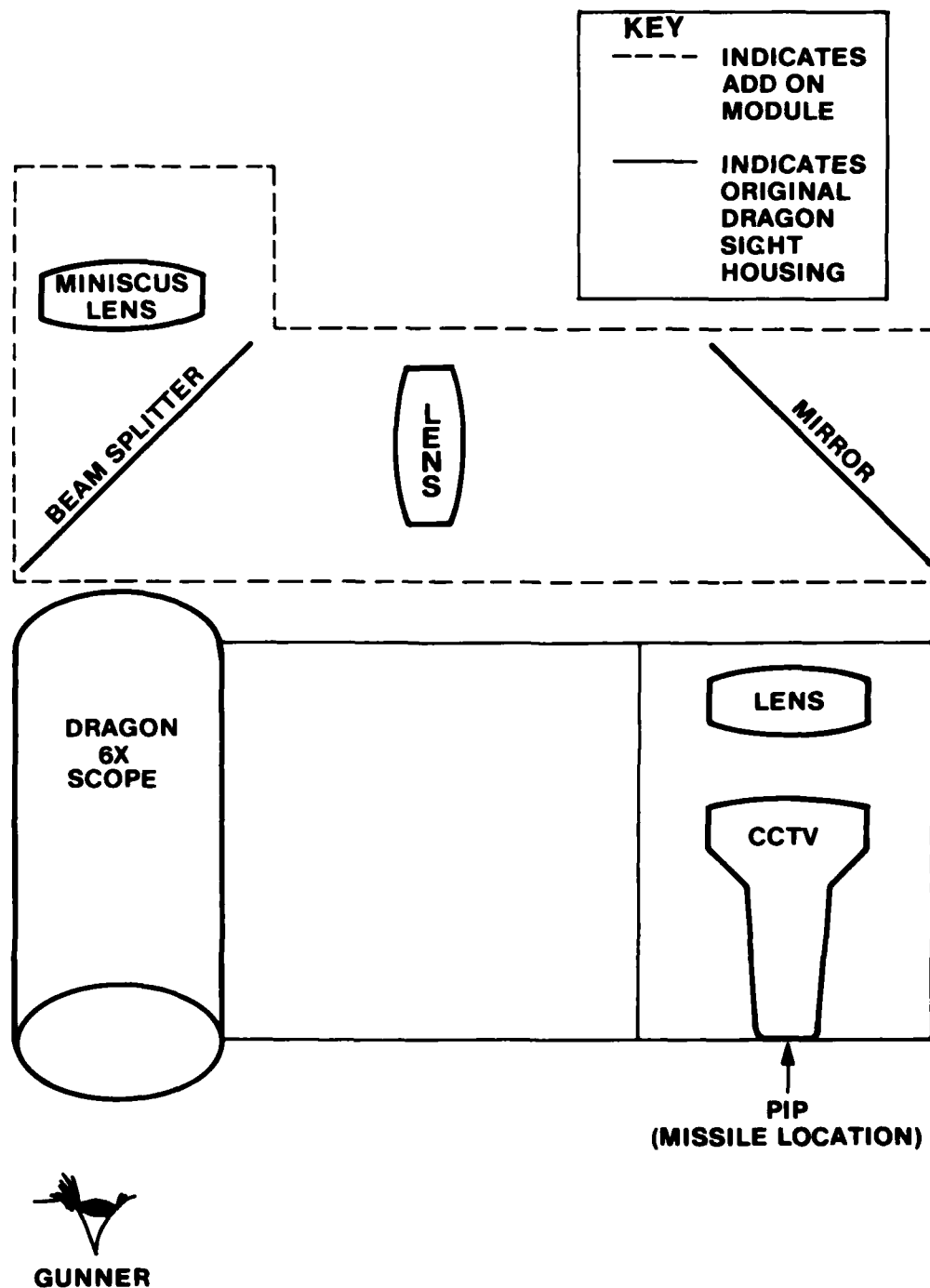


FIGURE III-6 DRAGON GUNNER'S SIGHT SYSTEM

Any of the computer graphic plots may be made into a hard-copy printout. The hard-copy may include the gunner's name or other pertinent data as desired by the instructor.

The instructor's diagnostic graphs, keyboard controls and hard copy printouts are controlled by the PIP through an ADM-3 dumb terminal and Digital Engineering Retrographics RG-512 graphic board and Digital Engineering GP-100 hard copy printer.

The operation of the Retro-Graphics equipped ADM-3A can be best understood by considering the RG-512 card as the terminal controller and the ADM-3A as a "peripheral" device. The RG-512 is situated in series between the ADM-3A and the serial input to the terminal. This means that all incoming ASCII will be received by the RG-512 and processed. Input to the terminal will only reach the ADM-3A circuitry if it is transmitted there through the RG-512.

The RG-512 can perform several functions on the incoming data. The function performed depends on the actual ASCII code received and the RG-512 operating mode. Data may be retransmitted to the ADM-3A as mentioned above if the data were alphanumeric text. This is the usual function performed by the RG-512 when in the ADM-3A Alpha Mode. Certain control codes, called mode transition codes, can set the RG-512 to one of the two graphics modes, the Vector Mode or the Point Mode. An additional alphanumeric mode, the 4010 Alpha Mode, is included and can also be entered by sending the terminal the appropriate mode transition code.

After entering one of the graphics modes, subsequent input is interpreted as x-y coordinate data and is used in the generation of a point or vector display. The RG-512 does not retransmit an ASCII code to the ADM-3A if it is being used as an x-y coordinate.

The RG-512 employs the "bit map" method of storing graphic images. This means the information is stored in a digital memory as a rectangular array of bits. Each bit in this memory is mapped onto the CRT screen and can cause a bright point to be displayed. The RG-512 displays graphs and pictures by writing the proper bits into the graphics memory. This architecture has several advantages over the traditional storage tube approach which has dominated lower cost graphics terminal designs. Since the CRT is not relied upon for storage of the image, less expensive CRTs employing more conventional long life, brighter phosphors can be used. Another important by-product is the ability to selectively erase portions of the screen. This is desirable if the application requires the use of dynamic displays employing motion or rotation to convey information.

All circuitry for the RG-512 is packaged on a single 12" x 12.31" printed circuit card. This circuitry consists of four functional elements: Z-80A microprocessor and control, 128,000 bit graphics RAM, raster synchronization and CRT refresh, and power supply.

The Z-80A microprocessor and control section performs command decoding and is responsible for the writing of information into the graphics RAM. The Z-80A automatically generates vectors from transmitted endpoints and also performs scaling and character generating functions.

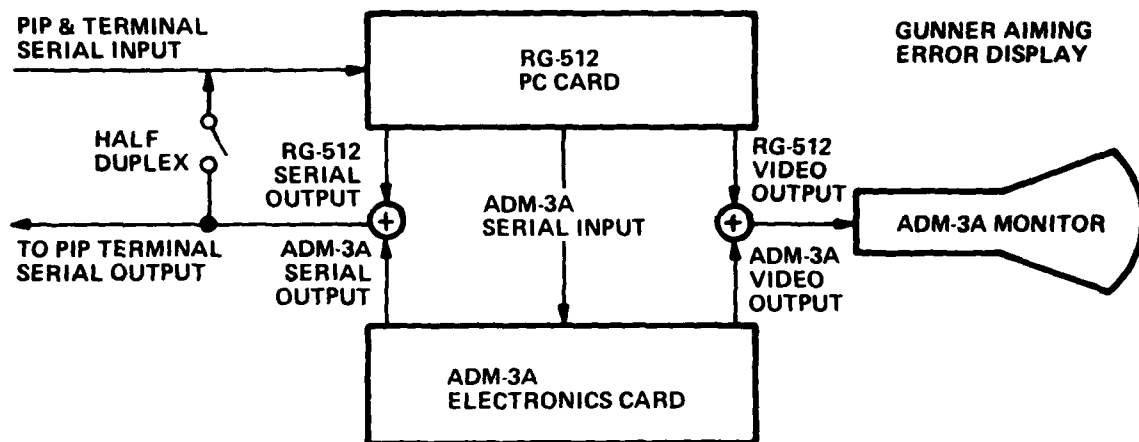


FIGURE III-7 RG-512 FUNCTIONAL BLOCK DIAGRAM

The GP-100 Graphics-Printer is designed to interface with the Retro-Graphics upgraded Lear Siegler ADM-3A (or 3A+) computer terminal.

As an optional feature to Retro-Graphics, Graphx-Printer reproduces the terminal's displayed graphics (or alphanumerics) on hardcopy. The electro-sensitive device is ideal in those computer graphics applications where clear, economical printing is needed.

The GP-100's printing system is electrosensitive. This advanced technology allows the GP-100 to quietly print the displayed graphics within 16 seconds and alphanumerics at 170 lines per minute.

With the electrosensitive printing system all graphics and alphanumerics are drawn by a durable printhead that produces dark, clear images with no distortion. In other words, the high resolution graphics screen image is reproduced, dot-for-dot, on hardcopy.

Additionally, paper is the printer's only consumable. Typically an 8 1/2" x 11" hardcopy costs less than 3¢. Also, the paper can be photocopied, and it will not fade or yellow with time.

The electrosensitive paper is made from a base of black coated ordinary bond paper deposited with a thin aluminum layer; this gives the unprinted paper a metallic appearance. During printing, an electric current flows through styli that touch the aluminum. This action vaporizes the aluminum at the point of contact and exposes the contrasting black under-layer to form the graphics or character image.

The print head consists of 12 styli mounted one above the other as a unit. This head is attached to a carriage which moves the styli from left to right and maintains them in contact with the paper. The styli are pulsed electrically while crossing the paper so that the required characters or graphics are printed. During printing, each stylus burns a single dot in response to a current pulse. At the end of the line, the carriage moves the head away from the paper and returns to the left hand margin without touching the paper.

D. Computer Generated Sound System

Simulation of sounds produced during an actual DRAGON missile firing is accomplished by interfacing an Intel 8748 microcomputer to a General Instruments AY-3-8910 Programmable Sound Generator (PSG). Data necessary for the PSG to reproduce sounds is acquired from the permanent memory of the microcomputer. During missile flight time the DFS processor simply selects the sound to be made and communicates its choice to the microcomputer. This approach allows the processor to handle sound-making decisions with minimum time take from its primary functions.

The choice of sounds available to the DFS processor are:

- (1) Gyro wind-up
- (2) Missile launch explosions
- (3) Rocket thruster motor firing
- (4) Target missed explosions
- (5) Target hit explosions

The General Instruments Programmable Sound Generator (PSG) is a 40 pin, 8 bit device with microprocessor compatibility. The device features three independent analog channels each with access to its own tone generator. A 16 control register array communicates to the microcomputer through an eight bit bi-directional port. Four lines are allotted for bus control logic (read and write). Each tone generator looks to two registers within the array for a 12 bit tone period. A range of frequencies covering the full eight octaves of the equal tempered chromatic scale is available.

Pseudo-random noise may be mixed to any or all channels from a noise generator with basic frequencies of 4 KHz to 125 KHz. Two modes of output control are available for each channel. The fixed level amplitude mode selects an amplitude specified in the array by the microcomputer. For use in this system the variable amplitude mode is selected, forcing an envelope generator to control the shape

and cycle of all outputs. Controlling the envelope generator is a 16 bit tone period within the array allowing for frequency ranges of 12 Hz to 7812.5 Hz and a five bit shape/cycle control register. Three D/A converters supply 0 to 1 volt signals to the output channels.

To accurately represent the flight of a DRAGON missile as it moves down-range two sound phenomena must be simulated:

- (1) Time delay due to the differences in the speeds of light and sound and,
- (2) The Logarithmic decay in the amplitude of sound with distance.

Software developed for the microcomputer closely approximates these conditions within a 1000 meter range.

As shown in Figure III-8, the outputs of the PSGs are input to circuits whose function is to control the amplitude of the sound. These circuits consist of operational amplifiers with closed loop gains under direct control of the microcomputer. An Intel 8243 I/O port expander is used to select feedback networks of the operational amplifiers. Harris analog switches HI518 and HI304 under the direction of the 8243 provide a variable feedback network for the rocket thruster sounds. The hit and miss explosions pass through a separate operational amplifier circuit utilizing the same HI518 for gain control. To further massage the rocket thruster sounds a Pioneer Reverberation Amplifier is inserted between the output of the operational amplifier and a Bozak Pre-amp and Mixer. Rocket thruster sounds, hit and miss explosions, and the launch explosion all pass through the mixer and a Bozak Amplifier. The launch explosion is generated from a Frazier 8-ohm speaker located at the trainees station. Rocket thruster firings are heard from a speaker near the modelboard as well as hit/miss explosions. The gyro wind-up noise emanates from a speaker located within the DRAGON tube.

The DRAGON Flight Simulator processor initiates a timer within the microcomputer upon request of a launch explosion. Thereafter, each request for a sound by the processor causes the microcomputer to inspect the timer. Assuming the missile travels at an average speed of 280 feet per second the microcomputer is able to approximate the distance covered and determine the appropriate sound amplitude. The microcomputer selects one of thirteen levels of amplitude, for rocket thruster sounds, decreasing logarithmically from a gain of 10 to 1 over a time span of 11 seconds corresponding to a distance of 1000 meters. When the missile hits its target a series of three rapid explosions are generated, each explosion louder than the previous. For a missed target two explosions occur. Distance in terms of three ranges is the criteria used to determine the amplitudes of these explosions. These ranges are: low range (less than 333 meters), mid range (334 to 630 meters), and a high range (greater than 630 meters). The gyro wind-up noise and the launch explosion have fixed amplitudes.

Time delay associated with distance covered by the missile is accomplished upon inspection of the timer for each requested sound after launch. Before signals are passed to the PSG to create a sound, software completes a sequence of three delays. The first delay represents the real-time between requests from the processor. This timeout occurs only when two or more requests are made before

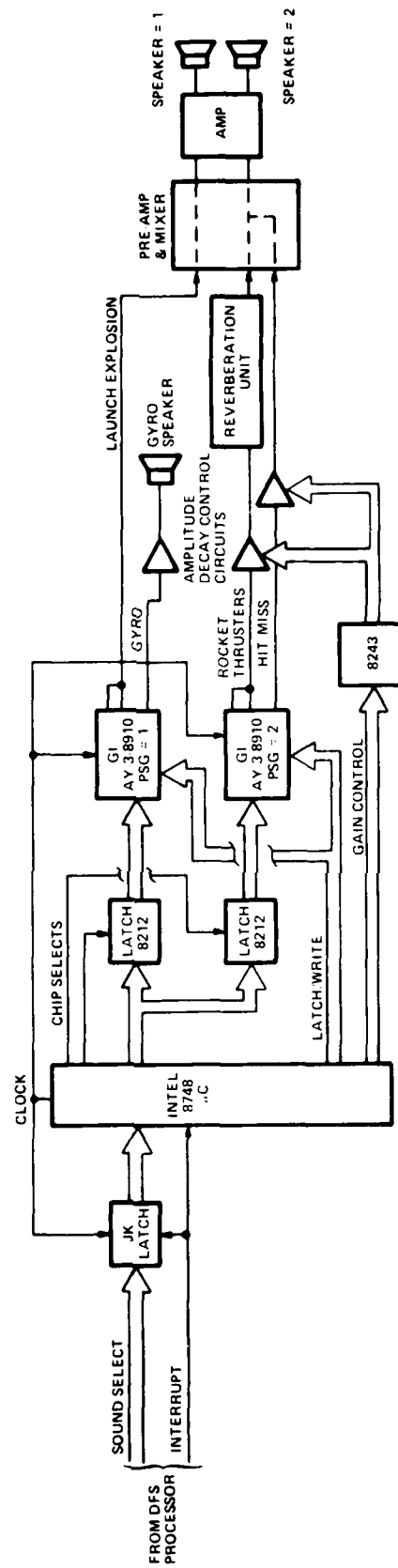
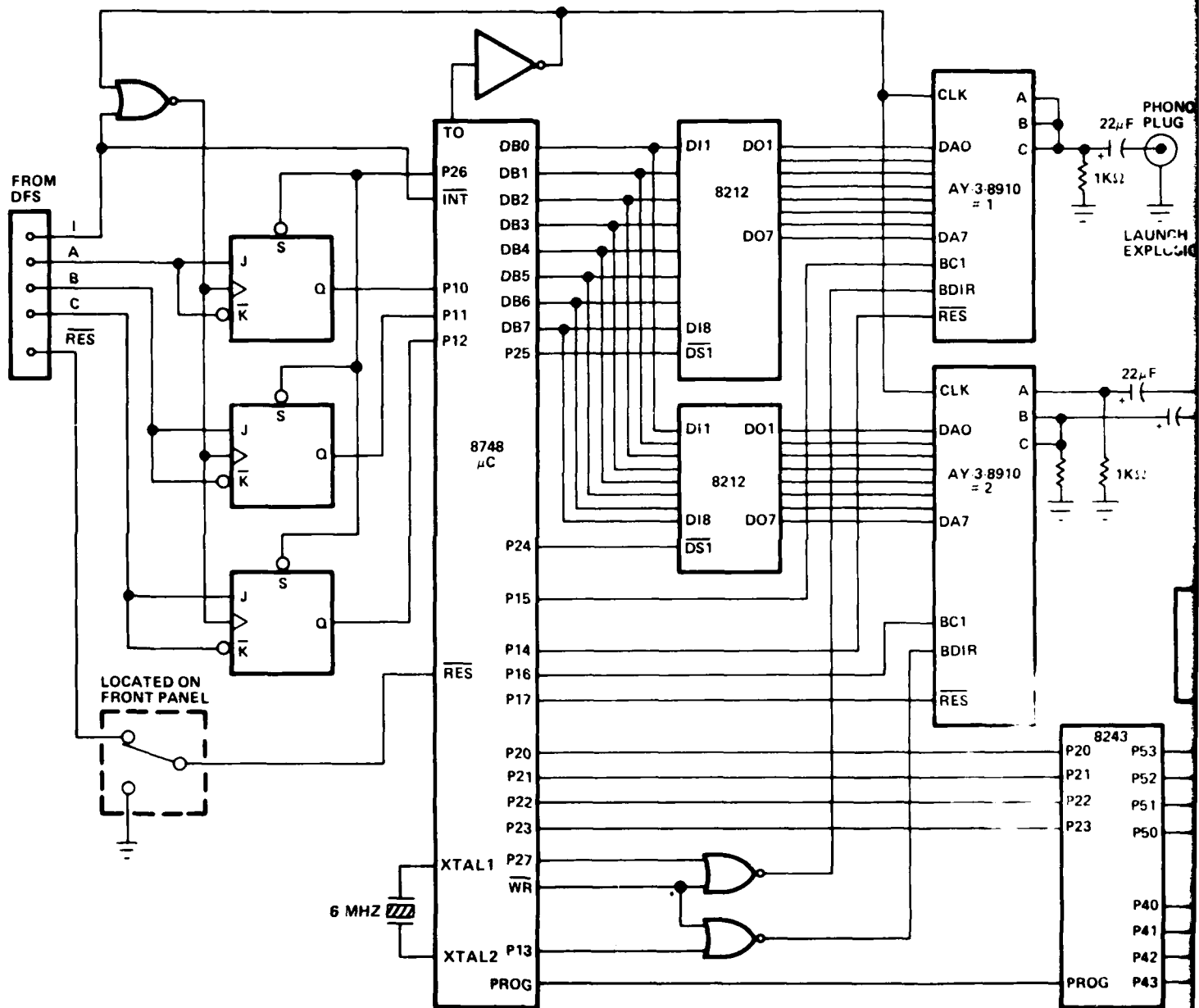


FIGURE III-8 SOUND SYSTEM FUNCTIONAL BLOCK DIAGRAM





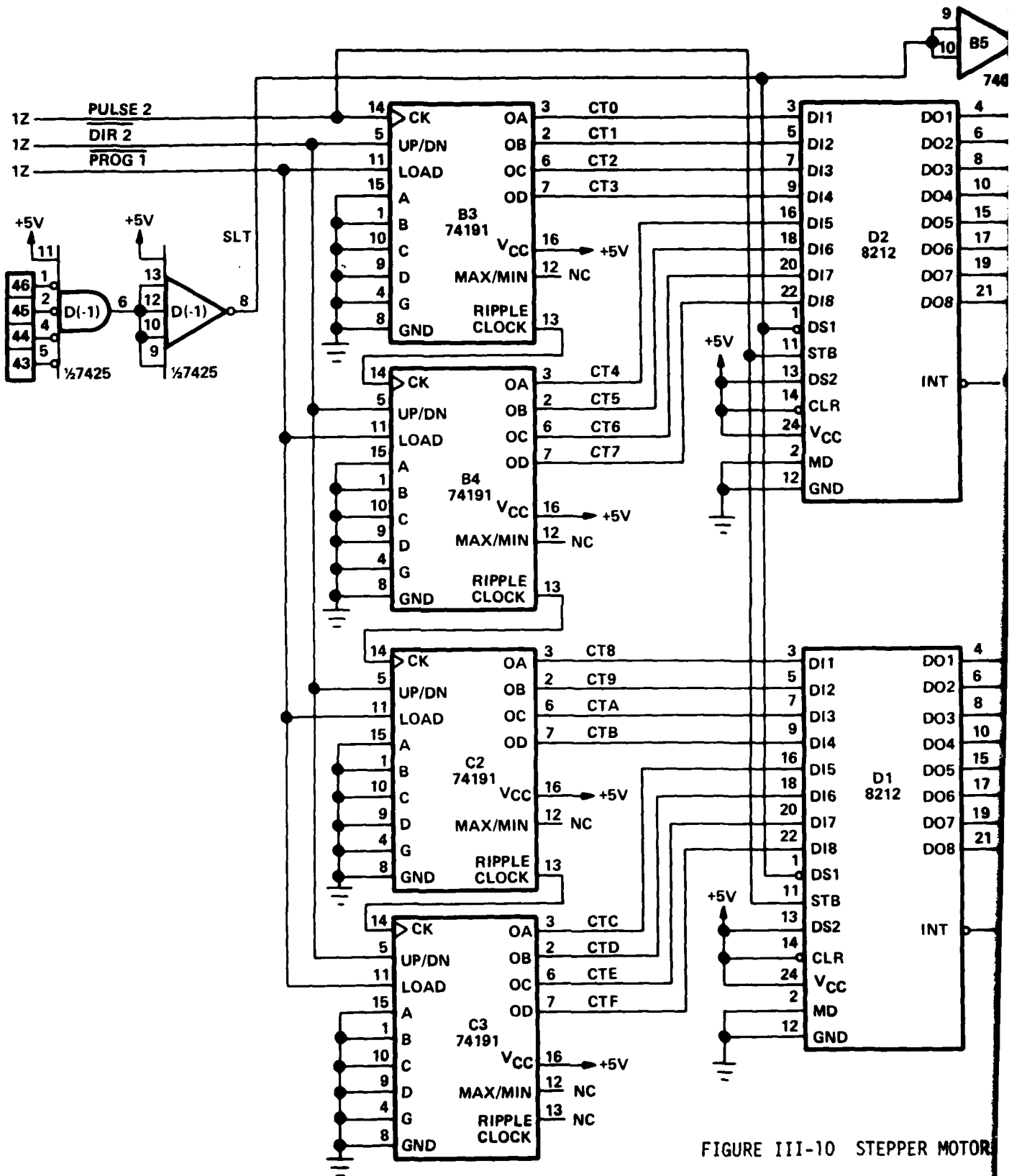


FIGURE III-10 STEPPER MOTOR

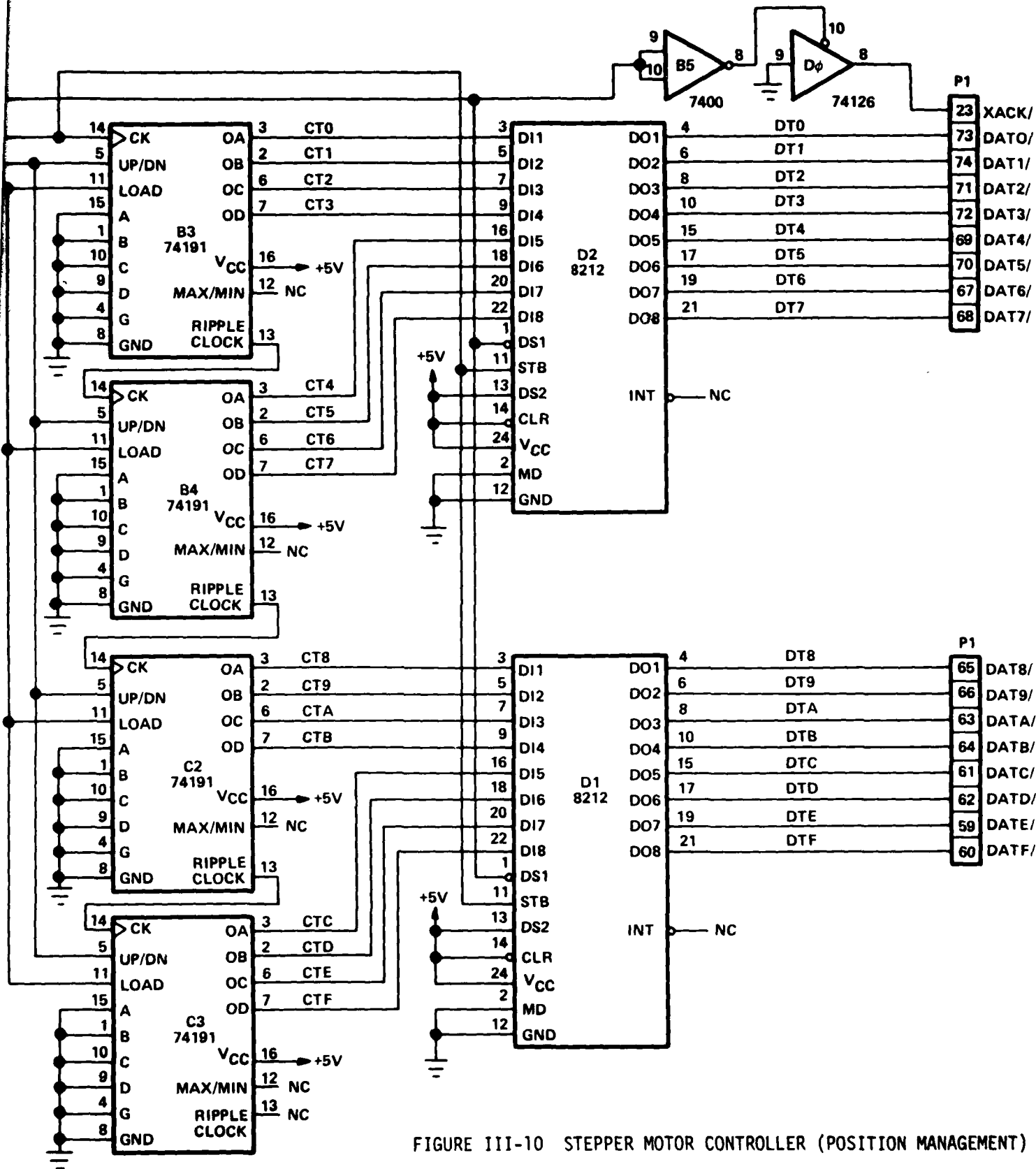


FIGURE III-10 STEPPER MOTOR CONTROLLER (POSITION MANAGEMENT)

the first request is serviced by passing signals to the PSG. The real-time between any two requests represents distance traveled by the missile and is decoded into the second time delay as determined by the time required for sound waves to travel this distance. These incremental time delays are accumulated in the microcomputers data memory. The third time delay before a sound is made is the cumulative total of all the second time delays that have already been decoded. The complete algorithm produces a series of logarithmically decaying, time delayed, sound waves that approximate the actual conditions within a 1000 meter range.

E. Miniature Target Board

Because most anti-armor devices use high power telescopes to view the targets, a 1/120 scaled miniature model was chosen. The target model has an IRED located at the center of the target mass. The model is moved using a stepper motor. The stepper motor controller is a stand-alone intelligent controller that is independent of the host computer, the Personnel Interface Processor, except for loading the scenario. The stepper motor controller uses a high level language for control of the stepper motor direction, position, speed and acceleration. The tank is moved over a 40 inch track. It takes 5,240 half steps to run this track. Using this system the tanks location is known to 0.0076 inches on the model board. Scaled to the real world one half step moves the tank 0.9 inches.

The controller utilized is a Cybernetic Micro Systems, CY 512. The CY 512 controller is a standard five volt, 40 pin LSI device configured to control a 4-phase stepper motor. The CY 512 interfaces to the microcomputer using parallel TTL input. It also has a software controllable pin which is used to initiate movement of the tanks turret.

Hi-level commands to control the device are stored externally in the PIP processor.

Under instructor control a scenario can be selected. The commands are then transferred and stored internally in a program buffer in the CY 512. The CY 512 outputs sequence the stepper drive circuits that consist of standard Darlington drivers. When absolute position commands are executed, the CY 512 automatically determines whether it is necessary to move CW or CCW to reach the specified target position.

Tank position is measured by a 16-bit counter consisting of four 74191 TTL chips. (See Figure III-10) The counter is reset whenever a new scenario is loaded into the CY 512. The counter then records half-steps of the stepper motor.

The CY 512 interface is shown in Figure III-11.

The Darlington drivers are shown in Figure III-12.

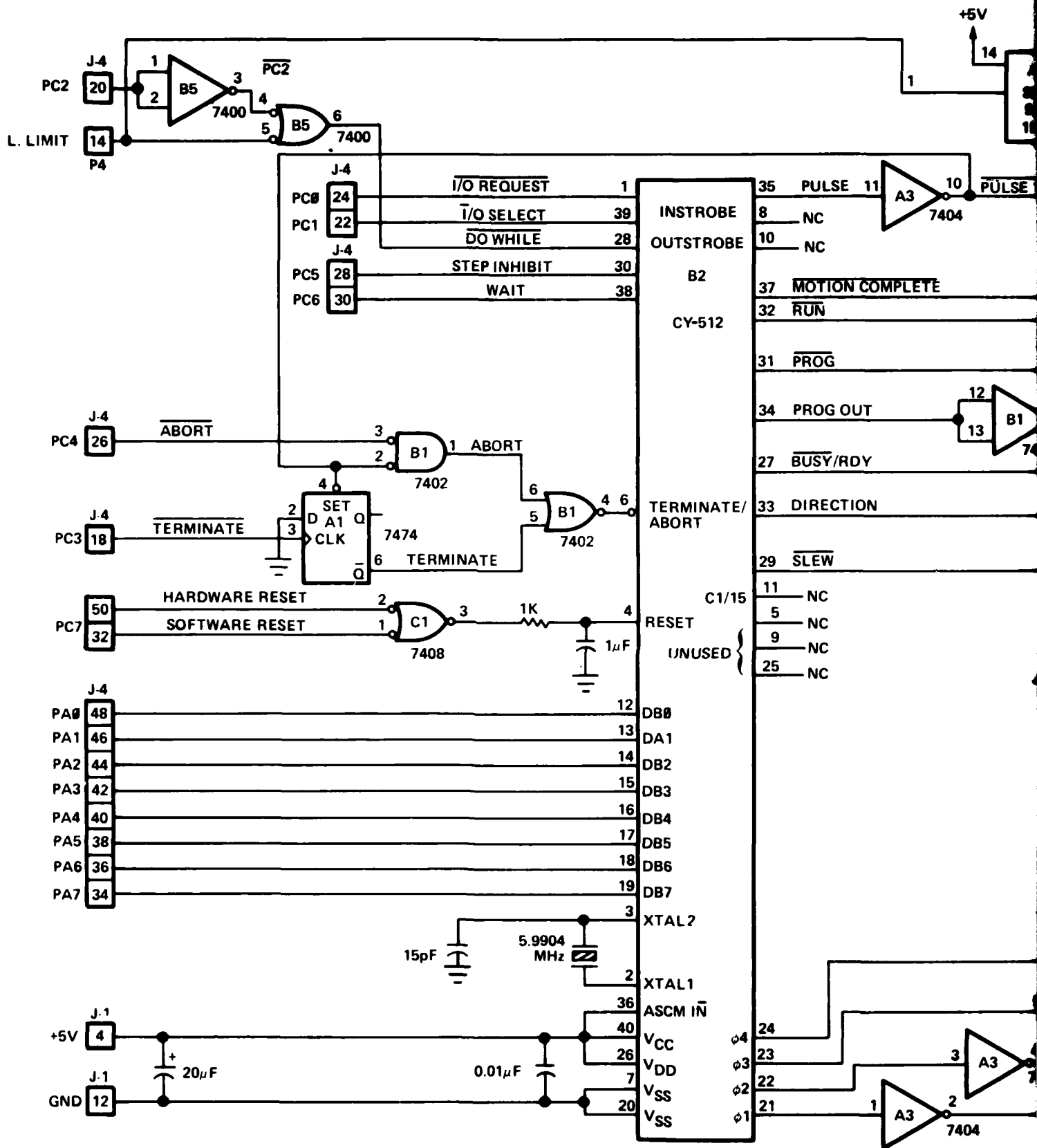


FIGURE III-11

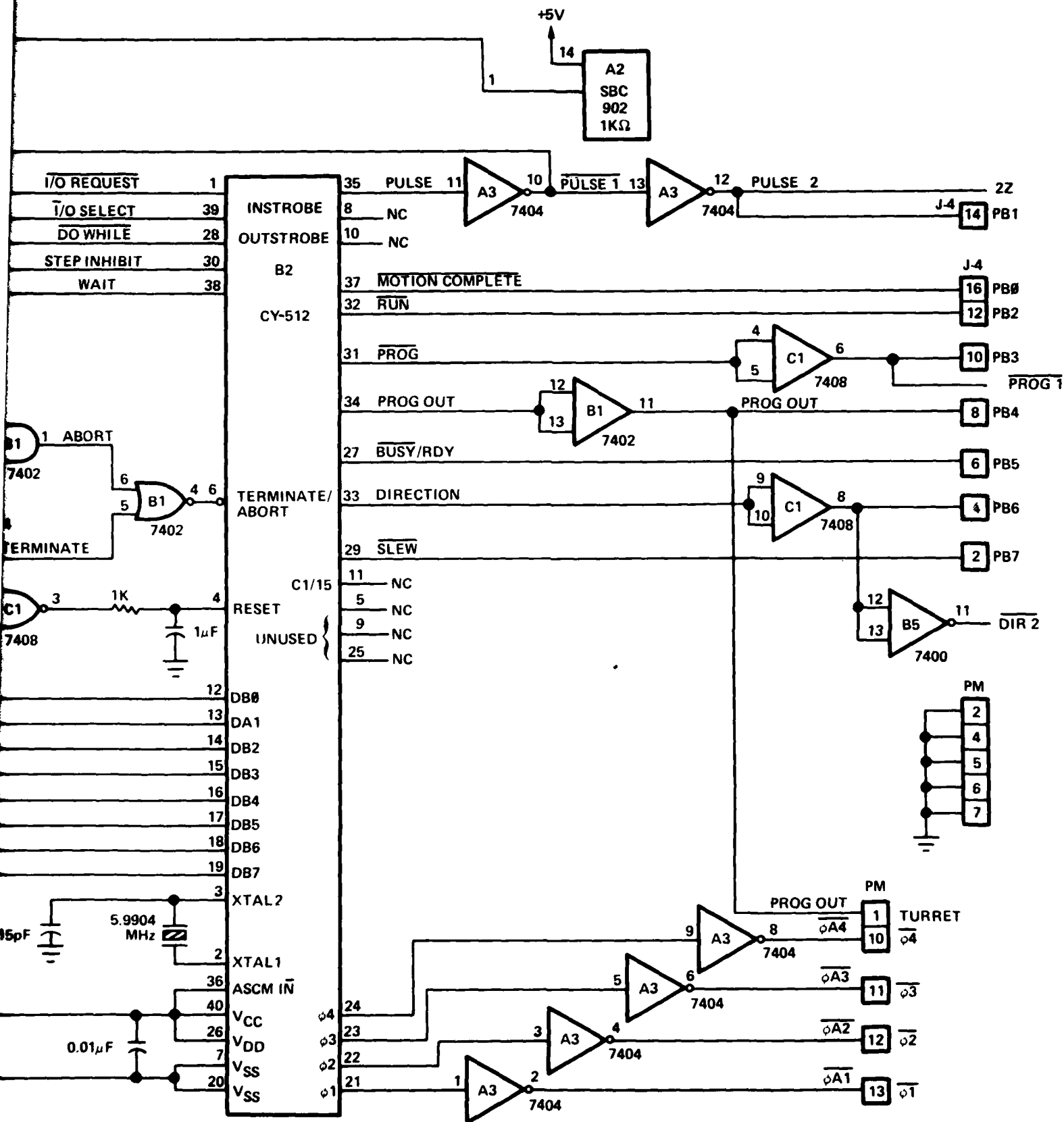


FIGURE III-11 STEPPER MOTOR CONTROLLER (CY-512 INTERFACE)

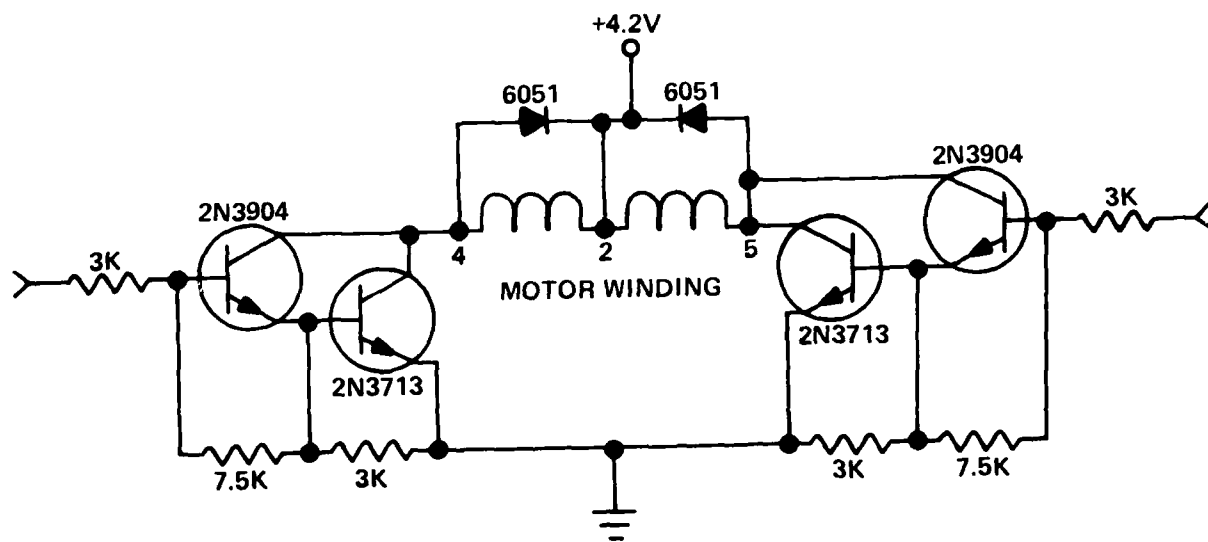
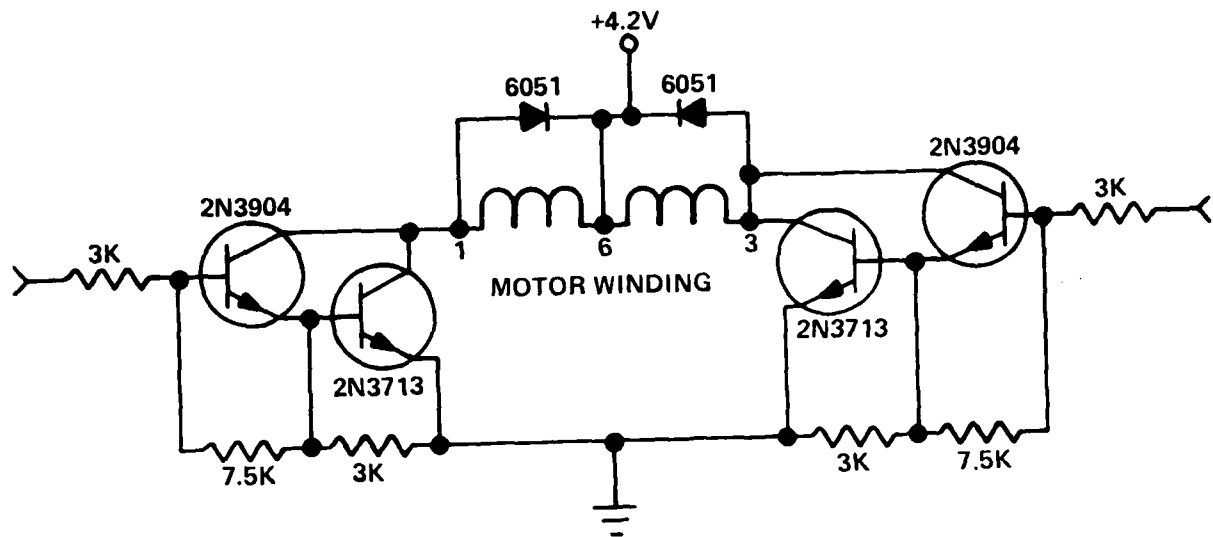


FIGURE III-12 STEPPER MOTOR DRIVERS

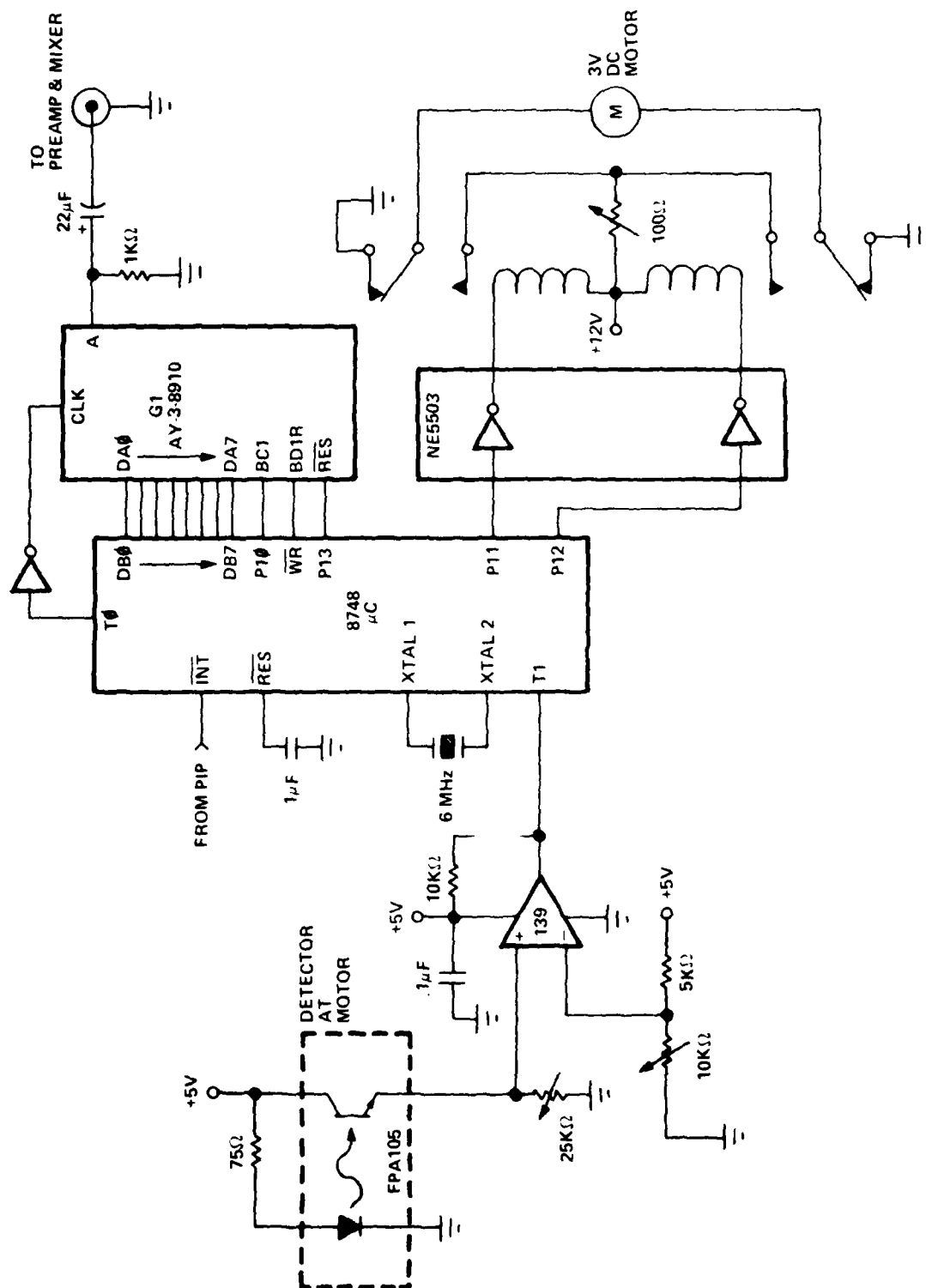


FIGURE III-13 TURRET CONTROLLER

A Superior Electric, Slo-Syn, Synchronous Stepping Motor with 200 steps per revolution was utilized.

The tank turret can be moved by using a software controlled pin on the CY-512. The CY-512 is fed into the circuit shown in Figure III-13. On software command the turret moves 90° toward the trainee and the tank gun fires. It then moves back to dead ahead after a short 2 or 3 second time delay.

F. Weight Loss and Recoil Mechanism

Launch effects of the DRAGON simulator are a very important facet of the training mission. Two of the launch transients which must be overcome by the DRAGON gunner are the weight loss due to the missile leaving the launch tube and the recoil of the launcher due to slight uncompensated differences in the pressures at launch. Weapon launch effects of weight loss and recoil are simulated via mechanical attachments to the DRAGON bipod.

The recoil mechanism is a sliding platten upon which the DRAGON bipod and gunner's feet are supported. The platten is covered with a rubber and steel hybrid material that allows the gunner to firmly plant the bipod legs in position and stabilize the launcher using his boots to press against the bipod supports. At launch the platten is given an impulse from a pneumatic solenoid thus imparting a sensation of recoil to the launcher.

The weight loss simulation is accomplished by a weight mass that is attached to the bipod via a pivot and pneumatic cylinder. When the DRAGON simulator is armed for launch, the pneumatic cylinder is energized which in turn raises the weight and places an additional equivalent weight of the DRAGON missile on the shoulder of the DRAGON gunner through mechanical leverage. When the simulated missile is launched, the pneumatic cylinder is relaxed, thus releasing the weight and effectively removing the equivalent ROCKET weight from the gunner's shoulder. The recoil and weight loss circuit for driving the pneumatics is shown in Figure III-14.

G. Pull Down Measurement and Reticle Insertion for Gunner Sight Picture Display

Three LED indicator lights are present on the instructor's console to provide the instructor a quantitative indication of how much force a trainee places on the DRAGON tube and his shoulder. When the trainee produces a force on his shoulder equivalent to or greater than a predetermined threshold, the yellow LED comes on. If pull down force is increased beyond a second, higher threshold, a green LED comes on. If neither threshold is reached, a red LED is on. The threshold for the yellow and green LEDs are variable in a range of approximately 50 to 250 pounds force.

A circuit utilizing a strain gauge bridge was developed to generate a signal which is strictly the result of a force at the trainee's shoulder. The strain gauges used are manufactured by Wm. T. Bean, Inc. They are general purpose foil gauges constructed of Constantan with a polyimide backing. Two of the strain gauges are strategically located on the DRAGON tube so as to unbalance the bridge only if the trainee has his shoulder properly positioned and is applying a downward force on the sight. The bridge, when unbalanced, supplies a DC level to a two stage DC amplifier. The amplified DC level is the input to two comparators. One comparator activates the yellow light when its threshold is breached while the other controls the green light. The circuit is shown in Figure III-15.

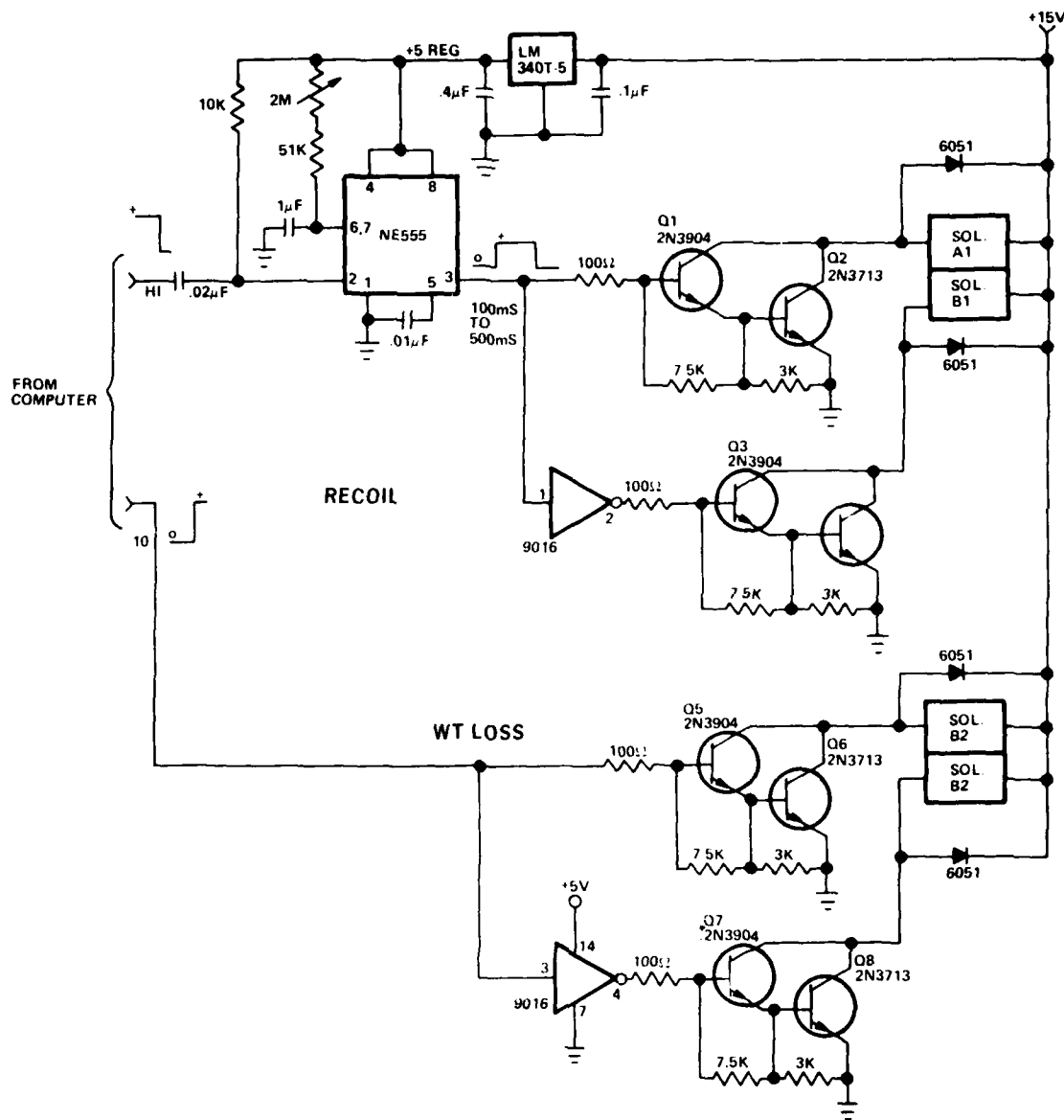


FIGURE III-14 RECOIL AND WEIGHT LOSS CIRCUIT

In order to provide more realism to the instructor's view of the gunner's sight picture, an electronic reticle was inserted into the instructor's TV monitor. A Cohu sync generator located inside the instructor's console provides drive signals to synchronize all the video signals throughout the system. The vertical and horizontal drive signals provide inputs to the reticle circuit. These signals each pass through a low pass active filter with a cut-off frequency centered at the repetition rate of the drive signal. In this way the square wave drive signals are filtered to provide sine wave outputs of frequency identical to the repetition rate of the inputs. The outputs of the filters input to voltage comparators which generate TTL square waves with falling edges adjustable about the midway times between two drive pulses. These falling edges trigger one shots which generate pulses whose duration determines the width of the retical lines. A horizontal reticle is produced by blanking out one or more lines of video. To insure that an entire line is blanked out and not a portion of it, a flip-flop further conditions the output of the horizontal line one shot. The clock for this flip-flop is provided by the vertical drive pulse which occurs for each line of video. An AND gate combines the output of the flip- flop (horizontal line) and the output of the vertical line one shot. This in turn controls an analog switch. The switch allows video to pass through to the TV, or when activated by the AND gate, sends a negative (black) signal to the TV. The position of the horizontal line is adjusted at the voltage comparator. The level of comparison, as it moves in relation to the sine wave input, controls the position of the falling edge at the output. The position of the vertical line is controlled by a phase shifter at the input of the voltage comparator. The reticle insertion circuit is shown in Figure III-16.

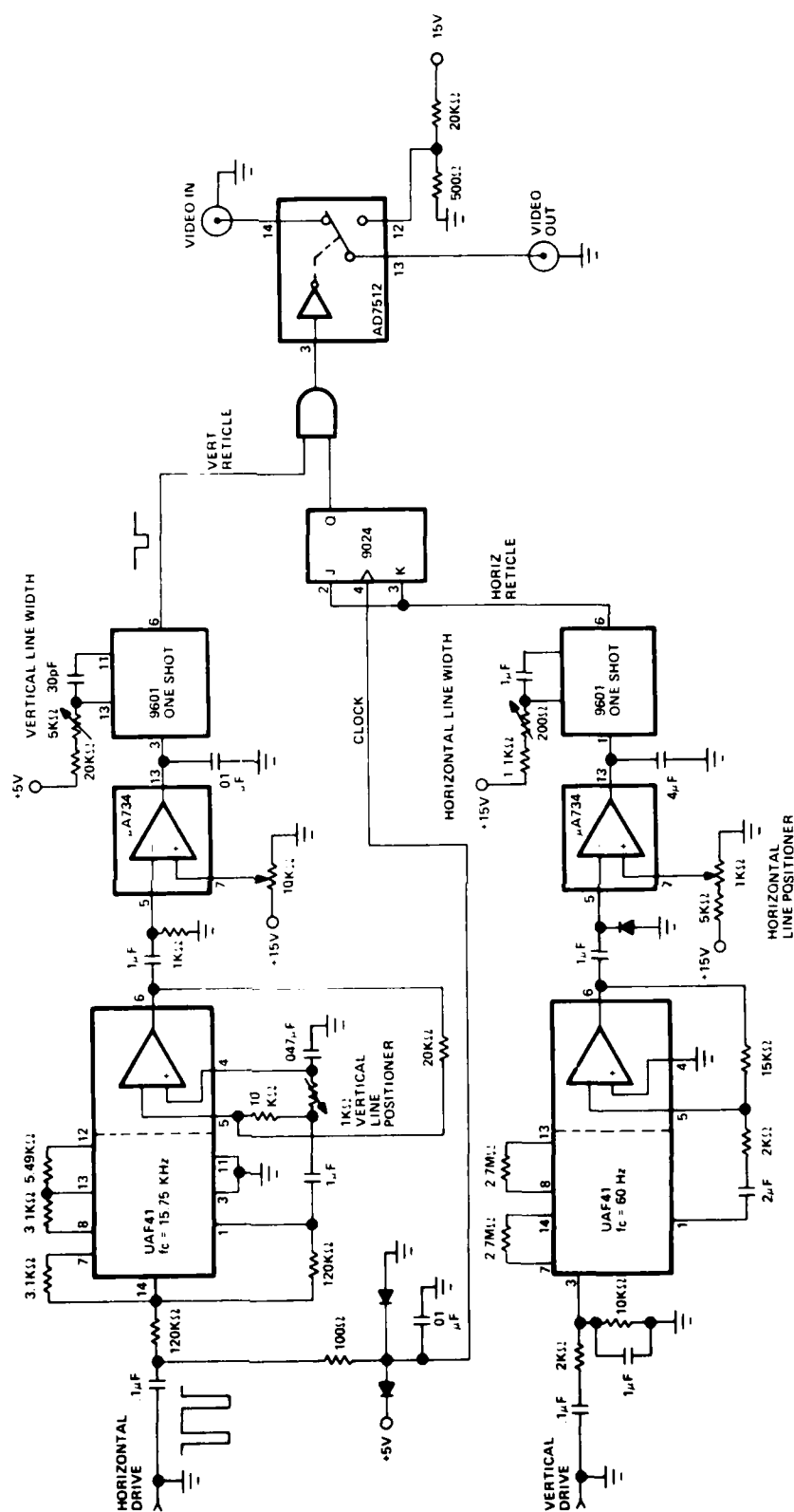


FIGURE III-16 RETICLE INSERTION CIRCUITRY

SECTION IV

CONCLUSIONS

This system has undergone preliminary evaluation by both Army and US Marine Corps experienced DRAGON gunners. All gunners were favorably impressed with its realism and teaching attributes.

The results of testing this device will be included in the final report.

Work is currently under way to include a TOW training capability as part of the STAGS system.

Development has also begun to add a speech synthesizer chip. This chip has a 274 word vocabulary and will be used to coach the student using verbal output.

Work has also started to simulate a thermal sight capability. This work will be covered in the final report.

APPENDIX A

DRAGON FLIGHT SIMULATOR EQUATIONS

The following data was provided by McDonnell Douglas Corporation under Contract N61339-80-M-3518 for use in simulating the DRAGON.

OBJECTIVE

Develop a set of simplified equations that will approximate the Dragon missile in flight when acted upon by the guidance commands as influenced by the gunner's aiming errors.

STUDY APPROACH

The equations currently programmed in the Dragon six degree of freedom simulator were examined and simplified as much as possible while still maintaining a statistically accurate representation of weapon performance. Some of the simplifying assumptions are:

- (1) Missile dynamics based on a point mass solution
- (2) Small angle approximation are used in the calculation of missile dynamics
- (3) Effect of tracker sampling on missile trajectory while in the tracker linear field of view is negligible and is not simulated.

The six degree of freedom equations thus modified were exercised and compared to results from the six degree of freedom simulator. Modification to the thrust level and guidance parameters were made to tailor the trajectory to the more exact six degree of freedom results. Sufficient comparative analysis was conducted to assure that the simplified equations gave acceptable results over a range of crossing and stationary target conditions and with a variety of gunner aiming errors.

PROGRAM DESCRIPTION

At the beginning of each simulated flight, initial missile velocity and position is established in each of 3 orthogonal axes. The reference axes are established by the initial launch line. The target is placed on the launch line with a constant crossing velocity and time is set to zero.

Equations of motion are then solved every 0.02 seconds in each axis using gravity, drag and side thruster accelerations as inputs (see Figure A-1). At the end of each time increment, the new missile position (X, Y, Z) along with gunner aiming error (G1 and G2) and target position (E3) are seen as an angular input (E1, E2) into the tracker (See Figure A-2). The tracker calculates a side thruster firing

angle based on the azimuth error (E1) and a firing frequency based on the elevation error (E2) and the commanded firing angle (W1).

When the tracker commands a firing, the resulting velocity change is resolved into each axis. This in turn changes missile position in a direction to reduce the sensed angular displacements between tracker and missile, thereby closing the guidance loop.

The program listing in BASIC language along with a symbol reference list and symbol descriptions are included.

DISCUSSION AND CONCLUSIONS

The equations presented herein will provide a good approximation of the flight characteristics of Dragon when subjected to the gunner aiming errors used in this analysis.

To interface this Dragon flight model with STAGS, several input parameters from the STAGS are necessary. The input parameters are trigger pull; target speed, direction and range; and gunner aiming error. Trigger pull will be initiated by the gunner using the Dragon training mockup, electrically sensed and transmitted to the Dragon flight simulator. This signal will be used to begin the simulated missile launch and subsequent flight. The target speed, direction, and range information are predetermined values for a given scenario. Target information is used in the Dragon flight simulator to generate system lag characteristics, i.e., the average distance at which the missile flies behind the target center. The STAGS will measure gunner aiming error with respect to a selected aim point on the tank target. This aiming error data is needed in the Dragon simulator to generate guidance error commands.

The sequence of events in a simulated flight begins with actuation of the tracker trigger. Figure A-3 is a time line or sequence of events for the launch phase based on nominal conditions at 70°F. This is an abbreviated time line which includes only those events which are relevant to the weapons trainer. Between trigger pull and gas generator ignition batteries are building up voltage and safe and arm functions are taking place; however, gas generator ignition at 515 milliseconds after trigger pull is important as an indicator of when to apply the simulation of sound pressure level. First motion of the missile in the launch tube begins at 533 milliseconds and could be used to initiate a simulation of weight shift ending at a tube exit time 20 milliseconds later. At tube exit, launch gas (fire and smoke) visible to the gunner is released. From this point the missile is flying ballistically and the missile flare is building up to its operating level. This flare is operating at 735 milliseconds allowing the tracker to recognize missile position relative to its line of sight and guidance corrections are generated in the tracker. At 1003 millisecond the warhead is armed providing an indication of what type of simulation of ground impact should be considered. Prior to this time a ground impact appears as a dud but beyond this time ground impact would cause the warhead to detonate and simulating this situation would be

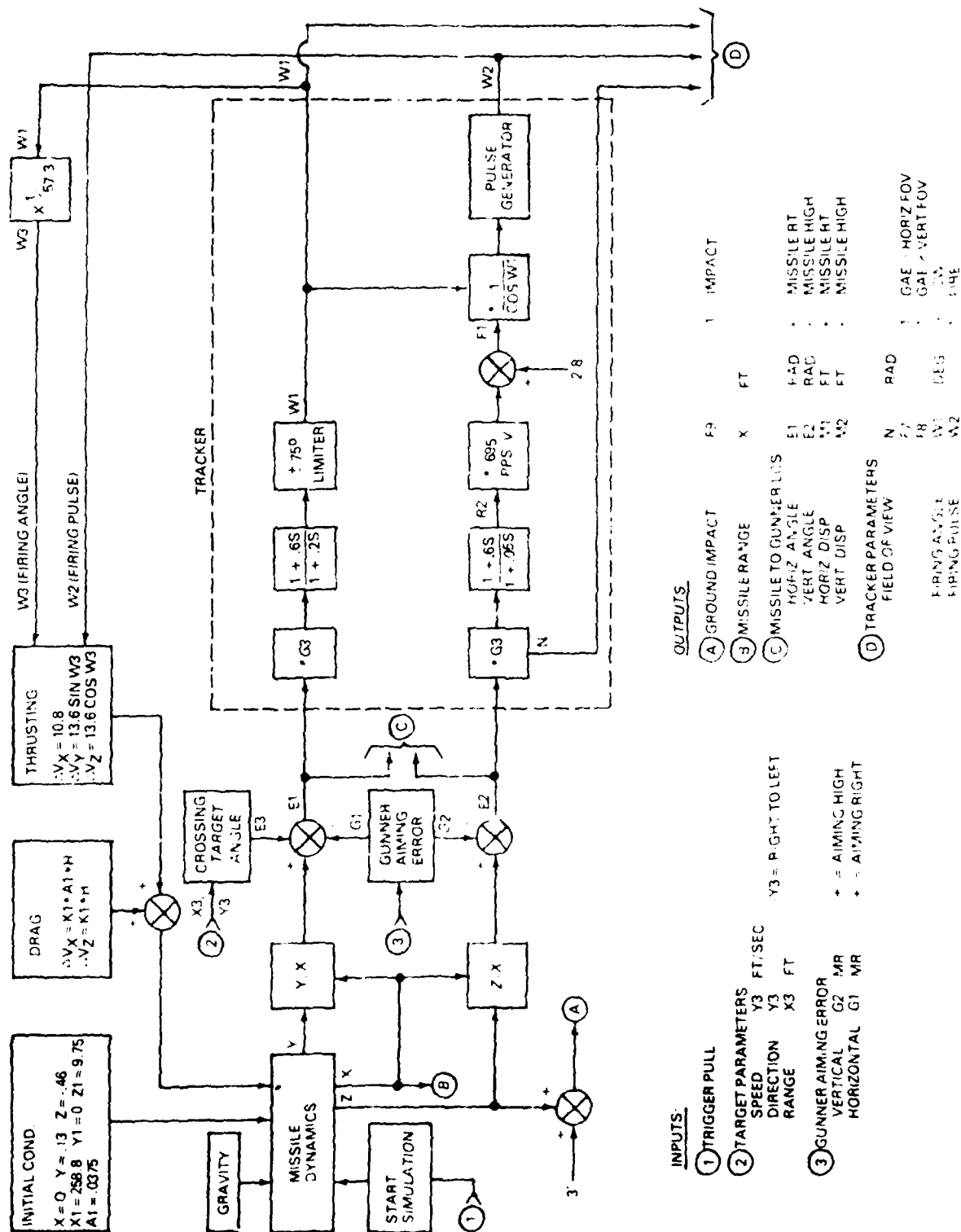


FIGURE A-1 SIMULATION BLOCK DIAGRAM

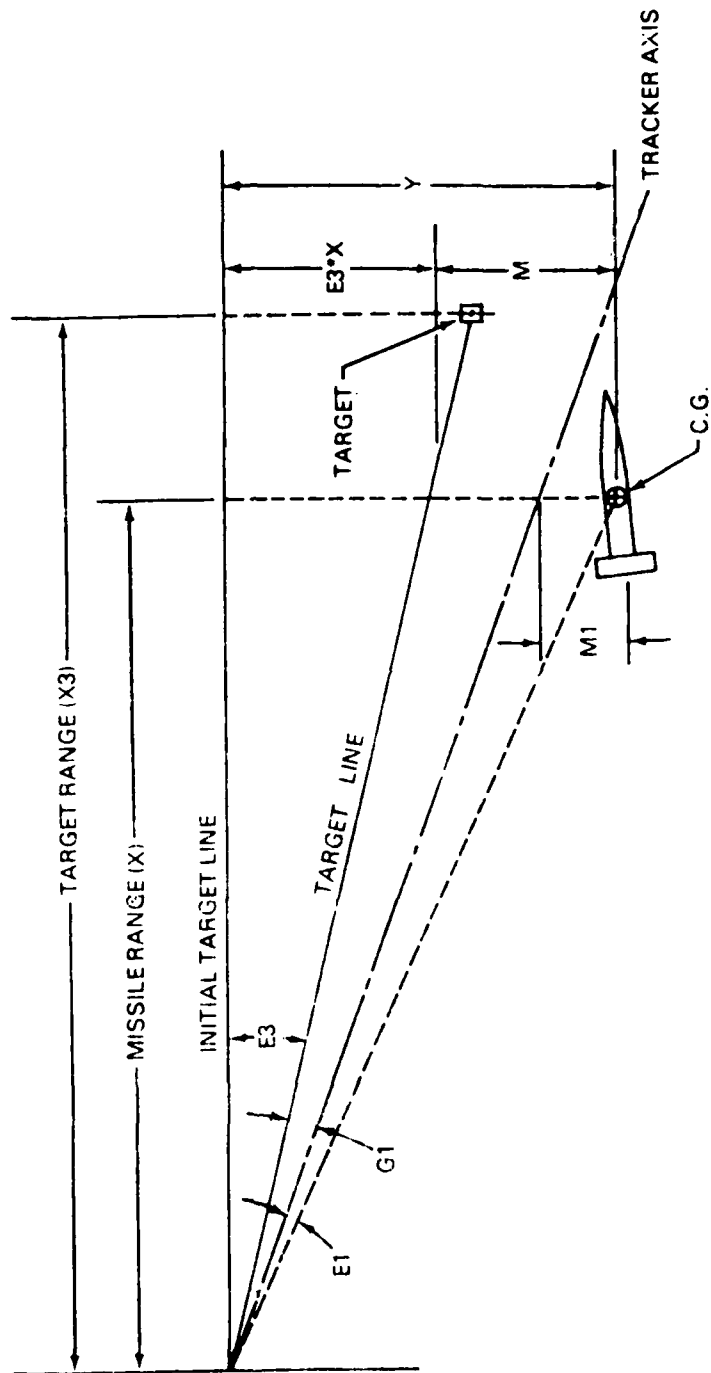


FIGURE A-2 HORIZONTAL PLANE GEOMETRY

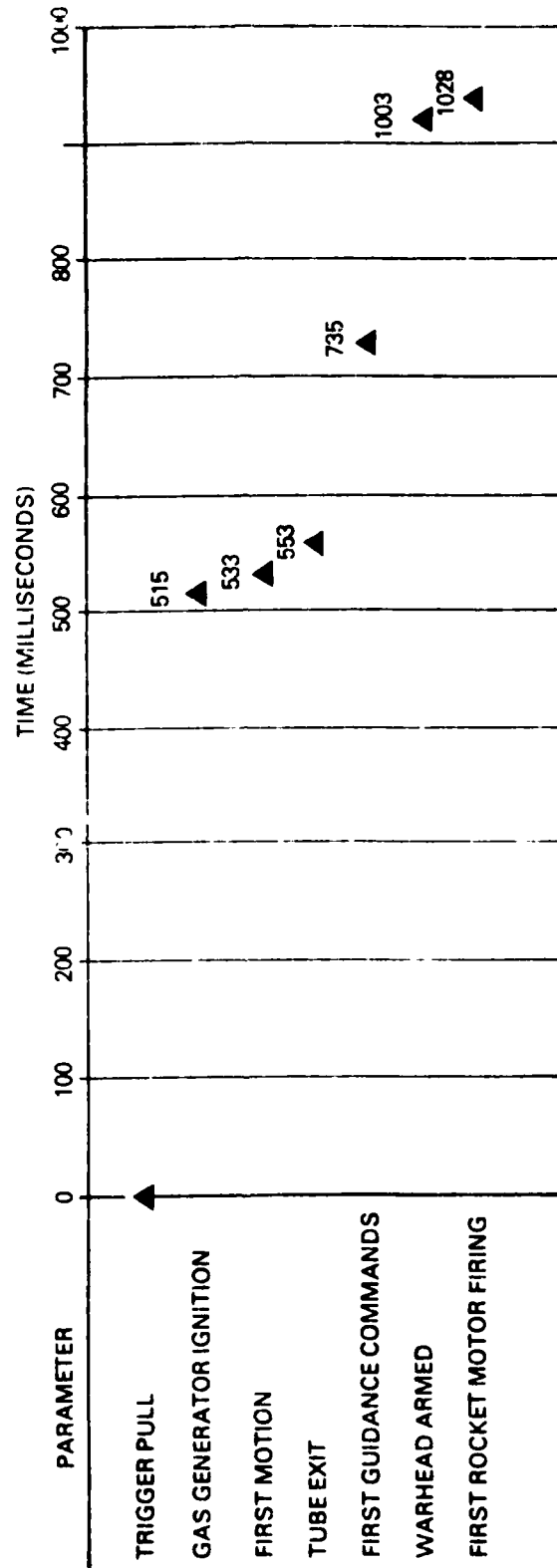
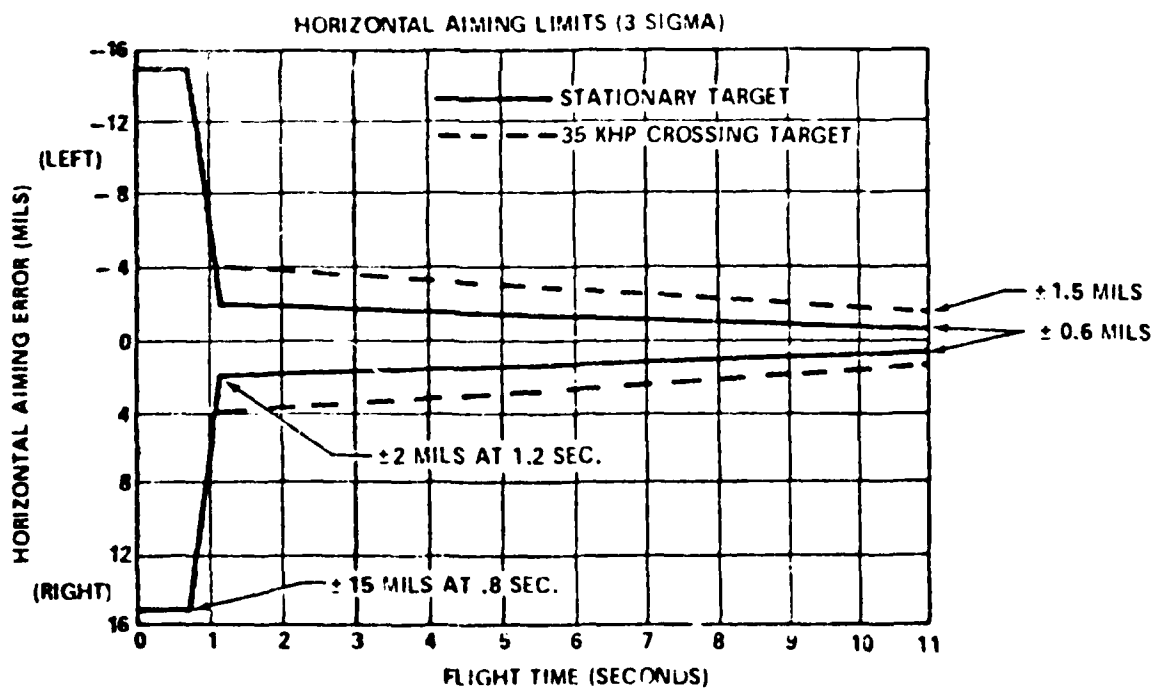
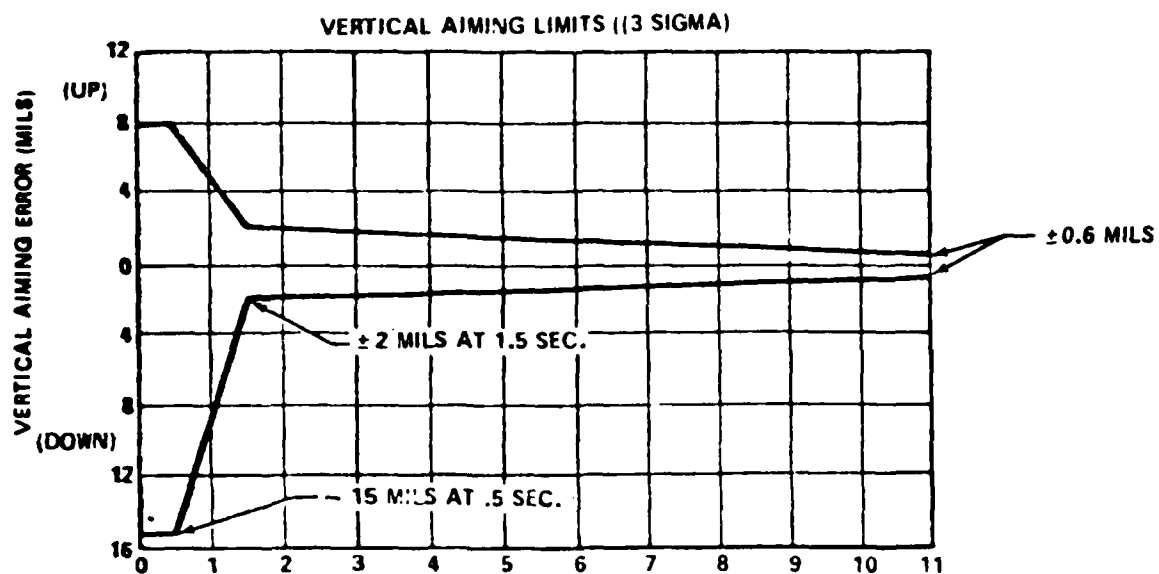


FIGURE A-3 DRAGON LAUNCH SEQUENCE TIME LINE

quite different. The ballistic phase ends with the first rocket motor firing which is commanded automatically at a fixed time of 475 milliseconds from missile first motion. Subsequent to this first firing, the normal closed loop guidance is active in both the horizontal and vertical channels. The Dragon system was designed with a set of limits established for the aiming errors and the trainer may want to incorporate these limits in its scheme of scoring the gunners performance. Figure A-4 is a plot of these limits in both channels for stationary and crossing targets. Another factor that may be considered in modeling the Dragon flight is the influence of the trackers field of view; i.e., missiles' flare image relative to the center of the trackers' IR detector (coincident with gunners line of sight). As this flare image approaches the field of view boundaries guidance performance is degraded and when these boundaries are exceeded guidance is lost and the system goes into a squelch mode. In this mode of operation the tracker commands a constant firing angle and firing rate based on the last guidance information. A more accurate model of tracker performance which includes the field of view effect may be added at a later time but does require significantly more computing than this initial model.



TP575-21

FIGURE A-4 GUNNER ERROR LIMITS

APPENDIX B

MULTI-PROCESSOR MAIN PROGRAMS

ISIS-11 PL/M-86 V2.1 COMPILATION OF MODULE DRAGONFLIGHTMODULE
 OBJECT MODULE PLACED IN F1 DRAGFL.OBT
 COMPILER INVOKED BY PLM86 F1 DRAGFL 011 DEBUG FOR IXREF DATE (08/16/10)

```

1      DRAGONFLIGHT$MODULE CO.

      *****
      OFF-BOARD ABSOLUTE ADDRESSES
      *****/

2 1     DECLARE (HANG_BIRD, ZANG_BIRD) INTEGER AT (00010H), (BIRD_DT_RDY,
      FIRE_BIRD, BIRD_HITS, BIRD_MISSES, H_REF_RD, H_REF_GO, V_REF_RD,
      V_REF_GO, GRND_BIRD, END_REPRISE) BYTE AT (00014H).

      ***** END OFF-BOARD ADDRESSES *****/

1     DECLARE VELOCITY LITERALLY 34. /* TARGET VELOCITY
      IN UNITS OF 0.1 MILLI-RADIANS PER SEC */

4 1     DECLARE (GOING_ACTION) BYTE, PORTB LITERALLY (00AH),
      DEL_BIGH INTEGER BIGH INTEGER.

5 1     DECLARE (TCOUNT, HTARG1, DEL_HTARG, DEL_MISS, DEL_Y) INTEGER, TONT WORD AT (0F000H);

6 1     TARGET_Y PROCEDURE INTEGER.
7 2     DECLARE (TCOUNT, TTOUNT, HTCOUNT, TENS_COUNT) INTEGER.
8 2     TCOUNT = INT ( NOT TONT ) - TCOUNT0.
9 2     TENS_COUNT = TCOUNT/10.
10 2    HTCOUNT = TCOUNT/100.
11 2    TTOUNT = TCOUNT/1000.
12 2    RETURN (TTOUNT*267 + (HTCOUNT - TTOUNT*10)*27 +
      (TENS_COUNT - HTCOUNT*10)*3).
/* MODEL MOVES 36 7/8" IN 5240 COUNTS IT IS 22 FEET FROM TRAINEE
IT THEREFORE MOVES (36 875/22*12)*10000/5240 = 0.267 (0.1 MRAD/COUNT) */
13 2    END TARGET_Y.

14 1    TIME_DELAY PROCEDURE (HOW_LONG) EXTERNAL.
15 2    DECLARE HOW_LONG WORD.
16 2    END TIME_DELAY.

17 1    DECLARE RESULTS(000) STRUCTURE(S_COUNT INTEGER, S_X INTEGER,
      S_Y INTEGER, S_Z INTEGER, S_GAEX_I INTEGER, S_GAEZ_I INTEGER,
      S_S0TONT INTEGER, S_VMISS INTEGER, S_VOUT INTEGER) AT (2000H),
      T INTEGER.

18 1    DECLARE (BLY, B_Z, DATA_RDY1) BYTE EXTERNAL.
19 1    DECLARE SAVE_TONT INTEGER.

20 1    H_REPRISE PROCEDURE PUBLIC.
21 2    SAVE_TONT = 0.
22 2    H_REF_RD = 1.
23 2    DO WHILE NOT H_REF_GO.
24 2    END.
25 2    H_REF_GO = 0.
26 2    DO I = 0 TO COUNT - 1.

```



```

10 1 IF RESULTS(I) SLS$TENT > SAVE_TENT THEN
11 2 THRUSTER = 0;
12 3 FIRE_BIRD = 1;
13 4 SAVE_TENT = RESULTS(I) SLS$TENT;
14 5 END THRUSTER;
15 6 CALL TIME_DELAY (10);
16 7 BLY = LOW (UNSIGN (100 - RESULTS(I) S_GAEZ(I)));
17 8 BLZ = LOW (UNSIGN (RESULTS(I) SLY + 100));
18 9 DATA_P0Y1 = 1;
19 10 BIRD_DT_P0Y = 1;
20 11 END;
21 12 END REPRISE = 1;
22 13 END H_REPRISE

```

```

40 1 V_REPRISE PROCEDURE PUBLIC;
41 2 SAVE_TENT = 0;
42 3 V_REP_P0Y = 1;
43 4 DO WHILE NOT V_REP_GO;
44 5 END;
45 6 V_REP_P0Y = 0;
46 7 DO I = 1 TO COUNT - 1;
47 8 IF RESULTS(I) SLS$TENT > SAVE_TENT THEN
48 9 THRUSTER = 0;
49 10 FIRE_BIRD = 1;
50 11 SAVE_TENT = RESULTS(I) SLS$TENT;
51 12 END THRUSTER;
52 13 CALL TIME_DELAY (10);
53 14 BLY = LOW (UNSIGN (100 - RESULTS(I) S_GAEZ(I)));
54 15 BLZ = LOW (UNSIGN (RESULTS(I) SLY + 100));
55 16 DATA_P0Y1 = 1;
56 17 BIRD_DT_P0Y = 1;
57 18 END;
58 19 END REPRISE = 1;
59 20 END V_REPRISE;

```

```

60 1 DECLARE GROUND_LOAD LITERALLY 16;
61 2 GROUND_EXP LITERALLY 5;
62 3 HIT_TARGET LITERALLY 1;
63 4 ROCKET_F0R LITERALLY 12;

```

```

64 1 SOUND PROCEDURE (WHAT_KIND) EXTERNAL;
65 2 DECLARE WHAT_KIND BYTE;
66 3 END SOUND;

```

/* THIS VERSION OF "DRAGON" HAS BEEN TESTED AGAINST AN NTEC BASIC-80 PROGRAM. THE BASIC-80 PROGRAM, IN TURN, WAS CHECKED WITH THE MCDONNELL DOUGLAS VERSION OF TYPICAL DRAGON MISSILE FLIGHTS, WITH AND WITHOUT GUNNER ERRORS. NO SIGNIFICANT DIFFERENCES BETWEEN THE VARIOUS PROGRAMS HAVE BEEN FOUND. */

/* THE PROGRAM USES INTEGER MATH EXCLUSIVELY AND REQUIRES 2.12 MILLI-SEC TO EXECUTE EACH PASS THROUGH THE "FLIGHT" LOOP AS DETERMINED USING ICE86. A SOFTWARE, FLOATING-POINT-MATH VERSION WAS TRIED BUT REQUIRED ABOUT 2 SECONDS PER PASS. THE PROGRAM MUST OPERATE IN REAL TIME TO SIMULATE THE MISSILE PERFORMANCE TO DO THIS EACH PASS MUST REQUIRE NO MORE THAN 20 M-SECONDS. THEREFORE, THE FLOATING-POINT VERSION WAS ABANDONED.

THE PURPOSE OF THE PROGRAM IS TO PROVIDE DRAGON CROSS-TRACK POSITION DATA

TO THE SMALL "TV" VIEWER IN THE TRAINEE'S SIGHTING DEVICE THE TV DRIVER WILL BE ON A SEPARATE PC BOARD PLUGGED INTO THE MULTIBUS. THIS WILL REQUIRE MULTIPROCESSOR OPERATION AND ALL M.P. PROTOCOL INCLUDING "MUTUAL EXCLUSION" MUST BE OBSERVED. THE REQUIREMENT, THEREFORE, REMAINS TO ESTABLISH A BLOCK OF MEMORY THAT CAN BE ACCESSED BY MULTIPLE MASTERS ACROSS THE MULTIBUS AND A SEMAPHORE FLAG MUST BE PROVIDED FOR DATA PROTECTION. */

```

64 1  DECLARE (GAEV, GAEZ) WORD EXTERNAL, (GAEV_I, GAEZ_I) INTEGER,
65 1  DECLARE (X, Y, Z, VX, VY, VZ, GAMMA, PHI, DEL$VX, DEL$VY, DEL$VZ) INTEGER,
66 1  DECLARE (H$FOV, V$FOV, FIRE) BYTE,
    (GAIN$FAC, NUTAT, GAIN, REF$VOLT, COUNT) INTEGER,
67 1  DECLARE (HOUT, INT$H, ERR$H, IN$HCOMP) INTEGER,
68 1  DECLARE (VOUT, INT$V, ERR$V, IN$VCOMP) INTEGER,
69 1  DECLARE (HANG, VANG, HMISS, VMISS) INTEGER,
70 1  DECLARE (HTARG, VTARG, XTARG) INTEGER,
71 1  DECLARE FINISHED BYTE PUBLIC, FIRST$FIRE BYTE,
    ($$TENT, INT$FF, COS$PHI, F$FREQ) INTEGER,
72 1  DECLARE (HMISS_HEX, VMISS_HEX, XMISS_HEX) INTEGER PUBLIC,
    (IDEAL_$TENT, TARGET_$TENT) INTEGER PUBLIC,
73 1  DECLARE (DEL$OFF_H, OFF_LN) INTEGER,
74 1  DECLARE SMOOTH(4) INTEGER, II BYTE,

```

```

/* $TENT IS THE NUMBER OF SIDE THRUSTER FIRINGS
   COS$PHI : UNIT = 0.001
   F$FREQ : UNIT = 0.001 FIRE/SEC
   INT$FF : UNIT = 0.001 FIRINGS
   FINISHED IS THE FLAG FOR A HIT GROUND
   COUNT : UNIT = 0.02 SECOND
   GAIN$FAC : UNIT = 0.01 X McDONNELL BASIC PROGRAM "G" UNIT
   NUTATE : UNIT = 10^-4 RADIAN
   GAIN : UNIT = 0.1 VOLT / RADIAN
   REF$VOLT : UNIT = 0.01 VOLT */

```

```

/* H$OUT : UNIT = 0.002 VOLT -- BASIC PROGRAM R1 VALUE
   INT$H : UNIT = 0.002 VOLT -- BASIC PROGRAM 01 VALUE
   GAEV_I : UNIT = 1/2 PIXEL (IS 25 MRAD) -- BASIC PROG. G1/RAD
   LENS FOCAL LENGTH = 125 MM --- SEE DRAGON VAR
   ERR$H : UNIT = 0.002 VOLT -- BASIC PROGRAM I1 VALUE
   IN$HCOMP : UNIT = 0.002 VOLT BASIC PROGRAM P1 VALUE
   V$OUT : UNIT = 0.002 VOLT -- BASIC PROGRAM R2 VALUE
   INT$V : UNIT = 0.002 VOLT -- BASIC PROGRAM 02 VALUE
   GAEZ_I : UNIT = 1/2 PIXEL (IS 25 MRAD) -- BASIC PROG. G2/RAD
   ERR$V : UNIT = 0.002 VOLT -- BASIC PROGRAM I2 VALUE
   IN$VCOMP : UNIT = 0.002 VOLT -- BASIC PROGRAM P2 VALUE
   HMISS & VMISS = 0.1 MRAD -- G1 + E1 & G2 + E2 ANGLE FROM
   MISSILE TO TARGET LINE
   XTARG : UNIT = 2 INCHES -- NOT IN BASIC

```

HTARG * VTARG. UNIT = 0.1 MRAD -- BASIC E1 & E2

* HANG . UNIT 0.1 MILLIRADIAN --- BASIC "E1"

VANG . UNIT 0.1 MILLIRADIAN --- BASIC "E2"

BIGLH : UNIT 0.1 MIL-RAD/50

VANG_BTRG. UNIT 0.1 MILLIRADIAN = HANG

CHNG_BTRG. UNIT 0.1 MILLIRADIAN = VANG */

/* V IN 2 INCHES, VX IN 2 INCHES PER SECOND, Y & Z IN UNITS OF 0.05 INCHES.

VY & VZ IN UNITS OF 0.00 INCHES PER 10 SECONDS. GAMMA & PHI ARE IN DEGREES */

/* OFF_LH IS THE HORIZONTAL DISTANCE OFF TARGET LINE. UNITS OF 0.05 INCHES */

/* THIS PROGRAM ASSUMES THAT EVERY CYCLE REQUIRES 0.02 SECONDS. IT MUST
BE CORRECTED WHEN WE DETERMINE HOW LONG THE THING TAKES */

/* *****

PROGRAM VARIABLE INITIALIZATION

***** */

75 1 INITIATE\$VAR: PROCEDURE PUBLIC:

76 2 TCOUNT = INT(NOT TCNT); /* TCNT COMES INVERTED FROM CY512 BRD */

77 1 HTARG1 = 0; /* HTARG FROM PREVIOUS PASS */

78 2 X = 0;

79 2 OFF_LH, HMISS = 0;

80 1 SMOOTH(0), SMOOTH(1), SMOOTH(2), SMOOTH(3) = 0;

81 2 I = -110;

82 2 VX = 1550;

83 2 VY = 0;

84 2 VZ = 5850;

85 2 GAMMA = 2;

86 2 PHI, HOUT, INT\$H, GRAY_L, VOUT, INT\$V, GRAY_L, HANG, VANG, S\$TCNT, INT\$FF = 0;

87 2 HTARG = TARGET_Y;

88 1 VTARG = 0;

89 2 HTARG = 14655; /* THIS WILL CHANGE WITH FILM DATA NOW = 1000 M */

90 2 IREAL, S\$TCNT = HTARG/720; /***** ASSUMES FIXED XTARG *****/

91 2 FIRE, FINISHED, FIRST\$FIRE, BIRD_HITS, BIRD_MISSES, GRND_BIRD = 0; /* NOTE- TYPE IS ALL BYTE HERE */

92 2 H_REP_PQ, H_REF_LQ, V_REP_PQ, V_REF_LQ, END_PEPPISE = 0;

93 2 DEL_HMISS = 0;

94 2 I = 0;

95 2 COUNT = 0;

96 2 END INITIATE\$VAR;

/* ***** PROGRAM STARTS *****

47 1 FLIGHT: PROCEDURE PUBLIC:

MISSILE DATA SAMPLE

***** */

98 1 H_MISS_HEX = (SMOOTH(0)+SMOOTH(1)+SMOOTH(2)+SMOOTH(3))/4;

99 2 RESULTS, I, S_COUNT=COUNT;

```

100 2 RESULTS(I) SLY=0
101 2 RESULTS(I) SLY = HMISS_HEX
102 2 IF RESULTS(I) SLY < -95 THEN RESULTS(I) SLY = -95
103 2 IF RESULTS(I) SLY > 150 THEN RESULTS(I) SLY = 150
104 2 RESULTS(I) SLZ = ((X/100)*VMISS)/50 /* DITTO */
105 2 IF RESULTS(I) SLZ < -95 THEN RESULTS(I) SLZ = -95
106 2 IF RESULTS(I) SLZ > 150 THEN RESULTS(I) SLZ = 150
107 2 RESULTS(I) S_GAEV_LI=GAEV_LI
108 2 RESULTS(I) S_GAEZ_LI=GAEZ_LI
109 2 RESULTS(I) S_S$TONT=S$TONT

114 2 DO 11 = 0 TO 2
115 2   SMOOTH1 = 11 + SMOOTH2 - 11
116 2   END
117 2 11+1

*****
TINY TANK POSITION
*****

118 2 HTARG = TARGET_LY
119 2 DELHTARG = HTARG - HTARG1
120 2 HTARG1 = HTARG /* SAVE TARGET POSITION TILL NEXT PASS */

121 2 COUNT = COUNT + 1

/* *****
MISSILE DYNAMICS
***** */

122 2 ZANG_BIRD = VANG /* TRANSFER BIRD POSITIONS TO "B_BOARD " */
123 2 YANG_BIRD = HANG
124 2 BIRD_OT_FOV = 1

125 2 DEL$VZ = -3*GAMMA + 186

126 2 IF FIRE = 1 THEN DO
127 2   DEL$VZ = DEL$VZ + 7715 - PHI*PHI
128 2   CALL SOUND(ROCKET_FOV)
129 2   FIRE_BIRD = 1
130 2   END

132 2 GAEV_LI = SIGNED(GAEV)
133 2 GAEZ_LI = SIGNED(GAEZ)

134 2 TARGET_S$TONT = S$TONT
135 2 X_MISS_HEX = X-XTARG
136 2 IF ABS(X_MISS_HEX) < 25 THEN /* 20 ==> 3 & 1/3 FT FROM RANGE OF TARGET */
137 2   AT_TARGET DO
138 2     IF IDEAL_S$TONT > TARGET_S$TONT THEN IDEAL_S$TONT = TARGET_S$TONT
139 2     IF Y < 2000H THEN
140 2       V_MISS_HEX = ((X/100)*VMISS)/600 /* VERT MISS DISTANCE, FT */
141 2       ELSE V_MISS_HEX = ((X/100)*VMISS)/60
142 2       IF ABS(H_MISS_HEX) < 48 AND ABS(V_MISS_HEX) < 3 THEN /* IN 8X6 FT RECTANGLE */
143 2         GOOD_SHOT DO
144 2           CALL SOUND(HIT_TARGET)
145 2

```

```

146 4      BIRD_HITS = 1.
147 4      BIRD_MISSES = 0.
148 4      FINISHED = 1.
149 4      END GOOD_SHOT.
150 3      ELSE BACK_SHOT BIRD_MISSES = 1.
151 1      END AT_TARGET.

152 2      WZ = WZ + DEL$WZ / 2.
153 2      Z = Z + WZ / 125.
154 2      VZ = VZ + DEL$VZ / 2.

155 2      DEL$VZ = -Z.
156 2      IF FIRE = 1 THEN DEL$VX = DEL$VX + 6Z.
158 2      VX = VX + DEL$VX / 2.
159 2      DEL$X = VX/50.
160 2      X = X + DEL$X.
161 2      VX = VX + DEL$VX / 2.

162 2      GAMMA = VZ / (VX*2.).

163 2      IF FIRE = 1 THEN DEL$VY = -(21598-PI*PI)/160)*PI.
165 2      ELSE DEL$VY = 0.
166 2      VY = VY + DEL$VY / 2.
167 2      DEL_OFF_H = VY/125 + ((DEL$X/10)*HMISS/25) + (X/250)*DEL_HTARG.
168 2      OFF_H = OFF_H + DEL_OFF_H.
169 2      SMOOTH(O) = OFF_H/20.
170 2      VY = VY + DEL$VY / 2.
171 2      FIRE = 0.

```

DEFINING ANGLES

/* WE INTRODUCE THE TARGET DATA FOR TARGET MOVEMENT FROM I C */

```

172 2      IF COUNT > 5 THEN /* TO AVOID A "DIVIDE BY ZERO" WHEN CALCULATING "HMISS" */
173 2      ANGLES DO.
174 1      HMISS = (2*OFF_H)/(X*120.).
175 1      VMISS = (2*(X/128) - VTARG.
176 1      HANG = HMISS + 5*GRAVY/12.
177 1      VANG = VMISS + 5*GRAVZ/12.
178 1      END ANGLES.

```

THIS IS THE TRACKER GAIN SECTION

```

179 2      GAIN$FAC = (1448 - 2 * COUNT)/10.
180 2      IF GAIN$FAC > 140 THEN GAIN$FAC = 140.
181 2      IF GAIN$FAC < 100 THEN GAIN$FAC = 100.
182 2      IF COUNT < 94 THEN NUTAT = 240. /* WITH 125MM LENS. FOV IS 24 MPAD */
183 2      ELSE NUTAT = ((28595/GAIN$FAC)*100)/COUNT.
184 2      IF COUNT > 47 THEN REF$VOLT = 875.
185 2      ELSE REF$VOLT = 18 * COUNT.
186 2      IF REF$VOLT > 875 THEN REF$VOLT = 875.
187 2      IF COUNT < 46 THEN GAIN = 43 * COUNT.

```

```

194 0      ELSE GAIN = 110 * ( 8750 / NUTAT )

*****
      (CHECK FOR NUTATION RADIUS EXCEEDED)
*****
195 0      H$FOV,V$FOV = 0.
196 0      IF COUNT > 20 THEN
197 0      CHECK$FOV DO.
198 0          IF (ABS(H$ANG) > NUTAT) THEN H$FOV = 1.
200 0          IF (ABS(V$ANG) > NUTAT) THEN V$FOV = 1.
202 0      END CHECK$FOV

/*****
      THIS IS THE HORIZONTAL RATE POSITION PORTION
*****/

207 0      IF NOT H$FOV THEN
208 0      CALC$H DO.
209 0          IF COUNT < 22 THEN IN$HCOMP = (GAIN/10)*H$ANG/20. /* COUNT=22 (==) TIME= 44 S
                                     & FIRST FIRE OCCURS @ 474 S */
210 0          ELSE IN$HCOMP = (GAIN/200)*H$ANG.
211 0          END CALC$H
212 0          ELSE IN$HCOMP = (REF$VOLT/5)*H$ANG/(ABS(H$ANG)).

213 0      ERR$H = IN$HCOMP - HOUT.
214 0      HOUT = INT$H/10 + 3*IN$HCOMP.
215 0      INT$H = INT$H + ERR$H.

/*****
      HORIZONTAL WIRE
*****/

216 0      PHI = HOUT/50.
217 0      IF PHI < -75 THEN PHI = -75.
218 0      IF PHI > 75 THEN PHI = 75.

/*****
      THIS IS THE VERTICAL RATE POSITION PORTION
*****/

219 0      IF NOT V$FOV THEN
220 0      CALC$V DO.
221 0          IF COUNT < 22 THEN IN$VCOMP = (GAIN/10)*V$ANG/20.
222 0          ELSE IN$VCOMP = (GAIN/200)*V$ANG.
223 0          END CALC$V.
224 0          ELSE IN$VCOMP = (REF$VOLT/5)*V$ANG/(ABS(V$ANG)).

225 0      ERR$V = IN$VCOMP - VOUT.
226 0      VOUT = INT$V/5 + 9*IN$VCOMP.
227 0      INT$V = INT$V + ERR$V.

228 0      ERR$W = IN$VCOMP - VOUT. /* HERE WE TAKE INTEGRATION @ 1/2 OF "COUNT" TWICE */
229 0      VOUT = INT$V/5 + 9*IN$VCOMP.
230 0      INT$V = INT$V + ERR$V.

/*****
      FIRE PULSE GENERATION
*****/

```

```

*****/
231 1  F$FREQ = (14000 - 7*VOUT)/5.
232 2  COS$PHI = 995 - (PHI*PHI)/7.

233 2  IF COUNT = 24 THEN
234 2  FIRST$SHOT = 0.
235 1  FIRE = 1.
236 1  S$TINT = 1.
237 1  INT$FF = 0.
238 3  FIRST$FIRE = 1.
239 3  END FIRST$SHOT.

240 2  IF FIRST$FIRE THEN
241 2  CANFIRE = 0.
242 3  IF S$TINT < 30 THEN
243 1  SOME$LEFT = 0.
244 4  IF INT$FF > COS$PHI THEN
245 4  FIRE$ONE = 0.
246 5  INT$FF = 0.
247 5  FIRE = 1.
248 5  S$TINT = S$TINT + 1.
249 5  END FIRE$ONE.
250 4  INT$FF = INT$FF + F$FREQ/50.
251 4  END SOME$LEFT.
252 3  END CANFIRE.

253 2  IF Z < -720 THEN
254 2  GROUNDED = 0.
255 3  FINISHED$GRND$BIRP = 1.
256 1  IF COUNT > 25 THEN CALL SOUND (GROUND$EXP).
257 1  ELSE CALL SOUND (GROUND$DUD).
258 1  END GROUNDED.

259 1  END FLIGHT.

260 1  END DRAGON$FLIGHT$MODULE.

```

MODULE INFORMATION

```

CODE AREA SIZE   = 0A03H   2671D
CONSTANT AREA SIZE = 0000H    0D
VARIABLE AREA SIZE = 0A02H   130D
MAXIMUM STACK SIZE = 0A08H    8D
400 LINES PERD
0 PROGRAM ERROR(S)

```

END OF PLM-R6 COMPILATION

ISIS-11 MCS-86 MACRO ASSEMBLER V2.1 ASSEMBLY OF MODULE IP_CENTER
 OBJECT MODULE PLACED IN: F1.DRAG12.OBT
 ASSEMBLER INVOKED BY: ARM86 F1.DRAG12.001 DEBUG DATE (02/24/89)

```

LOC  OBJ      LINE      SOURCE
                                1      NAME      IP_CENTER
                                2
                                3      .THIS IS A DRIVER PROGRAM FOR THE PETICON 6020 USING THE 86/12 BOARD
                                4      .IT IS BEING UPDATED 9/23/81
                                5
                                6      DGROUP GROUP    DATA, STACK, SBC_PEGS, XFER_SEG
                                7      CGROUP GROUP    CODE
                                8
                                9      ASSUME SS DGROUP, CS CGROUP, DS DGROUP, ES DGROUP
                               10
                               11      STACK SEGMENT STACK  STACK
00000 164      12          DW      64 DUP(?)
                               13
00000 164      13      TOP_STK LABEL  WORD
                               14      STACK  ENDS
                               15
                               16      .THIS PROGRAM WILL RESIDE ON THE SBC "DFS" IT WILL WRITE V. 2(CENTER)
                               17      .DATA TO THE SBC "PIP" VIA THE MULTIBUS THE "PIP" HAS BEEN "JUMPED"
                               18      .SO AS TO ALLOW THE MULTIBUS TO ACCESS 8K OF ITS RAM STARTING AT LOCATION
                               19      .A000H. THE "DFS" JUMPERS ALLOW MULTIBUS ACCESS TO 8K OF RAM STARTING
                               20      .AT 8000H. THE ON-BOARD LOCATION OF THESE AVAILABLE 8K-S START AT 6000H
                               21      .ON BOTH BOARDS. THE BOARDS (REF FIG 2-1 86/12) ARE JUMPED AS FOLLOWS:
                               22
                               23      .
                               24      . SBC DFS JUMPERS MULTIBUS ACCESS      SBC PIP JUMPERS MULTIBUS ACCESS
                               25      .-----
                               26      .      127-128 ==> X = 0                      127-128 ==> X = 0
                               27      .      S1 6-11 CLOSED                      S1 6-11 CLOSED
                               28      .      S1 5-12 "      ==> 8K              S1 5-12 "      ==> 8K
                               29      .      S1 1-16 "                      S1 1-16 "
                               30      .      S1 2-15 OPEN                      S1 2-15 OPEN
                               31      .      S1 3-14 CLOSED                      S1 3-14 CLOSED
                               32      .      S1 4-13 "      ==> 8000H          S1 4-13 OPEN ==> A000H
                               33      .
                               34
                               35      XFER_SEG      SEGMENT AT A000H      ON SBC "PIP" AS NOTED ABOVE
                               36      .IF THE "DFS" IS THE DATA "SUPPLIER" AND THE "PIP" IS THE "USER"
                               37
00000 164      38      START_BIT      DB      1 DUP(?)
                               39
00001 164      39      PUBLIC  B_LV, B_LZ, DATA_RDY1
                               40      B_LV      DB      1 DUP(?)
                               41
00002 164      41      B_LZ      DB      1 DUP(?)
                               42
00003 164      42      DATA_RDY1      DB      1 DUP(?)

```


LOC	DB	LINE	SOURCE
0000	1	43	BAD_MISS DB 1 DUP(?)
0001	1	44	OFFSET_Y DB 1 DUP(?)
0002	1	45	OFFSET_Z DB 1 DUP(?)
0003	1	46	XFER_SEG ENDS
0004	1	47	
0005	1	48	SBC_REGS SEGMENT COMMON
0006	1	49	SBCREG DB 800 DUP(?)
0007	1		
0008	1	50	MISS DB 1 DUP(?) IN RT86XF
0009	1		
0010	1	51	
0011	1	52	RIGHT DB 1 DUP(?)
0012	1		
0013	1	53	LEFT DB 1 DUP(?)
0014	1		
0015	1	54	UP DB 1 DUP(?)
0016	1		
0017	1	55	DOWN DB 1 DUP(?)
0018	1		
0019	1	56	DB 1 DUP(?)
0020	1		
0021	1	57	VCTR DB 1 DUP(?)
0022	1		
0023	1	58	ZCTR DB 1 DUP(?)
0024	1		
0025	1	59	YMAX DB 1 DUP(?)
0026	1		
0027	1	60	YMIN DB 1 DUP(?)
0028	1		
0029	1	61	ZMAX DB 1 DUP(?)
0030	1		
0031	1	62	ZMIN DB 1 DUP(?)
0032	1		

THE FOLLOWING 6 BYTES ARE NAMED "PARTLY_OFF"

DUMMY BYTE TO MAKE 3 WORDS OF "PARTLY_OFF" IN RT86XF

THE FOLLOWING 6 BYTES ARE IN "LOCATIONS" IN RT86XF

OP1	LINE	SOURCE
	114	
	115	THIS INDICATES THREE TRANSITIONS IN THE LINE BUT ONLY THE FIRST TWO ARE
	116	SIGNIFICANT AT 10H THERE IS A DARK-TO-LIGHT TRANSITION, AS INDICATED BY THE
	117	HIGHEST ORDER BIT (HOB) = 0 IN DATA BYTE #3 (60). THE FOLLOWING TRANSITION
	118	IS AT 1EH AND IS A LIGHT-TO-DARK, AS INDICATED BY HOB=1 IN THE FOLLOWING
	119	BYTE #5 (E0). EVERY LINE HAS A FORCED TRANSITION AT THE END-OF-LINE.
	120	LOCATION 64H=1000. THE PROGRAM STARTS FROM LINE #0 LOOKING FOR 03 AS THE
	121	INITIAL DATA BYTE. IF 03 IS NOT FOUND, THE NEXT LINE IS EXAMINED. THIS IS
	122	CONTINUED UNTIL 100 LINES HAVE BEEN EXAMINED FOR THE PROPER NUMBER OF
	123	TRANSITIONS
	124	
	125	REGISTER USAGE IN "CENTER"
	126	(AL) = NUMBER OF TRANSITIONS IN DATA LINE
	127	(AH) = BYTES TO ADD TO DATA LINE POINTER
	128	(BX) = DATA LINE POINTER. POINTS TO START OF DATA LINE IN "SBREG"
	129	(CL) = LINE NUMBER
	130	(CH) = 64H = 100 ==> THE LAST DATA LINE
	131	
0022 8901F5	132	CENTER MOV CX,6501H ; (CH)=65H, 1 + LAST LINE (CL)=1 --> FIRST LINE
0025 BFEFF	133	MOV BX,-2 ; INITIAL VALUE OF DATA LINE POINTER
0028 B402	134	MOV AH,2 ; INITIAL DATA LINE POINTER INCREMENT
002H C606290364	135	MOV YMIN,SIZ ; SET INITIAL VALUE AT 64H
002F C6062B0364	136	MOV ZMIN,SIZ ; DITTO FOR ZMIN
0034 C606280361	137	MOV YMAX,1
0037 C6062A0361	138	MOV ZMAX,1
	139	
003E 7AE9	140	DUMP CMP CH,CL ; HAVE WE FINISHED WITH LAST LINE?
0040 7502	141	JNE OVER ; NEED "OVER" BECAUSE CONDITIONAL JUMPS MUST BE
	142	LESS THAN +127 BYTES AWAY
0042 EB0E90	143	JMP DONE
0045 020C	144	OVER ADD BL,AH ; UPDATE DATA LINE POINTER. NOW BECAUSE WE CANNOT
0047 800700	145	ADC BH,0 ; ADD A SINGLE BYTE TO BX, WE DO IT IN TWO STEPS
	146	USING THE CARRY FLAG, "CY". N.B. (BX)=0 ON
	147	THE FIRST PASS THROUGH "DUMP."
	148	
004A 8A070000	149	MOV AL,SBREG[BX] ; FIRST DATA BYTE ==> TRANSITIONS IN DATA LINE
	150	
004E 8AE0	151	MOV AH,AL ; WILL FORM DATA LINE POINTER INCREMENT IN AH
0050 FEC4	152	INC AH
0052 D0E4	153	SHL AH,1 ; (AH)=2(AL+1), THE DATA LINE POINTER INCREMENT
	154	
0054 8A070200	155	MOV AL,SBREG[BX+2]
005A 3064	156	CMP AL,SIZ
005C 7405	157	JE SKIP ; IF NO SPOT, THEN GO TO NEXT DATA LINE
005E E80000	158	CALL GOODLN ; WILL UPDATE SPOT INFORMATION
005F FB00	159	JMP DUMP ; GO TO NEXT DATA LINE
	160	
0061 3AC0	161	SKIP CMP CL,CH ; THE LAST LINE?
0063 7440	162	JZ DONE ; YES! SO WE JUMP TO THE FINAL CLEAN-UP
0065 FEC1	163	INC CL ; NO! SO WE RETURN TO "DUMP" AND
0067 EB05	164	JMP DUMP ; EXAMINE THE NEXT LINE
	165	
0069 30BF000007	166	GOODLN CMP SBREG[BX],2 ; ONLY TWO TRANSITIONS?
006E 7419	167	JE TWOX ; IF SO, SPOT IS ON RIGHT EDGE
0070 3A062907	168	CMP AL,YMIN ; IF NOT, GET NORMAL CENTER. RECALL THAT

LOC	OP	LINE	SOURCE
		169	
0074	JA	170	N1
		171	
		172	
		173	
		174	
		175	
		176	
		177	
		178	
		179	
0076	MOV	180	YMIN, AL
0079	MOV	181	N1
007D	MOV	182	AL, SBCREG[4]
0081	CMF	183	AL, YMAX
0083	JB	184	N4
0086	MOV	185	YMAX, AL
0089	MOV	186	N4
008E	MOV	187	YMAX, 64H
0092	MOV	188	AL, SBCREG[2]
0096	CMF	189	AL, YMIN
0099	JA	190	N4
009E	MOV	191	YMIN, AL
00A4	CMF	192	CL, ZMAX
00A1	JB	193	N3
00A5	MOV	194	ZMAX, CL
00A9	CMF	195	CL, ZMIN
00AB	JA	196	N9
00AF	MOV	197	ZMIN, CL
00B1	INC	198	CL
	PET	199	
00B2	MOV	200	MISS, 0
00B7	CMF	201	ZMIN, 64H
00B8	JNE	202	N5
00BE	MOV	203	MISS, 1
00C3	MOV	204	BAD_MISS, 1
00C8	JMP	205	READ
00CE	CMF	206	ZMIN, 1
00D0	JNE	207	N6
00D2	MOV	208	UP, 1
00D7	CMF	209	ZMAX, 64H
00DC	JNE	210	N7
00DE	MOV	211	DOWN, 1
00E7	CMF	212	YMIN, 1
00E8	JNE	213	N8
00FA	MOV	214	LEFT, 1
00FF	CMF	215	YMAX, 64H
00F4	JNE	216	FINI
00F8	MOV	217	RIGHT, 1
		218	
00FB	MOV	219	FINI
00FD	SUB	220	AL, ZMAX
0101	MOV	221	AL, 65H
0103	SUB	222	AL, ZMIN
0107	MOV	223	ZMIN, AL

LOC	OBJ	LINE	SOURCE
0100	80262003	R 224	MOV ZMAX, AH
010E	A02003	R 225	MOV AL, YMAX
0111	02062003	R 226	ADD AL, YMIN
0115	8A1E0500	R 227	MOV BL, OFFSET_Y ; HORIZONTAL BORESIGHT OFFSET
0119	0203	228	ADD AL, BL
011B	A22603	R 229	MOV YCNTR, AL ; YCNTR IN HALF-PIXELS FROM LEFT SIDE OF SCREEN
011E	A20100	R 230	MOV B_V, AL
0121	B464	231	MOV AH, 100
0123	0AE0	232	SUB AH, AL
0125	8AC4	233	MOV AL, AH
0127	98	234	CBW
0128	A32003	R 235	MOV GAEZ, AX ; GAEZ +IVE TO THE RIGHT CAMERA INVERTS
012B	A02003	R 236	MOV AL, ZMAX
012E	02062003	R 237	ADD AL, ZMIN
0132	8A1E0600	R 238	MOV BL, OFFSET_Z
0136	0203	239	ADD AL, BL
0138	A22703	R 240	MOV ZCNTR, AL ; ZCNTR IN HALF-PIXELS FROM BOTTOM OF SCREEN
013B	A20200	R 241	MOV B_Z, AL
013E	B464	242	MOV AH, 100
0140	0AE0	243	SUB AH, AL
0142	8AC4	244	MOV AL, AH
0144	98	245	CBW
0145	A32E03	R 246	MOV GAEZ, AX ; GAEZ +IVE IF HIGH. REF. McDONNELL-DOUGLAS
0148	B001	247	READ MOV AL, 1
014A	A20300	R 248	MOV DATA_RDY1, AL ; THIS TELLS THE SLAVE PROCESSOR THAT NEW
		249	; DATA ARE READY.
014D	1F	250	POP DS
014E	5D	251	POP BP
014F	07	252	RET
		253	
		254	YCNTR ENDP
		255	
----		256	CODE ENDS
		257	
		258	END

ASSEMBLY COMPLETE, NO ERRORS FOUND

TS15-11 PLM-86 V2.1 COMPILATION OF MODULE MAIN.DRAGON_MODULE
 OBJECT MODULE PLACED IN F1 DRAGMN.OBJ
 COMPILER INVOKED BY PLM86 F1 DRAGMN.PLM DEBUG ROM IXREF DATE (10/01/10)

```

1      MAIN.DRAGON_MODULE DO.

      /*****
      OFF-BOARD ABSOLUTE ADDRESSES
      *****/

2      1  DECLARE (H_MIS_ASCII,V_MIS_ASCII,X_MIS_ASCII) (16) BYTE AT (0A020H).
      2      FELL_SHORT BYTE AT (0A01EH);

      /***** END OFF-BOARD ABSOLUTE ADDRESSES *****/

3      1  DECLARE (H_MISS_HEX,V_MISS_HEX,X_MISS_HEX) INTEGER EXTERNAL, 1 BYTE;

4      1  SHOW_THRUSTERS PROCEDURE EXTERNAL;
5      2  END SHOW_THRUSTERS;

6      1  MISS_COMMENT PROCEDURE(HEX$ADR, DEC$ADR, DIRECTION) EXTERNAL;
7      2  DECLARE (HEX$ADR, DEC$ADR) POINTER, DIRECTION BYTE;
8      2  END MISS_COMMENT;

9      1  DECLARE RT LITERALLY '0', LT LITERALLY '1',
      2  UP LITERALLY '2', DN LITERALLY '3',
      3  SH LITERALLY '4';

10     1  DECLARE FOREVER LITERALLY 'WHILE 1', NO_TRIG_PUL LITERALLY
      2  'INPUT(PORT_B) AND 1', ACTION BYTE;

11     1  V_REPRISE PROCEDURE EXTERNAL;
12     2  END V_REPRISE;

13     1  H_REPRISE PROCEDURE EXTERNAL;
14     2  END H_REPRISE;

15     1  TIME_DELAY PROCEDURE (HOW_LONG) EXTERNAL;
16     2  DECLARE HOW_LONG WORD;
17     2  END TIME_DELAY;

18     1  SETRET PROCEDURE EXTERNAL;
19     2  END SETRET;

20     1  SOUND PROCEDURE(KIND) EXTERNAL;
21     2  DECLARE KIND BYTE;
22     2  END SOUND;

23     1  DECLARE INITIAL_BANG LITERALLY '7', GYRO_START LITERALLY '1';

24     1  DECLARE ARM LITERALLY '2', DISARM LITERALLY '3',
      2  DROP LITERALLY '4', NO_DROP LITERALLY '5',
      3  FINISHED BYTE EXTERNAL;

25     1  DECLARE PORT_A LITERALLY '0C8H', PORT_B LITERALLY '0CAH';

```

PORT_C LITERALLY '00CH', CONTROL LITERALLY '0CEH';

```

26 1  YZCNTR PROCEDURE EXTERNAL;
27 2  END YZCNTR;

28 1  PPI_SET PROCEDURE EXTERNAL; /* SETS UP PORTS_A & _C OUTPUT, PORT_B INPUT */
29 2  END PPI_SET;

30 1  FLIGHT PROCEDURE EXTERNAL;
31 2  END FLIGHT;

32 1  INITIATE$VAR PROCEDURE EXTERNAL;
33 2  END INITIATE$VAR;

/******
PROGRAM STARTS
******/

34 1  START_UP;
    CALL PPI_SET;

35 1  OUTPUT(CONTROL) = NO_DROP /* DRIVES PORT_C BIT-2 HIGH & J1-20 LOW */

36 1  OUTPUT(CONTROL) = ARM; /* DRIVES PORT_C BIT-1 LOW & "J1"-22 HIGH */
    /* PROBABLY NOT NEEDED --- PORT_C COMES UP LOW FOLLOWING PPI_SET */

37 1  DO I = 0 TO 95;
38 2  H_MIS_ASCII(I) = 0;
39 2  END;

40 1  CALL INITIATE$VAR; /* FOR DRAGON FLIGHT */

41 1  DO WHILE NO_TRIG_PUL;
42 2  END;

43 1  CALL SOUND(GYRO_START);

44 1  CALL TIME_DELAY(560);

45 1  OUTPUT(CONTROL) = DROP;

46 1  OUTPUT(CONTROL) = DISARM;

47 1  CALL SOUND(INITIAL_BANG);

48 1  CALL SETPET;

49 1  DRAGON_FLYS DO WHILE NOT FINISHED;
50 2  CALL YZCNTR;
51 2  CALL FLIGHT;
52 2  END DRAGON_FLYS;

53 1  IF H_MISS_HEX > 2 THEN CALL MISS_COMMENT@H_MISS_HEX, @H_MIS_ASCII, PT);
55 1  IF H_MISS_HEX < -2 THEN CALL MISS_COMMENT@H_MISS_HEX, @H_MIS_ASCII, LT);
57 1  IF V_MISS_HEX > 2 THEN CALL MISS_COMMENT@V_MISS_HEX, @V_MIS_ASCII, UP);
59 1  IF V_MISS_HEX < -2 THEN CALL MISS_COMMENT@V_MISS_HEX, @V_MIS_ASCII, DN);

61 1  IF X_MISS_HEX < -24 THEN

```

```
62 1      DROP_SHORT DO;
63 2      %MISS_HEX = IABS(X_MISS_HEX)/6;
64 2      CALL MISS_COMMENT(@X_MISS_HEX,@X_MIS_ASCII,SH);
65 2      FELL_SHORT = 1;
66 2      END DROP_SHORT;
67 1      ELSE FELL_SHORT = 0;

68 1      CALL SHOW_THRUSTERS;

69 1      ACTION_WAIT      /* WAIT FOR REPRISE */
      DO FOREVER;
70 2      ACTION = NOT (INPUT(PORT_B));
71 2      IF ACTION = 2 THEN CALL H_REPRISE;
72 2      IF ACTION = 4 THEN CALL V_REPRISE;
73 2      END ACTION_WAIT;

74 1      END MAIN_DRAGON_MODULE;
```

MODULE INFORMATION

```
CODE AREA SIZE      = 0181H    3850
CONSTANT AREA SIZE = 0000H      00
VARIABLE AREA SIZE = 0002H      20
MAXIMUM STACK SIZE = 000CH     120
125 LINES READ
0 PROGRAM ERROR(S)
```

END OF PL/M-86 COMPILATION

1985-11 PL/M-86 V2.1 COMPILATION OF MODULE DRAGONUTILITY
 OBJECT MODULE PLACED IN F1 DRAGUT.OBJ
 COMPILER INVOKED BY: PLM86 F1 DRAGUT PLM DEBUG ROM IXREF DATE (02/24/89)

```

1      DRAGONUTILITY DO:

      /*****
      OFF-BOARD ABSOLUTE ADDRESSES
      *****/

2      1      DECLARE (ACTUAL_THRUSTER_ASCII, IDEAL_THRUSTER_ASCII) (24) BYTE AT (0A050H),
              DUMMY_BYTE AT (0A020H).

      /***** END OFF-BOARD ABSOLUTE ADDRESSES *****/

3      1      DECLARE COUNTER0 LITERALLY '000H', COUNTER1 LITERALLY '002H',
              CONTROL LITERALLY '006H' /* SEE PAGE 3-3 IN 86/12 MAN */
4      1      DECLARE CNTR0MODE LITERALLY '34H' /* 2 BYTES, MODE 2 */
              CNTR1MODE LITERALLY '74H' /* 2 BYTES, MODE 2 */

      /* TO PROGRAM THE 8253 PROGRAMMABLE INTERVAL TIMER OR "PIT" NOTE THAT */
      /* THE INPUT FREQUENCY TO CLK0 IS 1.23 MHZ ==> AN 813 NANOSEC PERIOD */

5      1      DECLARE LOW0 LITERALLY '05' /* COUNTER 0 PERIOD IS 5 MILLISECONDS */
              HIGH0 LITERALLY '18H'

      /* NOW WE WILL CONNECT OUT0 TO CLK1 BY JUMPER 59-61 INSTEAD OF THE
      DEFAULT CONNECTION, WHICH IS 59-60. */

6      1      DECLARE LOW1 LITERALLY '5FH' /* COUNTER 1 PERIOD IS 5 MINUTES */
              HIGH1 LITERALLY '0EAH' /* = 5 MIN * 60 (SEC/MIN) / 0.005 SEC -1 IN HEX */

7      1      DECLARE TIME$LATCH LITERALLY '40H' /* A COUNTER 1 LATCH PAGE 3-13 OF 86/12 */
              (LS$TIME$BYTE, MS$TIME$BYTE) BYTE PUBLIC.
8      1      DECLARE TIME ADDRESS PUBLIC.
9      1      DECLARE LOW$TIME$BYTE BYTE AT (TIME), HIGH$TIME$BYTE BYTE AT (TIME + 1),

10     1      TIMER$START PROCEDURE PUBLIC.
11     2      OUTPUT(CONTROL)=CNTR0MODE, /* SET COUNTERS 0 & 1 MODES */
12     2      OUTPUT(CONTROL)=CNTR1MODE,
13     2      OUTPUT(COUNTER0)=LOW0, /* INITIALIZE COUNTERS */
14     2      OUTPUT(COUNTER0)=HIGH0,
15     2      OUTPUT(COUNTER1)=LOW1,
16     2      OUTPUT(COUNTER1)=HIGH1,
17     2      END TIMER$START.

18     1      CLOCK$READ PROCEDURE ADDRESS PUBLIC, /* GETS THE CONTENTS OF COUNTER 1 */
19     2      OUTPUT(CONTROL)=TIME$LATCH,
20     2      LOW$TIME$BYTE=INPUT(COUNTER1),
21     2      HIGH$TIME$BYTE=INPUT(COUNTER1),
22     2      RETURN TIME,
23     2      END CLOCK$READ.

24     1      DECLARE (IDEAL_$TONT, TARGET_$TONT) INTEGER EXTERNAL.
  
```

```

      /* N.B. REFERENCES ARE TO ISOB 86/12 9800645A */

25 1  DECLARE PPI_CONTROL LITERALLY '0CEH', BUS_FREE LITERALLY '0BH';

26 1  DECLARE SENARIO BYTE AT '6000H';

27 1  TARGET_LOC PROCEDURE (ID) INTEGER PUBLIC;
28 2  DECLARE ID BYTE; /* ID IS IDENTIFICATION OF H.V. OF X TARG */
29 2  DECLARE POSITION INTEGER;

30 2  IF SENARIO = 'A' THEN
31 2  SCENE_A DO;
32 3  IF ID = 1 THEN
33 3  TARG_H DO; /* REPEAT FOR V AND X OF TARGET */
34 4  END TARG_H;
35 3  RETURN POSITION;
36 3  END SCENE_A;

37 2  IF SENARIO = 'B' THEN /* ETC. ETC */
38 2  SCENE_B DO;
39 3  END SCENE_B;

40 2  END TARGET_LOC;

41 1  INIT_STEPPER PROCEDURE PUBLIC;
42 2  IF SENARIO = 'A' THEN
43 2  INIT_A DO;
44 3  END INIT_A;

45 2  IF SENARIO = 'B' THEN /* ETC. ETC */
46 2  INIT_B DO;
47 3  END INIT_B;

48 2  END INIT_STEPPER;

49 1  HX2AS PROCEDURE (HEX_ADR, ASCII_ADR) PUBLIC;
50 2  DECLARE (HEX_ADR, ASCII_ADR) POINTER, HEX BASED HEX_ADR INTEGER,
      ASCII BASED ASCII_ADR (5) BYTE, (N,M) BYTE, REMAINDER INTEGER;

51 2  HEX = IABS(HEX);
52 2  DO N=0 TO 4;
53 3  M = 4-N;
54 3  REMAINDER = HEX M/10 + 30H;
55 3  ASCII(M) = LOW(UNSIGN(REMAINDER));
56 3  HEX = HEX/10;
57 3  END;
58 2  N=0;

59 2  DO WHILE ASCII(N) = 30H AND N<5; /* REPLACE LEADING ZEROS WITH BLANKS */
60 3  ASCII(N) = 20H;
61 3  N = N+1;
62 3  END;
63 2  END HX2AS;

64 1  SHOW_THRUSTERS PROCEDURE PUBLIC;
65 2  CALL HX2AS(@TARGET_S$CONT, @ACTUAL_THRUSTER_ASCII);

```

```

66 1      ACTUAL_THRUSTER_ASCII(5) = 'T';
67 2      ACTUAL_THRUSTER_ASCII(6) = 'H';
68 2      ACTUAL_THRUSTER_ASCII(7) = 'R';
69 2      ACTUAL_THRUSTER_ASCII(8) = 'U';
70 2      ACTUAL_THRUSTER_ASCII(9) = 'S';
71 2      ACTUAL_THRUSTER_ASCII(10) = 'T';
72 2      ACTUAL_THRUSTER_ASCII(11) = 'E';
73 2      ACTUAL_THRUSTER_ASCII(12) = 'R';
74 2      ACTUAL_THRUSTER_ASCII(13) = 'S';
75 2      ACTUAL_THRUSTER_ASCII(14) = 'U';
76 2      ACTUAL_THRUSTER_ASCII(15) = 'U';
77 2      ACTUAL_THRUSTER_ASCII(16) = 'S';
78 2      ACTUAL_THRUSTER_ASCII(17) = 'E';
79 2      ACTUAL_THRUSTER_ASCII(18) = 'D';

80 2      CALL HX2ASC(IDEAL,$TONT,@IDEAL_THRUSTER_ASCII);
81 1      IDEAL_THRUSTER_ASCII(5) = 'T';
82 2      IDEAL_THRUSTER_ASCII(6) = 'H';
83 2      IDEAL_THRUSTER_ASCII(7) = 'R';
84 2      IDEAL_THRUSTER_ASCII(8) = 'U';
85 2      IDEAL_THRUSTER_ASCII(9) = 'S';
86 2      IDEAL_THRUSTER_ASCII(10) = 'T';
87 2      IDEAL_THRUSTER_ASCII(11) = 'E';
88 2      IDEAL_THRUSTER_ASCII(12) = 'R';
89 2      IDEAL_THRUSTER_ASCII(13) = 'S';
90 2      IDEAL_THRUSTER_ASCII(14) = 'U';
91 2      IDEAL_THRUSTER_ASCII(15) = 'U';
92 2      IDEAL_THRUSTER_ASCII(16) = 'D';
93 2      IDEAL_THRUSTER_ASCII(17) = 'E';
94 2      IDEAL_THRUSTER_ASCII(18) = 'R';
95 2      IDEAL_THRUSTER_ASCII(19) = 'U';
96 2      IDEAL_THRUSTER_ASCII(20) = 'U';
97 2      IDEAL_THRUSTER_ASCII(21) = 'Y';

98 2      END; SHOW_THRUSTERS;

99 1      MISS_COMMENT PROCEDURE(HEX$ADR, DEC$ADR, DIRECTION) PUBLIC;
100 2      DECLARE(HEX$ADR, DEC$ADR) POINTER;
           PHRASE FASED(DEC$ADR * 16) BYTE; (N,DIRECTION) BYTE;

101 2      CALL HX2ASC(HEX$ADR, DEC$ADR);

102 2      PHRASE(5) = 'T';
103 2      PHRASE(6) = 'H';
104 2      PHRASE(7) = 'R';
105 2      PHRASE(8) = 'U';
106 2      PHRASE(9) = 'S';
107 2      PHRASE(10) = 'T';
108 2      DO CASE DIRECTION;
109 1          NO;
110 4          PHRASE(11) = 'R';
111 4          PHRASE(12) = 'S';
112 4          PHRASE(13) = 'U';
113 4          PHRASE(14) = 'H';
114 4          PHRASE(15) = 'T';
115 4          END;
116 2      DO;

```

```

117 4 PHRASE(11) = 1.
118 4 PHRASE(12) = 2.
119 4 PHRASE(13) = 3.
120 4 PHRASE(14) = 4.
121 4 END.
122 DO.
123 4 PHRASE(11) = 5.
124 4 PHRASE(12) = 6.
125 4 PHRASE(13) = 7.
126 4 PHRASE(14) = 8.
127 4 END.
128 DO.
129 4 PHRASE(11) = 9.
130 4 PHRASE(12) = 0.
131 4 PHRASE(13) = 1.
132 4 END.
133 DO.
134 4 PHRASE(11) = 2.
135 4 PHRASE(12) = 3.
136 4 PHRASE(13) = 0.
137 4 PHRASE(14) = 1.
138 4 PHRASE(15) = 1.
139 4 END.
140 3 END.
141 2 END MISS COMMENT.

142 1 SOUND: PROCEDURE (WHAT) IND: PUBLIC.
143 2 DECLARE WHAT IND: BYTE. PORTA LITERALLY 008H.
144 2 OUTPUT (PORTA) = WHAT IND. /* SOUND COMMAND OUTPUT THRU PORTA */
145 2 OUTPUT (PPI_CONTROL) = 1. /* SETS PPI PORTC BIT 0 FOR SOUND CONTROL */
146 2 OUTPUT (PPI_CONTROL) = 1. /* EXTRA ONES FOR 6 MICRO-SEC TIMING */
147 2 OUTPUT (PPI_CONTROL) = 1.
148 2 OUTPUT (PPI_CONTROL) = 0. /* RESETS PPI PORTC BIT 0 */
149 2 END SOUND.

150 1 ON_BROUSE: PROCEDURE (SEMA4_PTR: BIT) PUBLIC.
151 2 DECLARE SEMA4_PTR POINTER: BIT BYTE. BUSLOCK LITERALLY 0AH.
152 2 /* N.B. 8255 (4-5) WHEN RESET (=0), ASSERTS THE BUS "OVERRIDE." */
153 2 /* REFER TO PAGE 3-16,-17 FOR PPI PORTC BIT SET/RESET */
154 2 DECLARE TEMP BYTE. SEMA4 BASED SEMA4_PTR BYTE.
155 2 TEMP = 1.
156 2 IF BIT = 1 THEN SET_SEMA4
157 2 DO WHILE TEMP = 1
158 3 FIRST CHECK DO WHILE SEMA4 = 1. /* WAIT HERE TO AVOID REPEATEDLY LOCKING/UNLOCKING BUS */
159 4 END FIRST CHECK.
160 3 OUTPUT (PPI_CONTROL) = BUSLOCK. /* THIS REQUESTS A BUS-LOCK WHEN WE GET CONTROL */
161 3 TEMP = DUMMY. /* WHEN THIS EXECUTES, WE HAVE CONTROL OF A LOCKED BUS */
162 3 TEMP = SEMA4. /* SAVE CURRENT BIT OF THE SEMA4 */
163 3 SEMA4 = 1. /* SEMA4 IS NOW SET. WILL DETERMINE LATER IF WE DID IT */
164 3 OUTPUT (PPI_CONTROL) = BUS_FREE. /* IF SEMA4 WERE OFF-BOARD, COULD REPLACE THESE */
165 3 /* LAST FIVE STEPS WITH "LOCK SET (SEMA4_PTR, 1) */

```

/* IF SEMA4 WAS SET ANOTHER MASTER DID IT. SO MUST WAIT TILL USER RESETS IT */

```

167 3      END SET_SEMA4.

169 2      IF BIT = 0 THEN CLEAR_SEMA4: DO:
168 1          OUTPUT(PPI_CONTROL) = BUS_LOCK;
167 1          TEMP = DUMMY;
166 1          SEMA4 = 0; /* ASSUMES PROGRAM NEVER CLEARS SEMA4 UNLESS SAME PROG SET IT */
169 1          OUTPUT(PPI_CONTROL) = BUS_FREE;
170 1          END CLEAR_SEMA4.

171 2      RETURN.

172 2      END ON_BRO_SET.

173 1      PPI_SET PROCEDURE PUBLIC:
174 2      DO:
175 3          DECLARE PPI_MODE LITERALLY '32H'; /* PORTS A & C OUTPUT B INPUT */
176 3          /* REF PAGES 2-10 & 3-15 */
177 3          DECLARE SFLAG LITERALLY '0'; /* RESETS PORT "C" BIT 0 */
178 3          /* WHICH OUTPUTS A "1" FROM 7400. SETTING THE "SOUND-FLAG" TO 8748 */
179 3          OUTPUT(PPI_CONTROL) = PPI_MODE; /* ALL PPI OUTPUTS GO LOW INCLUDING
180 3          PORT-C. BIT-5. WHICH ASSERTS THE MULTI-BUS "OVERRIDE " */
181 3          OUTPUT(PPI_CONTROL) = BUS_FREE; /* NEGATES THE MULTI-BUS OVERRIDE */
182 3          OUTPUT(PPI_CONTROL) = SFLAG;
183 3          END;
184 2      END PPI_SET;

185 1      TIME_DELAY PROCEDURE (HOW_LONG) PUBLIC:
186 2      DECLARE (HOW_LONG, TEST_WORD) WORD;
187 2      LOOPA DO WHILE HOW_LONG <> 0:
188 3          TEST_WORD = 39H;
189 3          LOOPB DO WHILE TEST_WORD <> 0:
190 4              TEST_WORD = TEST_WORD - 1;
191 4              END LOOPB;
192 3          HOW_LONG = HOW_LONG - 1;
193 3          END LOOPA;
194 2      END TIME_DELAY.

195 1      END DRAGON.UTILITY.

```

MODULE INFORMATION

```

CODE AREA SIZE      = 0475H 11410
CONSTANT AREA SIZE = 0000H   00
VARIABLE AREA SIZE = 000EH  140
MAXIMUM STACK SIZE = 001AH  260
264 LINES PERD
A PROGRAM ERRORS:

```

END OF PL/M-86 COMPILEATION

ISIS-II MCS-86 MACRO ASSEMBLER V2.1 ASSEMBLY OF MODULE PD/RSB
 OBJECT MODULE PLACED IN FILE PD/RSB.OBJ
 ASSEMBLER INVOKED BY: ASMBR F1 (DEBUG SRC DEBUG DATE 02/24/89)

```

LOC:OBJ      LINE      SOURCE
1          THIS PROGRAM, STARTED SEPT 5, 1979, READS DATA FROM THE RETICON RSB6820
2          INTERFACE BOARD INTO THE 86/12 MEMORY. REFERENCES ARE:
3              1. RSB6820 OPERATING INSTRUCTIONS, MARCH 9, 1979, EG&G RETICON
4              SUNNYVALE, CALIFORNIA
5              2. MCS-86 ASSEMBLY LANGUAGE REFERENCE MANUAL, #9800640A,
6              INTEL CORP., SANTA CLARA, CALIFORNIA
7
8          .IT IS BEING CLEANED UP A BIT FEB 20, 1981
9
10         EQUATES AT TOP OF PROGRAM PER P. 8-1, REF 2
11
12         NAME      PD/RSB
13         DGROUP    GROUP    DATA, STACK, SBC_REGS, RSB_REGS
14         CGROUP    GROUP    CODE
15
16         INMSK     EQU      01      .SET UP FOR CAMERA 1 ONLY. SEE P. 19, REF 1
17         LINES     EQU      100
18         ENDFR     EQU      10H     .MASK FOR THE 2-TO-THE-4TH BIT. P. 45, REF 1
19
20         ASSUME SS DGROUP, CS CGROUP, DS DGROUP, ES DGROUP
21
22         SBC_REGS SEGMENT COMMON      .NOTE THAT "COMMON" FILES MUST BE
23                                     .COMMON IN ALL MODULES, I.E. CAN'T BE
24         SBCREG DB      800 DUP (?)   . "AT" IN ONE AND "COMMON" IN ANOTHER
25
26                                     .THEY DO NOT, HOWEVER, HAVE TO BE POINTED
27                                     .TO BY THE SAME SEGMENT REGISTER IN BOTH
28                                     .MODULES. NOR DO THEY HAVE TO
29         PARTLY_OFF DB      6 DUP (?)   . OF THE SAME LENGTH
30                                     . INITIALIZE = 0
31
32         LOCATIONS DB      6 DUP (?)   . INITIALIZE = 1
33
34         SBC_REGS ENDS
35
36         RSB_REGS SEGMENT AT 0000H     .BASE ADDRESS OF RETICON BOARD IS 0000H
37         RSBOTA DB      200H DUP (?)
38
39         STAT1 DB      1 DUP (?)      .THIS FORM IS NECESSARY TO AVOID LOADING ERRORS
40
41         STAT2 DB      0BH DUP (?)
42
43         RESET DB      2 DUP (?)

```

```

LOC OBJ          LINE    SOURCE

020E (1          38      CNFG15 DB      1 DUP (?)
??
)
020F (1          39      PROCOM DB      1 DUP (?)
??
)
----
40      RSB_REGS ENDS
41
----
42      STACK SEGMENT STACK 'STACK'
0000 (10        43      DW      10 DUP (?)
??
)
0014          44      STKTOP LABEL WORD
----
45      STACK ENDS
46
47
----
48      CODE SEGMENT PUBLIC 'CODE'
49
50      PUBLIC INIT1
0000          51      INIT1 PROC NEAR ; INITIALIZATION OF RSB 6020 INTERFACE BOARD
0000 A20C02      R 52      RTINIT MOV RESET,AL ; RESET IS A "DUMMY" REGISTER, ALL IT NEEDS
0003 C6060E0201 R 53      MOV CNFG15,INMSK ; IS THE "MUTC/" PULSE FROM P1 #20
0008 A20F02      R 54      MOV PROCOM,AL ; PROCOM IS ALSO A "DUMMY" REGISTER
0008 03          55      RET
56      INIT1 ENDP
57
58      PUBLIC PD_LAST
000C          59      PD_LAST PROC NEAR
000C A20F02      F 60      LAST MOV PROCOM,AL ; WILL WAIT FOR LAST RASTER LINE
000F A00002      R 61      WTLP0 MOV AL,STAT1 ; FROM HERE TO CHECK IS ST'D NUCMCY
0012 D0E0        62      SHL AL,1
0014 7303        63      JNB WTLP3
0016 A20F02      R 64      PSPR0 MOV PROCOM,AL
0019 A00002      R 65      WTLP3 MOV AL,STAT1
001C D0E0        66      SHL AL,1
001E 7206        67      JB CHECK
0020 D0E0        68      SHL AL,1
0022 72F5        69      JE WTLP2
0024 EBF0        70      JNP PSPR0
0026 A00300      R 71      CHECK MOV AL,RSBOTAC3]
0029 2410        72      AND AL,ENDFR
002B 740F        73      JZ LAST
74
75      ; HAVING FOUND THE LAST LINE OF THE FRAME, WE WILL TRANSFER THE RETICON
76      ; DATA LINE-BY-LINE THE THE INTEL 86/12 BOARD. EACH LINE TRANSFERRED STARTS
77      ; WITH A "NEW COMMAND CYCLE" AS PER PAGE 40 OF REFERENCE 1
78
002D B164        79      MOV BL,LINES ; WILL DECREMENT FROM 100 TO ZERO
002F BF0000      R 80      MOV DI,OFFSET DGROUP:SBORIG
81
0032 A20F02      R 82      NUCMCY MOV PROCOM,AL ; AGAIN, PROCOM IS A DUMMY
0035 A00002      P 83      WTLP1 MOV AL,STAT1
0038 D0E0        84      SHL AL,1
003A 7303        85      JNB WTLP

```

LOC	OBJ		LINE	SOURCE
003C	620F02	R	86	PSPR: MOV PROCOM,AL
003F	A00002	R	87	WTLP: MOV AL,STAT1
0042	D0E0		88	SHL AL,1
0044	7206		89	JB OTLP
0046	D0E0		90	SHL AL,1
0048	72F5		91	JB WTLP
004A	EBF0		92	JMP PSPR
			93	
			94	; NOW TRANSFER A SINGLE LINE OF RETICON RSB 6020 DATA TO THE INTEL 86 BOARD.
			95	
004C	A00000	R	96	OTLP: MOV AL,RSB0TA ; TRANSITIONS IN THE LINE
004F	32E4		97	XOR AH,AH
0051	40		98	INC AX ; NUMBER OF WORDS TO XFER
0052	D1E0		99	SHL AX,1 ; X2 NUMBER OF BYTES TO XFER
0054	8BC8		100	MOV CX,AX
0056	EE0000	R	101	MOV SI,OFFSET DGROUP:RSB0TA
0059	F3		102	REP MOVSB BYTE PTR SBCREG [DI], BYTE PTR RSB0TA [SI]
005A	A4			
005B	FE00		103	DEC BL
005D	75D3		104	JNZ NUCMVC
			105	
005F	C3		106	RET
			107	
			108	RD_LAST ENDP
			109	
			110	CODE ENDS
			111	
			112	END

ASSEMBLY COMPLETE, NO ERRORS FOUND

APPENDIX C

COMPUTER GRAPHICS AND VIDEO SUBSYSTEM PROGRAMS

SERIES-III 8086/8087/8088 MACRO ASSEMBLER V1.0 ASSEMBLY OF MODULE MATROX
 OBJECT MODULE PLACED IN :F2:MATROX.OBJ
 INVOCATION LINE CONTROLS: DEBUG

```

LJC OBJ      LINE  SOURCE
              1  NAME MATROX
              2
              3  CGROUP GROUP CODE
              4
              5  DATA_GROUP GROUP DGROUP, DATA_SEG, GAE_SEG
              6  ASSUME CS, CGROUP, DS: DATA_GROUP
              7  PUBLIC BACKGROUND, MATROX_START_UP, START_BIT, X_Y, DATA_READY, ERROR
              8  PUBLIC XCNT, YCNT, BAD_MISS, FIRE_BIRD, THRUSTER_FIRE
              9  EXTRN SMOKE_SET: NEAR, GAE_GT_FOV: NEAR, GRAPH_VREP: NEAR
             10  EXTRN GRAPH_GAE_POINT: NEAR, GRAPH_HREP: NEAR
             11  EXTRN SMOKE_CHECK NEAR
             12  EXTRN GRAPH1 NEAR
             13  EXTRN SMOKE_START_UP: NEAR
             14  EXTRN GAE_START_UP: NEAR
             15  EXTRN COUT: NEAR
             16  EXTRN CIN: NEAR
             17  EXTRN HIT_EXPLOSION: NEAR, GROUND_EXPLOSION: NEAR
             18  EXTRN TANK_INIT: NEAR, TANK_KILLED: NEAR
             19  EXTRN USART_SET_UP_FOR_ADM: NEAR
             20  EXTRN DELAY_3: NEAR ; 160MS DELAY FOR CLEARING RETRO_GRAPHICS SCREEN
             21
             22  DGROUP SEGMENT PUBLIC 'DATA'
             23  DGROUP ENDS
             24
             25  DATA_SEG SEGMENT PUBLIC
             26  EXTRN H_REP_FLAG: BYTE, V_REP_FLAG: BYTE
             27  DATA_SEG ENDS
             28
             29  GAE_SEG SEGMENT PUBLIC
             30  EXTRN ELAPSED_TIME: WORD
             31  GAE_SEG ENDS
             32
             33
             34  XREG EQU 14H
             35  YREG EQU 16H
             36  GSCALE EQU 10H
             37  SCROLL EQU 12H
             38  FLAGS EQU 12H
             39  ERASE EQU 14H
             40
             41  DATA_SEG SEGMENT PUBLIC
             42
             43  XCNT DB 1 DUP(?)
             44  YCNT DB 1 DUP(?)
             45  XCNT_OLD DB 1 DUP(?)
  
```

0014
 0016
 0018
 0012
 0012
 0014

0000 (1
 ??
)
 0001 (1
 ??
)
 0002 (1
 ??

LOC	OBJ	LINE	SOURCE
0003	(1 ??)	46	YCNT_OLD DB 1 DUP(?)
0004	(1 ??)	47	XCNT_SAVE DB 1 DUP(?)
0005	(1 ??)	48	YCNT_SAVE DB 1 DUP(?)
0006	(1 ??)	49	GSCALE_VAL DB 1 DUP(?)
0007	(1 ??)	50	GSCALE_NUM DB 1 DUP(?)
0008	(1 ??)	51	THRUSTER_FIRE DB 1 DUP(?)
0009	(1 ????)	52	SIZ DW 1 DUP(?)
0008	(1 ????)	53	XMIN DW 1 DUP(?)
0008	(1 ????)	54	YMIN DW 1 DUP(?)
0008	(1 ????)	55	XMAX DW 1 DUP(?)
0011	(1 ????)	56	YMAX DW 1 DUP(?)
0013	(1 ????)	57	XMAX_TMP DW 1 DUP(?)
0015	(1 ????)	58	XMIN_TMP DW 1 DUP(?)
0017	(1 ????)	59	TMP_WRD DW 1 DUP(?)
0019	(1 ????)	60	ONE_THIRD DW 1 DUP(?)
0018	(1 ????)	61	TWO_THIRDS DW 1 DUP(?)
0010	(1 ??)	62	THREE DB 1 DUP(?)
001E	(1 ??)	63	COUNT_EM DB 1 DUP(?)

LOC	OBJ	LINE	SOURCE	
001F	(1 ??)	64	BACKGROUND	DB 1 DUP(?)
0020	(1 ??)	65	OSCALE_SAVE	DB 1 DUP(?)
0021	(1 ??)	66	COUNT	DB 1 DUP(?)
0022	(1 ??)	67	BLINK_COUNT	DB 1 DUP(?)
0023	(1 ??)	68	REPLAY	DB 1 DUP(?)
0024	(1 ??)	69	ERROR	DB 1 DUP(?)
0025	(1 ??)	70	ERROR_MSG_FLAG	DB 1 DUP(?)
0026	(1 ??)	71	GRND_BIRD_FLAG	DB 1 DUP(?)
0027	(1 ??)	72	HIT_FLAG	DB 1 DUP(?)
0028	(1 ??)	73	DIST_FRO_TGT_FLAG	DB 1 DUP(?)
0029	(1 ??)	74	RESULTS_FLAG	DB 1 DUP(?)
002A	(1 ??)	75	THRUSTERS_FLAG	DB 1 DUP(?)
002B	(1 ????)	76	TWO	DW 1 DUP(?)
002C	(1 ????)	77	YANG_SCALED	DW 1 DUP(?)
002F	(1 ????)	78	ZANG_SCALED	DW 1 DUP(?)
0031	(1 ????)	79	YANG2_OLD	DW 1 DUP(?)
0033	(1 ????)	80	ZANG2_OLD	DW 1 DUP(?)
0035	(1 ????)	81	YANG2_SAVE	DW 1 DUP(?)
0037	(1 ????)	82	ZANG2_SAVE	DW 1 DUP(?)

LOC	OBJ	LINE	SOURCE
	0029	(1	83 YANG2 DW 1 DUP(?)
	0038	(1	84 ZANG2 DW 1 DUP(?)
	003D	(1	85 FLAG DB 1 DUP(?)
	003E	(1	86 POP_LEVEL DB 1 DUP(?)
	003F	(1	87 BORE_SIGHT DB 1 DUP(?)
	0040	(1	88 START_UP_BYTE DB 1 DUP(?)
			89
			90 DATA_SEG ENDS
			91
			92
			93 XFER_SEG SEGMENT AT 0600H
	0000	(1	94 START_BIT DB 1 DUP(?)
	0001	(1	95 X_Y DW 1 DUP(?)
	0001	(1	96 DATA_READY DB 1 DUP(?)
	0004	(1	97 BAD_MISS DB 1 DUP(?)
	0005	(1	98 OFFSET_X DB 1 DUP(?)
	0006	(1	99 OFFSET_Y DB 1 DUP(?)
	0007	(9	100 DUMMYS DB 9 DUP(?)
	0010	(1	101 YANG DW 1 DUP(?)
	0012	(1	102 ZANG DW 1 DUP(?)
	0014	(1	103 BIRD_DTA_RDY DB 1 DUP(?)

LOC	OBJ	LINE	SOURCE
0015	(1 ??)	104	FIRE_BIRD DB 1 DUP(?)
0016	(1 ??)	105	BIRD_HIT DB 1 DUP(?)
0017	(1 ??)	106	BIRD_MISSES DB 1 DUP(?)
0018	(1 ??)	107	H_REP_REQ DB 1 DUP(?)
0019	(1 ??)	108	H_REP_GO DB 1 DUP(?)
001A	(1 ??)	109	V_REP_REQ DB 1 DUP(?)
001B	(1 ??)	110	V_REP_GO DB 1 DUP(?)
001C	(1 ??)	111	GRND_BIRD DB 1 DUP(?)
001D	(1 ??)	112	END_OF_RPV DB 1 DUP(?)
001E	(1 ??)	113	HIT_SHORT DB 1 DUP(?)
001F	(1 ??)	114	DUMMY_ALSO DB 1 DUP(?)
0020	(16 ??)	115	H_MIS_ASCII DB 16 DUP(?)
0030	(16 ??)	116	V_MIS_ASCII DB 16 DUP(?)
0040	(16 ??)	117	DIS_FRO_TGT DB 16 DUP(?)
0050	(24 ??)	118	ACTUAL_THRUST DB 24 DUP(?)
0060	(24 ??)	119	IDEAL_THRUST DB 24 DUP(?)
----		120	XFER_SEG ENDS
----		121	
----		122	STACK_SEG SEGMENT STACK 'STACK'
0000	(64 ????)	123	DW 640 DUP(?)
0000		124	STKTOP LABEL WORD

LOC	OBJ	LINE	SOURCE
----		125	STACK_SEG ENDS
----		126	
----		127	CODE SEGMENT PUBLIC 'CODE'
		128	
0000	47524F554E4420 494D50414754	129	MESSAGE DB 'GROUND IMPACT', 350
0000	1D		
000E		130	FIN_OF_MESSAGE LABEL WORD
		131	
000E	4D49535E494D45 20504F53495449 4F4E2045584345 45444544204752 41504820424F55 4E4453	132	MESSAGE2 DB 'MISSILE POSITION EXCEEDED GRAPH BOUNDS', 350
0034	1D		
0037		133	FIN_OF_MESSAGE2 LABEL WORD
		134	
0035	54485255535445 52533A20	135	MESSAGE3 DB 'THRUSTERS: '
0040	02	136	END_OF_MESSAGE3 DB WORD
		137	
0041	800000	138	DRIVER MOV AX, XFER_SEG
0044	8EC0	139	MOV ES, AX
0046	80----	R 140	MOV AX, STACK_SEG
0049	8ED0	141	MOV SS, AX
004B	800000	R 142	MOV AX, OFFSET STKTOP
004E	8BE0	143	MOV SP, AX
0050	68----	R 144	MOV AX, DATA_GROUP
0057	8E06	145	MOV DS, AX
0055	26C606000000	146	MOV ES:START_BIT, 0
0058	803E400001	P 147	CMP START_UP_BYTE, 1
0050	740C	148	JE NOT_START_UP
0062	26C606050000	149	MOV ES:OFFSET_X, 0
0068	26C606060000	150	MOV ES:OFFSET_Y, 0
006E	C606400001	R 151	NOT_START_UP: MOV START_UP_BYTE, 1
0073	C606230000	R 152	MOV REPLAY, 0
0078	C70620000200	R 153	MOV TWO, 2
007E	C606200000	R 154	MOV DIST_FRO_TGT_FLAG, 0
0083	C606260000	R 155	MOV GRND_BIRD_FLAG, 0
0088	C606270000	R 156	MOV HIT_FLAG, 0
009D	C606290000	R 157	MOV RESULTS_FLAG, 0
00A2	C6063F0000	R 158	MOV BORE_SIGHT, 0
00A7	C606240000	R 159	MOV ERROR, 0
009C	C606250000	R 160	MOV ERROR_MESG_FLAG, 0
00A1	CF06260000	R 161	MOV GRND_BIRD_FLAG, 0
00A6	C606270000	R 162	MOV HIT_FLAG, 0
00AB	C6062F0000	R 163	MOV DIST_FRO_TGT_FLAG, 0
00B0	E80000	E 164	CALL USART_SET_UP_FOR_ADM
00B3	E80000	E 165	CALL USART_SET_UP_FOR_ADM
00B6	E80000	E 166	CALL SMOKE_START_UP
00B9	E80000	E 167	CALL GAE_START_UP ; INITIALIZES THE GAE PROGRAM
00BC	E8C901	168	CALL MATROX_START_UP ; CLEARS MATROX SCREEN
00BF	BAD690	169	MOV DX, 008H
00C2	B01D	170	MOV AL, 350

LOC	OBJ	LINE	SOURCE
0004	E80000	E 171	CALL COUT
0007	B018	172	MOV AL,310
0009	E80000	E 173	CALL COUT
000C	E80000	E 174	CALL DELAY_3 ; DELAY 160MS
000F	B000	175	MOV AL,150
0001	E80000	E 176	CALL COUT
0004	B018	177	MOV AL,0300
0006	E80000	E 178	CALL COUT
0009	B018	179	MOV AL,320 ; CLEAR ADM-3 SCREEN
000B	E80000	E 180	CALL COUT
000E	E80000	E 181	CALL TANK_INIT ; ALLOWS INST. TO SELECT FROM MENU
00E1	B80006	182	MOV AX,XFER_SEG ; THIS & THE NEXT INST. ARE A CLUGE
		183	; TO GUARD THE ES IF NECESSARY???
00E4	8ED0	184	MOV ES,AX
00E6	B018	185	MOV AL,320
00E8	BAD000	186	MOV DX,000H
00EB	E80000	E 187	CALL COUT ; CLEAR ADM-3 SCREEN
00EE	E80000	E 188	CALL GRAPH1 ; DRAWS AND CLEARS ENVELOPES ON ADM-3 SCREEN
00F1	26C060000001	189	MOV ES:START_BIT,1
00F7	E80007	190	CALL CHECK_FOR_B ; BORESIGHT CHECK
00FA	80FC01	191	CMP AH,1
00FD	7511	192	JNE DO_IT_OVER
00FF	3002	193	CMP AL,0002H ; CTRL-B ??
0101	750C	194	JNE DO_IT_OVER
0103	BAD000	195	MOV DX,000H
0106	B042	196	MOV AL,1020 ; OUTPUT A 'B' TO ADM-3
0108	E80000	E 197	CALL COUT
010B	C6063F0001	R 198	MOV BORE_SIGHT,1
0110	26003E030001	199	DO_IT_OVER: CMP ES:DATA_READY,1 ; DATA_READY???
0116	7520	200	JNE CHK_FOR_RPV
0118	803E3F0001	R 201	CMP BORE_SIGHT,1
011D	7508	202	JNE BEYOND
011F	E84507	203	CALL CALIBRATE ; CALIBRATE FROM FIRST DATA POINTS
0122	C6063F0000	R 204	MOV BORE_SIGHT,0
0127	26003E040001	205	BEYOND: CMP ES:BAD_MISS,1 ; BAD_MISS???
012D	7506	206	JNE DO_IT
012F	E80000	E 207	CALL GAE_GT_FOV
0132	E94601	208	JMP OVER2 ; DO NOT GET NEW DATA IF BAD_MISS
0135	E9FF00	209	DO_IT: JMP DO_IT_LONG
		210	
0138	26003E1A0001	211	CHK_FOR_RPV: CMP ES:V_REP_REQ,1
013E	7423	212	JE V_REP_SHORT
0140	26003E180001	213	CMP ES:H_REP_REQ,1
0146	741E	214	JE H_REP_SHORT
0148	26003E1E0001	215	CMP ES:HIT_SHORT,1
014E	7436	216	JE DIST_FROM_TGT
0150	26003E1D0001	217	CMP ES:END_OF_RPV,1
0156	744C	218	JE ERROR_MSG_CHK
0158	26003E170001	219	CMP ES:BIRD_MISSES,1
015E	741C	220	JE TEST1
0160	E80790	221	JMP BACK
0161	E9AF00	222	V_REP_SHORT: JMP V_REP
0166	E98A00	223	H_REP_SHORT: JMP H_REP
		224	
0169	26003E160001	225	BACK: CMP ES:BIRD_HIT,1

LOC	OBJ	LINE	SOURCE
016F 7427		226	JE PRNT_HIT
0171 3A80E100001		227	CMP ES_GRND_BIRD,1
0177 747		228	JE PRNT_GRND_BRO
0179 E376FF		229	JMP WAY_UP_HERE
		230	
0177 2A80E100001		231	TEST1: CMP ES_GRND_BIRD,1 ;WAIT FOR END OF FLIGHT BEFORE
0182 7406		232	JE PRINT_RESULT ;PRINTING MESSAGES
0184 EB03		233	JMP BACK
		234	
0186 E8FE00		235	DIST_FROM_TGT: CALL MATROX_START_UP
0189 E80000	E	236	CALL GROUND_EXPLOSION
018C E9B704		237	JMP DIST_FRO_TGT
018F E9F500		238	PRINT_RESULT: CALL MATROX_START_UP
0192 E80000	E	239	CALL GROUND_EXPLOSION
0195 E96804		240	JMP PRINT_RESULTS
0198 E8EC00		241	PRNT_HIT: CALL MATROX_START_UP
019B E80000	E	242	CALL HIT_EXPLOSION
019E E80000	E	243	CALL TANK_KILLED
01A1 E95405		244	JMP PRINT_HIT
		245	
01A4 003E280001	R	246	ERRPOP_MESG_CHK: CMP DIST_FRO_TGT_FLAG,1
01A9 7506		247	JNE SKIP
01AB 26C6061E0001		248	MOV ES_HIT_SHORT,1
01B1 003E260001	R	249	SKIP: CMP GRND_BIRD_FLAG,1
01B6 7506		250	JNE SKIP2
01B8 26C6061C0001		251	MOV ES_GRND_BIRD,1
01BE 003E270001	R	252	SKIP2: CMP HIT_FLAG,1
01C7 7506		253	JNE SKIP3
01C7 2F1006160001		254	MOV ES_BIRD_HIT,1
01CB 003E290001	R	255	SKIP3: CMP RESULTS_FLAG,1
01D0 7506		256	JNE SKIP4
01D2 26C606170001		257	MOV ES_BIRD_MISSES,1
01D8 003E240001	R	258	SKIP4: CMP ERROR,1
01D0 7406		259	JE ERROR_MESG_LONG
01DF 26C6061D0000		260	MOV ES_END_OF_RPV,0
01E5 060600000000	E	261	MOV H_REP_FLAG,0
01E8 E927FF		262	JMP DO_IT_OVER
01ED E91006		263	ERROR_MESG_LONG: JMP ERROR_MESG
		264	
01F0 E9C905		265	PRNT_GRND_BRO: JMP PRINT_GRND_BIRD
		266	
01F0 0006250001	R	267	H_REP: MOV REPLAY,1
01F8 26C606180000		268	MOV ES_H_REP_REQ,0
01FE E80000	E	269	CALL GRAPH_HREP
0201 E80000	E	270	CALL GAE_START_UP
0204 E80000		271	CALL MATROX_START_UP
0207 0606000001	E	272	MOV H_REP_FLAG,1
020C 26C606190001		273	MOV ES_H_REP_GO,1
0212 E9FEFF		274	JMP DO_IT_OVER
		275	
0215 0606270001	R	276	V_REP: MOV REPLAY,1
021A 26C6061A0000		277	MOV ES_V_REP_REQ,0
0220 E80000	E	278	CALL GRAPH_VREP
0223 E80000	E	279	CALL GAE_START_UP
0226 E85E00		280	CALL MATROX_START_UP ;THIS MIGHT BE "MATROX_CANCELL"

LOC	OBJ	LINE	SOURCE
0229	00000001	E 281	MOV V_REP_FLAG, 1
022E	26C60E160001	282	MOV ES:V_REP_GO, 1
0234	E9D9FE	283	JMP DO_IT_OVER
		284	
0237	A00000	R 285	DO_IT_LONG MOV AL, XCNT
023A	A20200	R 286	MOV XCNT_OLD, AL
0240	A00100	R 287	MOV AL, YCNT
0243	A20300	R 288	MOV YCNT_OLD, AL
0246	A13400	R 289	MOV AX, YANG2
0248	A33100	R 290	MOV YANG2_OLD, AX
0249	A13E00	P 291	MOV AX, ZANG2
024C	A33300	R 292	MOV ZANG2_OLD, AX
024F	26C6160100	293	MOV DX, ES:X,Y ; THIS INST GETS XCNTR, YCNTR IN ONE GULP.
0254	58160000	R 294	MOV XCNT, DL
0258	A3360100	R 295	MOV YCNT, DH
025C	26A11000	296	MOV AX, ES:YANG
0260	A33900	R 297	MOV YANG2, AX
0263	26A11200	298	MOV AX, ES:ZANG
0267	A33E00	R 299	MOV ZANG2, AX
026A	26C60E070000	300	MOV ES:DATA_READY, 0
0270	26803E040001	301	CMP ES:BAD_MISS, 1
0276	7403	302	JE OVER2
0278	E80000	E 303	CALL GRAPH_GAE_POINT ; PLOTS DOTS ON ADM-3.
027E	E84000	304	CALL START ; PLOTS ROCKET AND SMOKE ON MATROX.
027E	26C60E040000	305	MOV ES:BAD_MISS, 0
0284	E989FE	306	JMP GO_IT_OVER
		307	
0287	060E070009	R 308	MATROX_START_UP: MOV GSCALE_NUM, 09D
028C	A00700	R 309	MOV AL, GSCALE_NUM
028F	A20600	R 310	MOV GSCALE_VAL, AL
0292	0706090000900	R 311	MOV SIZE, 09D
0298	06063E0000A	R 312	MOV POP_LEVEL, 10D
029D	0606100003	R 313	MOV THREE, 3D
02A2	06063D00006	R 314	MOV FLAG, 0
02A7	06061F0000	R 315	MOV BACKGROUND, 0
02AC	0606210000	R 316	MOV COUNT, 0
02B1	06061E0000	R 317	MOV COUNT_EM, 0
02B6	8000	318	MOV AL, 0
02B8	E612	319	OUT SCROLL, AL
02BA	A01F00	R 320	MOV AL, BACKGROUND
02BD	E610	321	OUT GSCALE, AL
02BF	E414	322	IN AL, ERASE
02C1	E412	323	WAIT1 IN AL, FLAGS
02C3	2401	324	AND AL, 1
02C5	74FA	325	JZ WAIT1
02C7	03	326	RET
		327	
02C8	E95401	328	STILL_SMOKE_SHORT JMP STILL_SMOKE
02CB	503E250001	R 329	START CMP REPLAY, 1
02D0	7406	330	JE FIN_OF_MAT
02D2	813E0000F000	E 331	CMP ELAPSED_TIME, 2400
02D8	7603	332	JNA FIN_OF_MAT
02DA	EB0490	333	JMP TO
02D0	E9C601	334	FIN_OF_MAT JMP FIN_OF_MATROX
02FA	A00700	R 335	TO MOV AL, GSCALE_NUM

F/G 19/5

NOV 81 A MARSHALL, B SHAW, H TOWLE

PM TRADE-RE-U01U

NL .

2. 2

21

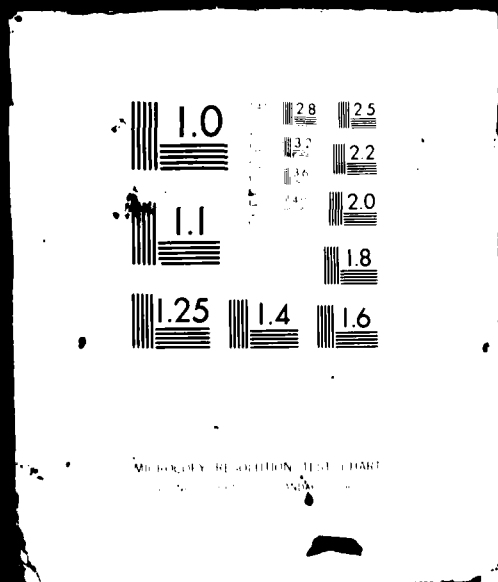
END
DATE
FILMED
28
DTIC

12 8

2 OF 2

AD-

A107481



LOC	OBJ	LINE	SOURCE
02E3	A20600	R 336	MOV GSCALE_VAL, AL
02E6	E80F00	E 337	CALL SMOKE_CHECK
02E9	80FC01	338	CMP AH, 1
02EC	75DA	339	JNE STILL_SMOKE_SHORT
02EE	A13900	R 340	MOV AX, YANG2
02F1	A33500	R 341	MOV YANG2_SAVE, AX
02F4	A13B00	R 342	MOV AX, ZANG2
02F7	A33700	R 343	MOV ZANG2_SAVE, AX
02FA	A00600	R 344	MOV AL, GSCALE_VAL
02FD	A22000	R 345	MOV GSCALE_SAVE, AL
0300	C606060000	R 346	MOV GSCALE_VAL, 0
		347	
0305	A00000	P 348	MOV AL, XCNT
0308	A20400	R 349	MOV XCNT_SAVE, AL
030B	A00200	R 350	MOV AL, XCNT_OLD
030E	A20000	R 351	MOV XCNT, AL
		352	
0311	A00100	R 353	MOV AL, YCNT
0314	A20500	R 354	MOV YCNT_SAVE, AL
0317	A00300	R 355	MOV AL, YCNT_OLD
031A	A20100	R 356	MOV YCNT, AL
		357	
031D	A13B00	R 358	MOV AX, ZANG2
0320	A33700	R 359	MOV ZANG2_SAVE, AX
0323	A13300	R 360	MOV AX, ZANG2_OLD
0326	A33B00	R 361	MOV ZANG2, AX
		362	
0329	A13900	R 363	MOV AX, YANG2
032C	A33500	R 364	MOV YANG2_SAVE, AX
032F	A13100	R 365	MOV AX, YANG2_OLD
0332	A33900	R 366	MOV YANG2, AX
		367	
0335	E86F01	368	CALL OCT_DRAW
0338	A02000	R 369	MOV AL, GSCALE_SAVE
033B	A20600	R 370	MOV GSCALE_VAL, AL
		371	
033E	A00400	R 372	MOV AL, XCNT_SAVE ; THESE NEXT 4 INST. RESTORE XCNT, YCNT
0341	A20000	R 373	MOV XCNT, AL ; AFTER AN ERASE CYCLE.
0344	A00500	R 374	MOV AL, YCNT_SAVE
0347	A20100	R 375	MOV YCNT, AL
		376	
034A	A13500	R 377	MOV AX, YANG2_SAVE ; THESE NEXT 4 INST RESTORE YANG2, ZANG2
034D	A33900	P 378	MOV YANG2, AX ; AFTER AN ERASE CYCLE.
0350	A13700	R 379	MOV AX, ZANG2_SAVE
0353	A33B00	R 380	MOV ZANG2, AX
0356	E80300	381	CALL S_P_AND_GSCALE_SET
0359	E90E00	382	JMP SIZ_IS_SET2
		383	*****
035C	A10000	E 384	S_P_AND_GSCALE_SET: MOV AX, ELAPSED_TIME
035F	3DF001	385	CMP , 506D ; WAS 500
0362	7513	386	JNE WAIT0 ; START THE SIZ, POP, AND GSCALE SETTING ROUTINE
0364	C70607000000	R 387	MOV SIZ, 80
036A	C606070000	R 388	MOV GSCALE_NUM, 80
036F	C6063E0000	R 389	MOV POP_LEVEL, 080
0374	E9A200	390	JMP SIZ_IS_SET

LOC	OBT	LINE	SOURCE
J377	3DF403	391	WAIT0: CMP ,10120 ; WAS 1000
037A	7513	392	JNE WAIT2
037C	C70609000700	393	MOV SIZ,70
J382	C606070007	394	MOV GSCALE_NUM,70
0387	C6063E0007	395	MOV POP_LEVEL,7
038C	E99A00	396	JMP SIZ_IS_SET
038F	3DEE05	397	WAIT2: CMP ,15180 ; WAS 1500
0392	7513	398	JNE WAIT3
0394	C70609000600	399	MOV SIZ,60
039A	C606070006	400	MOV GSCALE_NUM,60
039F	C6063E0006	401	MOV POP_LEVEL,6
03A4	EB7390	402	JMP SIZ_IS_SET
03A7	3D0207	403	WAIT3: CMP ,20020 ; WAS 2000
03AA	7513	404	JNE WAIT4
03AC	C70609000500	405	MOV SIZ,50
03B2	C606070005	406	MOV GSCALE_NUM,50
03B7	C6063E0005	407	MOV POP_LEVEL,6
03BC	EB5890	408	JMP SIZ_IS_SET
03BF	3D0C00	409	WAIT4: CMP ,30140 ; WAS 3000
03C2	7513	410	JNE WAIT7
03C4	C70609000400	411	MOV SIZ,40
03CA	C606070003	412	MOV GSCALE_NUM,30
03CF	C6063E0003	413	MOV POP_LEVEL,6
03D4	EB4390	414	JMP SIZ_IS_SET
03D7	3D9813	415	WAIT7: CMP ,50160
03DA	7513	416	JNE WAIT5
03DC	C70609000400	417	MOV SIZ,4
03E2	C606070002	418	MOV GSCALE_NUM,2
03E7	C6063E0004	419	MOV POP_LEVEL,4
03EC	EB2B90	420	JMP SIZ_IS_SET
03EF	3D6A1B	421	WAIT5: CMP ,70180
03F2	7510	422	JNE WAIT50
03F4	C70609000400	423	MOV SIZ,40
03FA	C606070001	424	MOV GSCALE_NUM,1
03FF	C6063E0004	425	MOV POP_LEVEL,4
0404	3D3C23	426	WAIT50: CMP ,90200
0407	7510	427	JNE SIZ_IS_SET
0409	C70609000400	428	MOV SIZ,40
040F	C606070001	429	MOV GSCALE_NUM,1
0414	C6063E0002	430	MOV POP_LEVEL,2 ; THIS ENDS THE SIZ SETTING ROUTINE.
0419	C3	431	SIZ_IS_SET: RET
		432	*****
041A	C606210000	433	SIZ_IS_SET2: MOV COUNT,0
		434	
041F	E412	435	STILL_SMOKE: IN AL,FLAGS ; CHECK TO SEE IF MATROX IS STILL BUSY
0421	3C01	436	CMP AL,1 ; 1=NOT BUSY, 0=BUSY
0423	740C	437	JE GO_ON2 ; JMP IF MATROX IS NOT BUSY
0425	26A00300	438	MOV AL,ES:DATA_READY ; MATROX IS BUSY=>CHECK FOR DATA READY
0429	3C01	439	CMP AL,1
042B	75F2	440	JNE STILL_SMOKE
042D	C3	441	RET ; IF DATA IS READY WE BAIL OUT AND RET
042E	EB1B90	442	DRAW_OCT_SHORT: JMP DRAW_OCT
0431	803E210000	443	GO_ON2: CMP COUNT,0
0436	74F6	444	JE DRAW_OCT_SHORT ; DRAW NEW OCTAGON
0438	EB21FF	445	CALL S_P_AND_GSCALE_SET ; SETS SIZ,POP DURING SMOKE GEN

LOC	OBJ	LINE	SOURCE
0438	E80000	E 446	SIZ_IS_SET3: CALL SMOKE_SET
043E	A01F00	R 447	MOV AL, BACKGROUND
0441	E610	448	OUT GSCALE, AL
0443	E414	449	IN AL, ERASE ; ERASE SCREEN
0445	C606210000	R 450	MOV COUNT, 0
044A	C3	451	RET
		452	
0448	803E210000	R 453	DRAW_OCT: CMP COUNT, 0 ; ARE WE DRAWING OR ERASING? COUNT=0=DRAW
0450	752F	454	JNE BY_PAS
0452	803E060001	R 455	CMP THRUSTER_FIRE, 1 ; AND IS THERE A THRUSTER FIRE??
0457	7508	456	JNE CHK_COUNT_EM
0459	C6061E0003	R 457	MOV COUNT_EM, 3
045E	E80890	458	JMP DO_IT_HERE
0461	803E1E0000	R 459	CHK_COUNT_EM: CMP COUNT_EM, 0
0466	7419	460	JE BY_PAS
0468	C606080000	R 461	DO_IT_HERE: MOV THRUSTER_FIRE, 0 ; ZERO THIS FLAG. AS WE HAVE SEEN IT.
046D	FE0E1E00	R 462	DEC COUNT_EM
0471	A00600	R 463	MOV AL, GSCALE_VAL
0474	02063E00	R 464	ADD AL, POP_LEVEL ; IF THERE IS THEN INC GSCALE_VAL BY P.L
0478	3C0F	465	CMP AL, 150 ; HOWEVER, GSCALE_VAL CANNOT BE GREATER THAN 150
047A	7602	466	JBE OK
047C	B00F	467	MOV AL, 150 ; IF GREATER THAN 15 THEN LOWER TO 15
047E	A20600	R 468	OK: MOV GSCALE_VAL, AL
0481	A00600	R 469	BY_PAS: MOV AL, GSCALE_VAL
0484	30061F00	R 470	CMP BACKGROUND, AL
0488	7206	471	JB THERE
048A	C606210001	R 472	MOV COUNT, 1
048F	C3	473	RET ; NO NEED TO DRAW OCTAGON IF SMOKE WILL HIDE IT
		474	
0490	26A01400	475	THERE: MOV AL, ES: BIRD_DTA_RDY
0494	3C01	476	CMP AL, 1
0496	75F8	477	JNE THERE
0498	26C606140000	478	MOV ES: BIRD_DTA_RDY, 0
049E	E80600	479	CALL OCT_DRAW
04A1	C606210001	R 480	MOV COUNT, 1
04A6	C3	481	FIN_OF_MATROX: RET
		482	
		483	
04A7	833E390000	R 484	OCT_DRAW: CMP YANG2, 0
04AC	7509	485	JNE NEXT
04AE	C7062D0000000	R 486	MOV YANG_SCALED, 0
04B4	EB0C90	487	JMP NEXT1
04B7	A13900	R 488	NEXT: MOV AX, YANG2
04BA	99	489	CMD
04BB	F73E2B00	R 490	IDIV TWO
04BF	A32D00	R 491	MOV YANG_SCALED, AX
04C2	833E3B0000	R 492	NEXT1: CMP ZANG2, 0
04C7	7509	493	JNE NEXT2
04C9	C7062F0000000	R 494	MOV ZANG_SCALED, 0
04CF	EB0C90	495	JMP NEXT3
04D2	A13B00	R 496	NEXT2: MOV AX, ZANG2
04D5	99	497	CMD
04D6	F73E2B00	R 498	IDIV TWO
04DA	A32F00	R 499	MOV ZANG_SCALED, AX
04DD	A10900	R 500	NEXT3: MOV AX, SIZ ; THIS STARTS THE OCTAGON DRAW ROUTINE!!!

LOC	OBJ	LINE	SOURCE
04E0	D1E8	501	SHR AX,1
04E2	BA7F00	502	MOV DX,1270 ; THIS WAS XCNT
04E5	03162000	503	ADD DX,YANG_SCALED
04E9	B97F00	504	MOV CX,1270 ; THIS WAS YCNT
04EC	030E2F00	505	ADD CX,ZANG_SCALED
04F0	2BD0	506	SUB DX,AX
04F2	2BC8	507	SUB CX,AX
04F4	89160B00	508	MOV XMIN,DX
04F8	890E0D00	509	MOV YMIN,CX
04FC	A10900	510	MOV AX,SIZ
04FF	03C2	511	ADD AX,DX
0501	A30F00	512	MOV XMAX,AX
0504	A10900	513	MOV AX,SIZ
0507	03C1	514	ADD AX,CX
0509	A31100	515	MOV YMAX,AX
050C	A10900	516	MOV AX,SIZ
050F	F6361D00	517	DIV THREE
0513	80F001	518	CMP AH,1
0516	7602	519	JBE GO_ON
0518	FEC0	520	INC AL
051A	8A08	521	MOV BL,AL
051C	32E4	522	XOR AH,AH
051E	03060D00	523	ADD AX,YMIN
0522	A31900	524	MOV ONE_THIRD,AX
0525	8AC3	525	MOV AL,BL
0527	D0E0	526	SHL AL,1
0529	32E4	527	XOR AH,AH
052B	03060D00	528	ADD AX,YMIN
052F	A31800	529	MOV TWO_THIRDS,AX
0532	A11900	530	MOV AX,ONE_THIRD
0535	2BC1	531	SUB AX,CX
0537	A31700	532	MOV TMP_WRD,AX
053A	03060D00	533	ADD AX,XMIN
053E	A31500	534	MOV XMIN_TMP,AX ; SETS XMIN
0541	A10F00	535	MOV AX,XMAX
0544	2B061700	536	SUB AX,TMP_WRD
0548	A31200	537	MOV XMAX_TMP,AX ; SETS XMAX
054B	003E3D0001	538	CMP FLAG,1
0550	7400	539	JE OVER_THIS
0552	033E090005	540	CMP SIZ,5
0557	7506	541	JNE OVER_THIS
0559	41	542	INC CX
055A	C6063D0001	543	MOV FLAG,1
055F	E86600	544	CALL LINE
0562	41	545	INC CX
0563	3B0E1900	546	CMP CX,ONE_THIRD
0567	7EC9	547	JLE FIRST_THIRD
0569	C6063D0000	548	MOV FLAG,0
056E	A10B00	549	MOV AX,XMIN
0571	A31500	550	MOV XMIN_TMP,AX
0574	A10F00	551	MOV AX,XMAX
0577	A31300	552	MOV XMAX_TMP,AX
057A	E84B00	553	CALL LINE
057D	41	554	INC CX
057E	3B0E1B00	555	CMP CX,TWO_THIRDS

LOC	OBJ	LINE	SOURCE
0582	7EF6	556	JLE OVER1
0584	A11B00	557	LAST_THIRD: MOV AX, TWO_THIRDS
0587	8B09	558	MOV BX, CX
0589	2B08	559	SUB BX, AX
058B	8B03	560	MOV AX, BX
058D	A31700	561	MOV TMP_HRD, AX
0590	03060B00	562	ADD AX, XMIN
0594	A31500	563	MOV XMIN_TMP, AX
0597	A10F00	564	MOV AX, XMAX
059A	2B061700	565	SUB AX, TMP_HRD
059E	A31300	566	MOV XMAX_TMP, AX
05A1	803E3D0001	567	CMP FLAG, 1
05A5	7410	568	JE OVER_THIS_2
05A8	833E090004	569	CMP SIZE, 4
05AD	7509	570	JNE OVER_THIS_2
05AF	FF0E1100	571	DEC YMAX
05B3	06063D0001	572	MOV FLAG, 1
05B8	E80100	573	OVER_THIS_2: CALL LINE
05BB	41	574	INC CX
05BC	3B0E1100	575	CMP CX, YMAX
05C0	7EC2	576	JLE LAST_THIRD
05C2	06063D0000	577	MOV FLAG, 0
05C7	03	578	RET
		579	
		580	
		581	THE ROUTINE DOT WILL NOT BE USED FOR A WHILE
		582	MOV AL, SIZE
		583	CMP AL, 3
		584	JE DOT
		585	SUB SIZE, 3D
		586	JMP START
		587	MOV DL, ES:X
		588	MOV CL, ES:Y
		589	MOV XMAX_TMP, DL
		590	CALL OVER
		591	MOV AL, BACKGROUND
		592	OUT GSCALE, AL
		593	IN AL, ERASE
		594	HLT
		595	
		596	
05C8	8B161500	597	LINE: MOV DX, XMIN_TMP
05CC	83F900	598	CMP CX, 00
05CF	7E20	599	JLE DUN
05D1	81F9FF00	600	CMP CX, 255D
05D5	7D1A	601	JGE DUN
05D7	8BFF00	602	MOV BX, 255D
05DA	2B09	603	SUB BX, CX
05DC	81FAFF00	604	CMP DX, 255D
05E0	7D08	605	JGE NO_WAY
05E2	83FA00	606	CMP DX, 00
05E5	7E03	607	JLE NO_WAY
05E7	E80B00	608	CALL OUTPUT
05EA	42	609	INC DX
05EB	3B161300	610	CMP DX, XMAX_TMP

LOC	OBJ	LINE	SOURCE
05EF	7EEB	611	JLE OVER
05F1	03	612	DUN: RET
		613	
05F2	8AC2	614	OUTPUT: MOV AL, DL
05F4	E614	615	OUT XREG, AL
05F6	8AC3	616	MOV AL, BL
05F8	E616	617	OUT YREG, AL
05FA	A00600	618	MOV AL, GSCALE_VAL
05FD	E618	619	OUT GSCALE, AL
05FF	03	620	RET
		621	
0600	260606170000	622	PRINT_RESULTS: MOV ES: BIRD_MISSES, 0
0606	0606290001	623	MOV RESULTS_FLAG, 1
0608	BAD000	624	MOV DX, 008H
060E	B01D	625	MOV AL, 0350 ; VECTOR MODE
0610	E00000	626	CALL COUT
0613	B037	627	MOV AL, 0670
0615	E00000	628	CALL COUT
0618	B078	629	MOV AL, 1700
061A	E00000	630	CALL COUT
061D	B028	631	MOV AL, 0500
061F	E00000	632	CALL COUT
0622	B040	633	MOV AL, 1000
0624	E00000	634	CALL COUT
0627	B01F	635	MOV AL, 0370 ; ALPHA MODE
0629	E00000	636	CALL COUT
062C	B92000	637	MOV CX, 320
062F	BE2000	638	SI, OFFSET HLMIS_ASCII
0632	260A04	639	AGAIN: MOV AL, ES:[SI]
0635	E00000	640	CALL COUT
0638	B01502	641	CALL SHORT_DELAY
063B	46	642	INC SI
063C	E2F4	643	LOOP AGAIN
063E	B01D	644	MOV AL, 0350
0640	E00000	645	CALL COUT
0643	E9CFA	646	JMP DO_17_OVER
		647	
0646	2606061E0000	648	DIST_FRO_TGT: MOV ES: HIT_SHORT, 0
064C	0606280001	649	MOV DIST_FRO_TGT_FLAG, 1
0651	BAD000	650	MOV DX, 008H
0654	B01D	651	MOV AL, 0350 ; VECTOR MODE
0656	E00000	652	CALL COUT
0659	B037	653	MOV AL, 0670
065B	E00000	654	CALL COUT
065E	B078	655	MOV AL, 1700
0660	E00000	656	CALL COUT
0663	B028	657	MOV AL, 0500
0665	E00000	658	CALL COUT
0668	B040	659	MOV AL, 1000
066A	E00000	660	CALL COUT
066D	B01F	661	MOV AL, 0370 ; ALPHA MODE
066F	E00000	662	CALL COUT
0672	B91000	663	MOV CX, 160
0675	BE4000	664	MOV SI, OFFSET DIS_FRO_TGT
0678	260A04	665	AGAIN: MOV AL, ES:[SI]

LOC	OBJ		LINE	SOURCE
067B	E80000	E	666	CALL COUT
067E	E8CF01		667	CALL SHORT_DELAY
0681	46		668	INC SI
0682	E2F4		669	LOOP AGN
0684	B01D		670	MOV AL, 350
0686	E80000	E	671	CALL COUT
0689	E904FA		672	JMP DO_IT_OVER
			673	
068C	BAD000		674	THRUSTERS_MSG: MOV DX, 808H
068F	B01D		675	MOV AL, 8350
0691	E80000	E	676	CALL COUT
0694	B020		677	MOV AL, 400
0696	E80000	E	678	CALL COUT
0699	B060		679	MOV AL, 1400
069B	E80000	E	680	CALL COUT
069E	B020		681	MOV AL, 400
06A0	E80000	E	682	CALL COUT
06A3	B040		683	MOV AL, 1800
06A5	E80000	E	684	CALL COUT
06A8	B01F		685	MOV AL, 370
06AA	E80000	E	686	CALL COUT
06AD	B90000		687	MOV CX, (OFFSET END_OF_MESSAGE3 - OFFSET MESSAGE3)
06B0	BE3500	R	688	MOV SI, OFFSET MESSAGE3
06B3	2E8A04		689	AGN?: MOV AL, 05:[SI]
06B6	E80000	E	690	CALL COUT
06B9	E89401		691	CALL SHORT_DELAY
06BC	46		692	INC SI
06BD	E2F4		693	LOOP AGN?
06BF	B90200		694	MOV CX, 2
06C2	BE6B00		695	MOV SI, OFFSET (IDEAL_THRUST + 3)
06C5	268A04		696	IT_Again: MOV AL, 05:[SI]
06C8	E80000	E	697	CALL COUT
06CB	E86201		698	CALL SHORT_DELAY
06CE	46		699	INC SI
06CF	E2F4		700	LOOP IT_Again
06D1	B049		701	MOV AL, 1110
06D3	E80000	E	702	CALL COUT
06D6	B02F		703	MOV AL, 570
06D8	E80000	E	704	CALL COUT
06DB	B90200		705	MOV CX, 2
06DE	BE5300		706	MOV SI, OFFSET (ACTUAL_THRUST + 3)
06E1	268A04		707	IT_Again2: MOV AL, 05:[SI]
06E4	E80000	E	708	CALL COUT
06E7	E86601		709	CALL SHORT_DELAY
06EA	46		710	INC SI
06EB	E2F4		711	LOOP IT_Again2
06ED	B041		712	MOV AL, 1810
06EF	E80000	E	713	CALL COUT
06F2	B01D		714	MOV AL, 350
06F4	E80000	E	715	CALL COUT
06F7	C?		716	RET
			717	
			718	
06FB	E891FF		719	PRINT_HIT: CALL THRUSTERS_MSG
06FB	C606220003	R	720	MOV BLINK_COUNT, 030

LOC	OBJ		LINE	SOURCE
0700	0606270001	R	721	MOV HIT_FLAG, 1
0705	26C606160000		722	MOV ES: BIRD_HIT, 0
0708	8A0000		723	PRINT_HIT_AGN: MOV DX, 008H
070E	B01D		724	MOV AL, 0350 ; VECTOR MODE
0710	E80000	E	725	CALL COUT
0713	B037		726	MOV AL, 0670
0715	E80000	E	727	CALL COUT
0718	B075		728	MOV AL, 1780
071A	E80000	E	729	CALL COUT
071D	B02E		730	MOV AL, 0560
071F	E80000	E	731	CALL COUT
0722	B042		732	MOV AL, 1020
0724	E80000	E	733	CALL COUT
0727	B01F		734	MOV AL, 0370 ; ALPHA MODE
0729	E80000	E	735	CALL COUT
072C	B048		736	MOV AL, 1100 ; H
072E	E80000	E	737	CALL COUT
0731	B049		738	MOV AL, 1110 ; I
0733	E80000	E	739	CALL COUT
0736	B054		740	MOV AL, 1240 ; T
0738	E80000	E	741	CALL COUT
073B	B021		742	MOV AL, 0410 ; !
073D	E80000	E	743	CALL COUT
0740	B01D		744	MOV AL, 0350
0742	E80000	E	745	CALL COUT
0745	E8FE00		746	CALL DELAY
0748	B01D		747	MOV AL, 0350
074A	E80000	E	748	CALL COUT
074D	26803E1A0001		749	CMP ES: V_REP_REQ, 1 ; ARE "WE" NEEDED ANYWHERE??
0753	7464		750	JE DOWN
0755	26803E180001		751	CMP ES: H_REP_REQ, 1 ; ARE "WE" NEEDED ANYWHERE??
075E	745C		752	JE DOWN
075D	FE0E2200	R	753	DEC BLINK_COUNT
0761	803E220000	R	754	CMP BLINK_COUNT, 0
0766	7451		755	JE DOWN
0768	B01B		756	MOV AL, 0330 ;
076A	E80000	E	757	CALL COUT ;
076D	B07F		758	MOV AL, 1770 ; THESE FOUR INSTRUCTIONS CHANGE THE
076F	E80000	E	759	CALL COUT ; DATA LEVEL TO BLACK!
0772	B037		760	MOV AL, 670
0774	E80000	E	761	CALL COUT
0777	B075		762	MOV AL, 1780
0779	E80000	E	763	CALL COUT
077C	B02E		764	MOV AL, 560
077E	E80000	E	765	CALL COUT
0781	B042		766	MOV AL, 1020
0783	E80000	E	767	CALL COUT
0786	B01F		768	MOV AL, 370
0788	E80000	E	769	CALL COUT ; ALPHA MODE
078B	B048		770	MOV AL, 1100 ; "BLACK 'H'"
078D	E80000	E	771	CALL COUT
0790	B049		772	MOV AL, 1110 ; "BLACK 'I'"
0792	E80000	E	773	CALL COUT
0795	B054		774	MOV AL, 1240 ; "BLACK 'T'"
0797	E80000	E	775	CALL COUT

LOC	OBJ	LINE	SOURCE
079A	B021	776	MOV AL, 410 ; "BLACK '1'"
079C	E00000	777	CALL COUT
079F	B021	778	MOV AL, 410
07A1	E00000	779	CALL COUT
07A4	B01E	780	MOV AL, 330 ; THESE NEXT FOUR INSTRUCTIONS SET
07A6	E00000	781	CALL COUT
07A9	B061	782	MOV AL, 1410 ; THE DATA LEVEL BACK TO WHITE
07AB	E00000	783	CALL COUT
07AE	B01D	784	MOV AL, 350 ; RETURN TO VECTOR MODE
07B0	E00000	785	CALL COUT
07B3	E09A00	786	CALL SHORT_DELAY
07B6	E952FF	787	JMP PRINT_HIT_AGN
07B9	E954F9	788	JMP DOWN: DO_IT_OVER
		789	
07BC	E0C0FE	790	PRINT_GRND_BIRD: CALL THRUSTERS_MSG
07BF	26C6061C0000	791	MOV ES: GRND_BIRD, 0
07C5	C606260001	792	MOV GRND_BIRD_FLAG, 1
07CA	BAD000	793	MOV DX, 008H
07CD	B01D	794	MOV AL, 0350
07CF	E00000	795	CALL COUT
07D2	B037	796	MOV AL, 0670
07D4	E00000	797	CALL COUT
07D7	B061	798	MOV AL, 1410
07D9	E00000	799	CALL COUT
07DC	B02E	800	MOV AL, 0560
07DE	E00000	801	CALL COUT
07E1	B042	802	MOV AL, 1020
07E3	E00000	803	CALL COUT
07E6	B01F	804	MOV AL, 0370 ; ALPHA MODE
07E8	E00000	805	CALL COUT
07EB	B90E00	806	MOV CX, (OFFSET FIN_OF_MESSAGE - OFFSET MESSAGE)
07EE	BE0000	807	MOV SI, OFFSET MESSAGE
07F1	2E0A04	808	REPEAT: MOV AL, 05:[SI]
07F4	E00000	809	CALL COUT
07F7	E05600	810	CALL SHORT_DELAY
07FA	46	811	INC SI
07FB	E2F4	812	LOOP REPEAT
07FD	E910F9	813	JMP DO_IT_OVER
		814	
0800	C606240000	815	ERROR_MSG: MOV ERROR, 0
0805	C606250001	816	MOV ERROR_MSG_FLAG, 1
080A	26C6061D0000	817	MOV ES: END_OF_RPV, 0
0810	BAD000	818	MOV DX, 008H
0813	B01D	819	MOV AL, 350
0815	E00000	820	CALL COUT
0818	B020	821	MOV AL, 400
081A	E00000	822	CALL COUT
081D	B060	823	MOV AL, 1400
081F	E00000	824	CALL COUT
0822	B02E	825	MOV AL, 560
0824	E00000	826	CALL COUT
0827	B041	827	MOV AL, 1010
0829	E00000	828	CALL COUT
082C	B01F	829	MOV AL, 370 ; ALPHA MODE
082E	E00000	830	CALL COUT

LOC	OBJ	LINE	SOURCE
0031	B92700	831	MOV CX, (OFFSET FIN_OF_MESSAGE2 - OFFSET MESSAGE2)
0034	BE0E00	832	MOV SI, OFFSET MESSAGE2
0037	2E8A04	833	MOV AL, CS:[SI]
003A	E80000	834	CALL COUNT
003D	E81000	835	CALL SHORT_DELAY
0040	46	836	INC SI
0041	E2F4	837	LOOP REPT2
0043	E9CAF8	838	JMP DO_IT_OVER
		839	
0046	B850C3	840	MOV AX, 500000
0049	48	841	DEC AX
004A	3D0000	842	CMP AX, 0
004D	75FA	843	JNE AGAIN_N_AGAIN
004F	C3	844	RET
0050	B81027	845	MOV AX, 100000
0053	48	846	DEC AX
0054	3D0000	847	CMP AX, 0
0057	75FA	848	JNE AGAIN_N_AGAIN
0059	C3	849	RET
		850	
005A	B400	851	MOV AH, 0
005C	E40E	852	IN AL, 00EH ; USART_STATUS
005E	2402	853	AND AL, 2
0060	7404	854	JZ GO_BACK
0062	E40C	855	IN AL, 00CH
0064	B401	856	MOV AH, 1
0066	C3	857	RET
		858	
0067	268B160100	859	MOV DX, ES:X,Y
006C	B064	860	MOV AL, 64H
006E	2AC2	861	SUB AL, DL
0070	2600060500	862	ADD ES:OFFSET_X, AL
0075	B064	863	MOV AL, 64H
0077	2AC6	864	SUB AL, DH
0079	2600060600	865	ADD ES:OFFSET_Y, AL
007E	C3	866	RET
		867	
		868	CODE
		869	ENDS
		870	END CS:DRIVER, DS:DATA_GROUP, SS:STACK_SEG

ASSEMBLY COMPLETE, NO ERRORS FOUND

SERIES-III 8086/8087/8088 MACRO ASSEMBLER V1.0 ASSEMBLY OF MODULE SMOKEY_THE_BARE
 OBJECT MODULE PLACED IN :F2:SMOKE.OBJ
 INVOCATION LINE CONTROLS: DEBUG

LOC	OBJ	LINE	SOURCE
		1	NAME SMOKEY_THE_BARE
		2	
		3	DATA_GROUP GROUP DAT_SEG, DATA_SEG
		4	CGROUP GROUP CODE
		5	
		6	ASSUME CS:CGROUP, DS:DATA_GROUP
		7	
		8	PUBLIC SMOKE_CHECK, SMOKE_SET, SMOKE_START_UP
		9	
----		10	DATA_SEG SEGMENT PUBLIC
		11	EXTRN BACKGROUND: BYTE
----		12	DATA_SEG ENDS
		13	
----		14	DAT_SEG SEGMENT PUBLIC
0000 (1		15	DONE DB 1 DUP(?)
0001 (1			
		16	SERIES_NO DB 1 DUP(?)
----		17	DAT_SEG ENDS
		18	
----		19	CODE SEGMENT PUBLIC 'CODE'
0000 0606000000 R		20	SMOKE_START_UP: MOV DONE, 0
0005 0606010001 R		21	MOV SERIES_NO, 1
0009 03		22	RET
		23	
0008 803E000000 R		24	SMOKE_CHECK: CMP DONE, 0
0010 7405		25	JE GO_BACK
0012 B401		26	MOV AH, 1
0014 EB0390		27	JMP GO_BACK2
0017 B400		28	GO_BACK: MOV AH, 0
0019 03		29	GO_BACK2: RET
		30	
001A 803E000000 R		31	SMOKE_SET: CMP DONE, 0
001F 7403		32	JE START
0021 B401		33	MOV AH, 1
0023 03		34	RET
		35	
		36	
0024 803E010001 R		37	START: CMP SERIES_NO, 1
0029 741F		38	JE SERIES_1
002B 803E010002 R		39	CMP SERIES_NO, 2
0030 742A		40	JE SERIES_2
0032 803E010003 R		41	CMP SERIES_NO, 3
0037 7435		42	JE SERIES_3
0039 803E010004 R		43	CMP SERIES_NO, 4
003E 7440		44	JE SERIES_4
0040 803E010005 R		45	CMP SERIES_NO, 5
0045 744B		46	JE SERIES_5

LOC	OBJ	LINE	SOURCE
0047	EB5B90	47	JMP SERIES_6
		48	
004A	FE060000	49	SERIES_1: INC BACKGROUND
004E	803E00000F	50	CMP BACKGROUND, 150
0053	7401	51	JE DONE1
0055	C3	52	RET
0056	C606010002	53	DONE1: MOV SERIES_NO, 2
005B	C3	54	RET
		55	
005C	FE0E0000	56	SERIES_2: DEC BACKGROUND
0060	803E000008	57	CMP BACKGROUND, 80
0065	7401	58	JE DONE2
0067	C3	59	RET
0068	C606010003	60	DONE2: MOV SERIES_NO, 3
006D	C3	61	RET
		62	
006E	FE060000	63	SERIES_3: INC BACKGROUND
0072	803E00000F	64	CMP BACKGROUND, 150
0077	7401	65	JE DONE3
0079	C3	66	RET
007A	C606010004	67	DONE3: MOV SERIES_NO, 4
007F	C3	68	RET
		69	
0080	FE0E0000	70	SERIES_4: DEC BACKGROUND
0084	803E000004	71	CMP BACKGROUND, 4
0089	7401	72	JE DONE4
008B	C3	73	RET
008C	C606010005	74	DONE4: MOV SERIES_NO, 5
0091	C3	75	RET
		76	
0092	FE060000	77	SERIES_5: INC BACKGROUND
0096	803E000008	78	CMP BACKGROUND, 80
009B	7401	79	JE DONE5
009D	C3	80	RET
009E	C606010006	81	DONE5: MOV SERIES_NO, 6
00A3	C3	82	RET
		83	
00A4	FE0E0000	84	SERIES_6: DEC BACKGROUND
00A8	803E000000	85	CMP BACKGROUND, 0
00AD	7401	86	JE FINISHED
00AF	C3	87	RET
00B0	C606000001	88	FINISHED: MOV DONE, 1
00B5	C3	89	RET
		90	
----		91	CODE ENDS
		92	END

ASSEMBLY COMPLETE, NO ERRORS FOUND

FILES-III 8086/8087/8088 MACRO ASSEMBLER V1.0 ASSEMBLY OF MODULE PETER_RABBIT
 OBJECT MODULE PLACED IN F2.GAE.OBJ
 INVOCATION LINE CONTROLS DEBUG

LOC	OBJ	LINE	SOURCE
		1	NAME PETER_RABBIT
		2	
		3	DATA_GROUP GROUP GAE_SEG, DATA_SEG, XFER_SEG
		4	CGROUP GROUP CODE
		5	
		6	EXTRN GRAPH1_NEAR, FIRE_BIRD, BYTE
		7	PUBLIC GRAPH1_GAE_POINT, GAE_START_UP, GAE_GT_FOV, H_REP_FLAG, V_REP_FLAG
		8	PUBLIC ELAPSED_TIME
		9	EXTRN COUT_NEAR
		10	
		11	ASSUME CS CGROUP, DS DATA_GROUP
		12	
		13	XFER_SEG SEGMENT AT 0600H
		14	EXTRN BAD_MISS, BYTE, START_BIT, BYTE, DATA_READY, BYTE
		15	XFER_SEG ENDS
		16	
		17	DATA_SEG SEGMENT PUBLIC
		18	EXTRN YCNT, BYTE, XCNT, BYTE, THRUSTER_FIRE, BYTE, ERROR, BYTE
		19	DATA_SEG ENDS
		20	
		21	GAE_SEG SEGMENT PUBLIC
		22	
00000	01	23	BIT_BUCKET DB 1 DUP(?)
00001	01	24	ELAPSED_TIME DW 1 DUP(?)
00007	01	25	FIFTEEN DW 1 DUP(?)
00005	01	26	FOUR DW 1 DUP(?)
00003	01	27	Y_SCALE_FACTOR EQU 03D
00007	01	28	H_X_GRAPHIC_POINT DW 1 DUP(?)
00009	01	29	H_Y_GRAPHIC_POINT DW 1 DUP(?)
0000B	01	30	HGAE_OFFSET DW 1 DUP(?)
0000D	01	31	FIFTY DW 1 DUP(?)
0000F	01	32	H_REP_FLAG DB 1 DUP(?)

LOC	OBJ	LINE	SOURCE
010	(1 ??)	33	V_REP_FLAG DB 1 DUP(?)
011	(1 ??)	34	BIG_MISS DB 1 DUP(?)
0012	(1 ??)	35	THRUSTER_FIRED DB 1 DUP(?)
		36	
----		37	GAE_SEG ENDS
		38	
----		39	CODE SEGMENT PUBLIC 'CODE'
		40	
0000	0606000000 R	41	GAE_START_UP: MOV BIT_BUCKET, 0
0005	0606110000 R	42	MOV BIG_MISS, 0
000A	070601000000 R	43	MOV ELAPSED_TIME, 0
0010	070603000F00 R	44	MOV FIFTEEN, 150
0016	070605000400 R	45	MOV FOUR, 40
001C	07060D003200 R	46	MOV FIFTY, 500
0022	070600000502 R	47	MOV HGAE_OFFSET, 7250
0028	0606120000 R	48	MOV THRUSTER_FIRED, 0
002D	06060F0000 R	49	MOV H_REP_FLAG, 0
0032	0606100000 R	50	MOV V_REP_FLAG, 0
0037	C3	51	RET
		52	
0038	EAD000 R	53	GAE_GT_FOV: MOV DX, 008H
003B	260606000000 E	54	MOV ES, DATA_READY, 0
0041	B01D	55	MOV AL, 0350, VECTOR MODE
0043	E00000 E	56	CALL COUT
0046	E00900	57	CALL CONTINUE
0049	C3	58	RET
		59	
004A	BAD000	60	GRAPH_GAE_POINT: MOV DX, 008H
004D	B01C	61	MOV AL, 0340
004F	E00000 E	62	CALL COUT
0052	33C0	63	CONTINUE: XOR AX, AX
0054	803E000001 R	64	CMP BIT_BUCKET, 1 ; IF SET THEN WE'RE ON PASS TWO
0059	7400	65	JE NORMAL ; I.E., LEFT SIDE OF SCREEN
005B	803E100001 R	66	CMP V_REP_FLAG, 1
0060	7506	67	JNE NORMAL
0062	070600004003 R	68	MOV HGAE_OFFSET, 8450
0068	801E0000 R	69	NORMAL: MOV BX, HGAE_OFFSET
006C	81FB0502	70	CMP BX, 7250
0070	7412	71	JZ X1
0072	81FB4003	72	CMP BX, 8450
0076	740C	73	JZ X1
0078	A00000 E	74	MOV AL, VCNT
007B	B3C8	75	MOV BL, 2000
007D	2A06	76	SUB BL, AL
007F	8AC1	77	MOV AL, BL
0081	EB0490	78	JMP ONWARD
0084	A00000 E	79	X1: MOV AL, VCNT
0087	B400	80	ONWARD: MOV AH, 0
0089	F7260300 R	81	MUL FIFTEEN

LOC	OBJ	LINE	SOURCE
0080	F7360500	R 82	DIV FOUR
0091	83FA02	83	CMP DX, 020
0094	7C01	84	JL GO_ON
0096	40	85	INC AX
0097	8B1E0000	R 86	MOV BX, HGRAE_OFFSET
0098	B97701	87	MOV CX, 3750
009E	81FB0502	88	CMP BX, 7250
00A2	7413	89	JZ X2
00A4	81FB4003	90	CMP BX, 8450
00A8	7400	91	JZ X2
00AA	8A1E0000	E 92	MOV BL, YCNT
00AE	B2C8	93	MOV DL, 2000
00B0	2AC3	94	SUB DL, BL
00B2	8ADA	95	MOV BL, DL
00B4	EB0590	96	JMP ONWARD1
00B7	8A1E0000	E 97	MOV BL, XCNT
00B8	80FB64	98	CMP BL, 1000
00BE	7314	99	JNB SUBT
00C0	2BC8	100	SUB CX, AX
00C2	8BC1	101	MOV AX, CX
00C4	8B1E0000	R 102	MOV BX, HGRAE_OFFSET
00C8	03060000	R 103	ADD AX, HGRAE_OFFSET
00CC	3DF203	104	CMP AX, 10100
00CF	7F15	105	JG ONWARD3
00D1	EB0090	106	JMP GO_ON5
00D4	2BC1	107	SUB AX, CX
00D6	8B1E0000	R 108	MOV BX, HGRAE_OFFSET
00DA	2BD8	109	SUB BX, AX
00DC	7E11	110	JLE ONWARD2
00DE	8BC3	111	MOV AX, BX
00E0	A30700	R 112	MOV H_X_GRAPHIC_POINT, AX
00E3	EB1090	113	JMP OVER_THERE
00E6	C7060700F203	R 114	MOV H_X_GRAPHIC_POINT, 10100
00EC	EB0790	115	JMP OVER_THERE
00EF	C70607000000	R 116	MOV H_X_GRAPHIC_POINT, 0
00F5	E82B01	117	CALL TIME
00F8	B00300	118	MOV BX, Y_SCALE_FACTOR
00FB	F7E3	119	MUL BX
00FD	05B000	120	ADD AX, 30000
0100	F7360000	R 121	DIV FIFTY
0104	83FA19	122	CMP DX, 250
0107	7C01	123	JL GO_ON4
0109	40	124	INC AX
		125	
010A	300B03	126	GO_ON4: CMP AX, 7790 ; IS TIME GOING TO EXCEED THE TOP OF
010D	7E03	127	JNG GO_ON6 ; THE ADM-3 SCREEN?? IF YES THEN REDUCE
010F	B00B03	128	MOV AX, 7790 ; THE MAGNITUDE TO 7790.
		129	
0112	A30900	R 130	GO_ON6: MOV H_Y_GRAPHIC_POINT, AX
0115	BAD000	131	MOV DX, 008H
		132	; THIS ROUTINE OUTPUTS HIGH Y, LOW Y, HIGH X AND LOW X FOR HORIZONTAL
		133	; AIM ERROR TO ADM3.
0118	26003E000001	E 134	CMP ES: BAD_MISS, 1 ; BAD_MISS???
011E	7505	135	JNE BY_PASS ; IF YES THEN
0120	B01D	136	MOV AL, 0350 ; GO TO VECTOR MODE
			C-24

LOC	OBJ		LINE	SOURCE
0122	E80000	E	137	CALL COUT ; ELSE, STAY IN POINT MODE
			138	
0125	A10900	R	139	MOV AX, H_V_GRAPHIC_POINT
0128	8105		140	MOV CL, 5
012A	D3E8		141	SHR AX, CL
012C	241F		142	AND AL, 00011111B
012E	0C20		143	OR AL, 00100000B
0130	E80000	E	144	CALL COUT
0133	A10900	R	145	MOV AX, H_V_GRAPHIC_POINT
0136	241F		146	AND AL, 00011111B
0138	0C20		147	OR AL, 01100000B
013A	E80000	E	148	CALL COUT
013D	A10700	R	149	MOV AX, H_X_GRAPHIC_POINT
0140	8105		150	MOV CL, 5
0142	D3E8		151	SHR AX, CL
0144	241F		152	AND AL, 00011111B
0146	0C20		153	OR AL, 00100000B
0148	E80000	E	154	CALL COUT
014B	A10700	R	155	MOV AX, H_X_GRAPHIC_POINT
014E	241F		156	AND AL, 00011111B
0150	0C40		157	OR AL, 01000000B
0152	E80000	E	158	CALL COUT
0155	26803E000001	E	159	CMP ES: BAD_MISS, 1
0158	751E		160	JNE BY_PASS2
015B	B01F		161	MOV AL, 0370 ; ALPHA MODE
015F	E80000	E	162	CALL COUT
0162	803E120001	R	163	CMP THRUSTER_FIRED, 1
0167	7508		164	JNE AST
0169	005F		165	MOV AL, 1370 ; OUTPUT A ' ' WHEN A THRUSTER FIRES.
016B	E80000	E	166	CALL COUT
016E	E80090		167	JMP BY_PASS2
0171	B02A		168	MOV AL, 0520 ; OUTPUT ASTERISK
0173	E80000	E	169	CALL COUT
0176	B01D		170	MOV AL, 0350
0178	E80000	E	171	CALL COUT
017B	803E000001	R	172	CMP BIT_BUCKET, 1
0180	743A		173	JE AGAIN2
0182	832E010016	P	174	SUB ELAPSED_TIME, 220 ; USED TO BE 20
0187	C606000001	R	175	MOV BIT_BUCKET, 1
018C	803E0F0001	R	176	CMP H_REP_FLAG, 1 ; IF REP THEN A DIFFERENT OFFSET
0191	7409		177	JE ABNORMAL ; FROM REGULAR IS USED
0193	C7060000C300	R	178	MOV HGRE_OFFSET, 1950 ; CHANGE THE OFFSETS TO GET
0199	E80790		179	JMP ACROSS ; READY TO DO THE VERTICAL GRE
019C	C7060000EF00	R	180	MOV HGRE_OFFSET, 2390
01A2	803E0000C8	E	181	CMP YCNT, 2000
01A7	7210		182	JB AROUND
01A9	26C606000001	E	183	MOV ES: BAD_MISS, 1
01AF	C606000001	E	184	MOV ERROR, 1
01B4	C6060000C8	E	185	MOV YCNT, 2000
01B7	E996FE		186	JMP CONTINUE
01BC	C606000000	R	187	MOV BIT_BUCKET, 0
01C1	803E120001	R	188	CMP THRUSTER_FIRED, 1
01C6	7464		189	JE HERE
01C8	26803E000001	E	190	CMP ES: FIRE_BIRD, 1
01CE	755C		191	JNE HERE

LOC	OBJ	LINE	SOURCE
01F0	C606120001	R 192	MOV THRUSTER_FIRED,1
01D5	C606000001	E 193	MOV THRUSTER_FIRE,1
01DA	C606110001	R 194	MOV BIG_MISS,1
01DF	26C6060000001	E 195	MOV ES:BAD_MISS,1
01E5	C606000001	R 196	MOV BIT_BUCKET,1
01EA	E83600	197	CALL TIME
01ED	832E010016	R 198	SUB ELAPSED_TIME,22D
01F2	201600	199	SUB AX,22D
01F5	B80300	200	MOV BX,Y_SCALE_FACTOR
01F8	F7E3	201	MUL BX
01FA	05B000	202	ADD AX,3000D
01FD	F7360000	R 203	DIV FIFTY
0201	83FA19	204	CMF DX,25D
0204	7C01	205	JL GO_ON_ARND
0206	40	206	INC AX
0207	3D0003	207	CMF AX,779D
020A	7603	208	JNA GO_ON_ARND2
020C	B80003	209	MOV AX,779D
020F	A30900	R 210	MOV H.Y_GRAPHIC_POINT,AX
0212	C706070000000	R 211	MOV H.X_GRAPHIC_POINT,0
0216	BAD000	212	MOV DX,008H
021B	B010	213	MOV AL,35D
021D	E80000	E 214	CALL COUT
0220	E902FF	215	JMP BY_PASS
		216	
		217	
0223	8306010016	P 218	ADD ELAPSED_TIME,22D
0228	A10100	R 219	MOV AX,ELAPSED_TIME
022B	C3	220	RET
		221	
022C	BAD000	222	MOV DX,008H
022F	B01C	223	MOV AL,034D ;CHANGE RGB TO POINT MODE
0231	E80000	E 224	CALL COUT
0234	C70600000502	R 225	MOV HGAIE_OFFSET,725D
		226	
023A	003E110001	R 227	CMF BIG_MISS,1
023F	7516	228	JNE LEAVE
0241	26C6060000000	E 229	MOV ES:BAD_MISS,0
0247	C6060000000	R 230	MOV BIT_BUCKET,0
024C	26C6060000000	E 231	MOV ES:FIRE_BIRD,0
0252	C606110000	R 232	MOV BIG_MISS,0
0257	C606120000	P 233	MOV THRUSTER_FIRED,0
025C	C3	234	RET
		235	
		236	
----		237	CODE ENDS
		238	
		239	END

ASSEMBLY COMPLETE. NO ERRORS FOUND

SERIES-III 8086/8087/8088 MACRO ASSEMBLER V1.0 ASSEMBLY OF MODULE MARLYN_MONROE
 OBJECT MODULE PLACED IN F2:RETRO.OBJ
 INVOCATION LINE CONTROLS: DEBUG

LOC	OBJ	LINE	SOURCE
		1	NAME MARLYN_MONROE
		2	PUBLIC GRAPH1, COUT, CIN, GRAPH_VREP, GRAPH_HREP, USART_SET_UP_FOR_ADM
		3	PUBLIC DELAY_3
		4	
		5	CGROUP GROUP CODE
		6	
		7	ASSUME CS:CGROUP
		8	
		9	CODE SEGMENT PUBLIC 'CODE'
		10	
0006		11	TIMER_CNTRL EQU 006H
0004		12	TIMER_CNTRL2 EQU 004H
0006		13	CNTR2_MODE EQU 006H
0004		14	LOW_ADM EQU 04H
0000		15	HIGH_ADM EQU 00H
000A		16	USART_CNTRL EQU 00AH
0040		17	USART_RESET EQU 40H
004E		18	USART_MODE EQU 4EH
0037		19	USART_CMDND EQU 37H
000E		20	USART_STATUS EQU 00EH
		21	
0075		22	DELAY_VAL EQU 75H
		23	
		24	
0000 1D		25	PICPOINTS DB 1DH, 21H, 7CH, 2FH, 54H, 23H, 6CH, 2FH, 54H, 440, 1440, 0650, 1270
0001 21			
0002 7C			
0003 2F			
0004 54			
0005 23			
0006 6C			
0007 2F			
0008 54			
0009 24			
000A 64			
000B 35			
000C 57			
0000 36		26	PICPOINTS1 DB 0660, 1570, 0660, 1120, 0660, 1570, 0660, 1360, 440, 1440, 0670, 1230, 430, 1540, 0750, 1260, 410
000E 6F			
000F 36			
0010 4A			
0011 36			
0012 6F			
0013 36			
0014 5E			
0015 24			
0016 64			
0017 37			
0018 53			

LOC	OBJ	LINE	SOURCE
0019	23		
001A	6C		
001B	3D		
001C	56		
001D	21		
001E	7C	27	PICPOINTS2 DB 1740, 0750, 1260, 410, 1740, 570, 1240, 0350, 410, 1740, 0660, 1250, 0660, 1570, 0660
001F	3D		
0020	56		
0021	21		
0022	7C		
0023	2F		
0024	54		
0025	1D		
0026	21		
0027	7C		
0028	36		
0029	55		
002A	36		
002B	6F		
002C	36		
002D	55	28	PICPOINTS3 DB 1250, 340, 640, 1640, 660, 1230, 620, 1780, 660, 1230, 680, 1740, 660, 1230, 570, 1480, 660, 1230, 550, 1440, 660, 1230, 530
002E	1C		
002F	34		
0030	74		
0031	36		
0032	53		
0033	32		
0034	78		
0035	36		
0036	57		
0037	30		
0038	7C		
0039	36		
003A	53		
003B	2F		
003C	60		
003D	36		
003E	53		
003F	2D		
0040	64		
0041	36		
0042	53		
0043	28		
0044	68	29	PICPOINTS4 DB 1500, 660, 1230, 510, 1540, 660, 1230, 470, 1600, 660, 1230, 450, 1640, 660, 1230, 430, 1700, 660, 1230, 640, 1640, 660
0045	36		
0046	53		
0047	29		
0048	6C		
0049	36		
004A	53		
004B	27		
004C	70		

LOC	DB	LINE	SOURCE
0040	36		
004E	53		
004F	25		
0050	74		
0051	36		
0052	53		
0053	23		
0054	78		
0055	36		
0056	53		
0057	34		
0058	74		
0059	36		
005A	57	30	PICPOINTS5 DB 1270, 620, 1700, 660
005B	32		
005C	78		
005D	36		
005E	57	31	PICPOINTS6 DB 1270, 680, 1740, 660, 1270, 570, 1400, 660, 1270, 550, 1440, 660, 1270, 530, 1580, 660, 1270, 510
005F	30		
0060	70		
0061	26		
0062	57		
0063	2F		
0064	60		
0065	36		
0066	57		
0067	20		
0068	64		
0069	36		
006A	57		
006B	28		
006C	68		
006D	26		
006E	57		
006F	29		
0070	60	32	PICPOINTS7 DB 1540, 660, 1270, 470, 1600, 660, 1270
0071	36		
0072	57		
0073	27		
0074	70		
0075	36		
0076	57		
0077	25	33	PICPOINTS8 DB 450, 1640, 660, 1270, 430, 1700, 660, 1270, 350, 570, 1640, 560, 1140, 370, 1240
0078	74		
0079	36		
007A	57		
007B	23		
007C	78		
007D	36		
007E	57		
007F	10		
0080	2F		
0081	74		

LOC	OBJ	LINE	SOURCE
0082	2E		
0083	4C		
0084	1F		
0085	54		
0086	1D	34	PICPOINTS9 DB 350, 560, 1660, 560, 1140, 370, 1110, 350, 550, 1700, 560, 1140, 370, 1150
0087	2E		
0088	76		
0089	2E		
008A	4C		
008B	1F		
008C	49		
008D	1D		
008E	2D		
008F	78		
0090	2E		
0091	4C		
0092	1F		
0093	4D		
0094	1D	35	PICPOINTS10 DB 350, 540, 1720, 560, 1140, 370, 1050, 350, 520, 1760, 560, 1140, 370, 1230, 550, 520, 1400, 560, 1140
0095	2C		
0096	7A		
0097	2E		
0098	4C		
0099	1F		
009A	45		
009B	1D		
009C	2A		
009D	7E		
009E	2E		
009F	4C		
00A0	1F		
00A1	53		
00A2	1D		
00A3	2A		
00A4	60		
00A5	2E		
00A6	4C		
00A7	1F	36	PICPOINTS11 DB 370, 1050, 350, 510, 1420, 560, 1140, 370, 1030, 350, 610, 1770, 560, 1220, 630, 1440, 560, 1220
00A8	45		
00A9	1D		
00AA	29		
00AB	62		
00AC	2E		
00AD	4C		
00AE	1F		
00AF	43		
00B0	1D		
00B1	31		
00B2	7F		
00B3	2E		
00B4	52		
00B5	33		
00B6	64		

LOC	OBJ	LINE	SOURCE
00E7	2E		
00E8	52		
00E9	32	37	PICPOINTS12 DB 620, 1660, 560, 1380, 350, 620, 1660, 560, 1140, 630, 1440, 560, 1220
00EA	76		
00EB	2E		
00EC	58		
00ED	10		
00EE	32		
00EF	76		
00F0	2E		
00F1	40		
00F2	33		
00F3	64		
00F4	2E		
00F5	52		
00F6	10	38	PICPOINTS13 DB 350, 440, 1660, 570, 1240, 370, 580, 1140, 1050, 1060, 1240, 510, 350, 440, 1660, 710, 1310
00F7	24		
00F8	76		
00F9	2F		
00FA	54		
00FB	1F		
00FC	28		
00FD	40		
00FE	45		
00FF	46		
0100	54		
0101	29		
0102	10		
0103	24		
0104	76		
0105	39		
0106	59		
0107	1F	39	PICPOINTS14 DB 370, 580, 1220, 1110, 1070, 1180, 1240, 510
0108	28		
0109	52		
010A	49		
010B	47		
010C	48		
010D	54		
010E	29		
010F	10	40	PICPOINTS15 DB 340, 410, 1710, 570, 1240, 410, 1660, 570, 1240, 410, 1710, 580, 1830, 410, 1660, 680, 1030
0110	21		
0111	79		
0112	2F		
0113	54		
0114	21		
0115	76		
0116	2F		
0117	54		
0118	21		
0119	79		
011A	30		
011B	43		

LOC	OBJ	LINE	SOURCE
00EC	21		
00ED	76		
00EE	30		
00EF	43		
00F0	21	41	PICPOINTS16 DB 410, 1710, 600, 1220, 410, 1660, 600, 1220, 410, 1710, 610, 1010, 410, 166 0, 610, 1010
00F1	79		
00F2	30		
00F3	52		
00F4	21		
00F5	76		
00F6	30		
00F7	52		
00F8	21		
00F9	79		
00FA	31		
00FB	41		
00FC	21		
00FD	76		
00FE	31		
00FF	41		
0100	21	42	PICPOINTS17 DB 410, 1710, 610, 1200, 410, 1660, 610, 1200, 410, 1710, 610, 1370, 410, 166 0, 610, 1370
0101	79		
0102	31		
0103	50		
0104	21		
0105	76		
0106	31		
0107	50		
0108	21		
0109	79		
010A	31		
010B	5F		
010C	21		
010D	76		
010E	31		
010F	5F		
0110	21	43	PICPOINTS18 DB 410, 1710, 620, 1160, 410, 1660, 620, 1160, 410, 1710, 620, 1350, 410, 166 0, 620, 1350
0111	79		
0112	32		
0113	4E		
0114	21		
0115	76		
0116	31		
0117	4E		
0118	21		
0119	79		
011A	32		
011B	50		
011C	21		
011D	76		
011E	32		
011F	50		

LOC	OBJ	LINE	SOURCE
0120	21	44	PICPOINTS19 DB 410, 1710, 630, 1140, 410, 1660, 630, 1140, 410, 1710, 630, 1330, 410, 1660, 630, 1330
0121	79		
0122	33		
0123	40		
0124	21		
0125	76		
0126	32		
0127	40		
0128	21		
0129	79		
012A	33		
012B	58		
012C	21		
012D	76		
012E	33		
012F	58		
0130	21	45	PICPOINTS20 DB 410, 1710, 640, 1120, 410, 1660, 640, 1120, 410, 1710, 640, 1310, 410, 1660, 640, 1310
0131	79		
0132	34		
0133	4A		
0134	21		
0135	76		
0136	34		
0137	4A		
0138	21		
0139	79		
013A	34		
013B	59		
013C	21		
013D	76		
013E	34		
013F	59		
0140	21	46	PICPOINTS21 DB 410, 1710, 650, 1100, 410, 1660, 650, 1100, 410, 1710, 650, 1270, 410, 1660, 650, 1270
0141	79		
0142	35		
0143	48		
0144	21		
0145	76		
0146	35		
0147	48		
0148	21		
0149	79		
014A	25		
014B	57		
014C	21		
014D	76		
014E	35		
014F	57		
0150	21	47	PICPOINTS22 DB 410, 1710, 660, 1060, 410, 1660, 660, 1060, 410, 1710, 660, 1250, 410, 1660, 660, 1250
0151	79		
0152	36		

LOC	OBJ	LINE	SOURCE
0153	46		
0154	21		
0155	76		
0156	36		
0157	46		
0158	21		
0159	79		
015A	36		
015B	55		
015C	21		
015D	76		
015E	36		
015F	55		
0160	21	48	PICPOINTS23 DB 410, 1710, 670, 1040, 410, 1660, 670, 1040, 410, 1710, 670, 1230, 410, 1660, 670, 1230
0161	79		
0162	37		
0163	44		
0164	21		
0165	76		
0166	37		
0167	44		
0168	21		
0169	79		
016A	37		
016B	53		
016C	21		
016D	76		
016E	37		
016F	53		
0170	21	49	PICPOINTS24 DB 410, 1710, 700, 1020, 410, 1660, 700, 1020, 410, 1710, 700, 1210, 410, 1660, 700, 1210
0171	79		
0172	36		
0173	42		
0174	21		
0175	76		
0176	38		
0177	42		
0178	21		
0179	79		
017A	38		
017B	51		
017C	21		
017D	76		
017E	38		
017F	51		
0180	21	50	PICPOINTS25 DB 410, 1710, 710, 1000, 410, 1660, 710, 1000, 410, 1710, 710, 1170, 410, 1660, 710, 1170
0181	79		
0182	39		
0183	40		
0184	21		
0185	76		
0186	39		

LOC	OBJ	LINE	SOURCE
0187	40		
0188	21		
0189	79		
018A	39		
018B	4F		
018C	21		
018D	76		
018E	39		
018F	4F		
0190	21	51	PICPOINTS26 DB 410, 1710, 710, 1360, 410, 1660, 710, 1360, 410, 1710, 720, 1150, 410, 1660, 720, 1150
0191	79		
0192	39		
0193	5E		
0194	21		
0195	76		
0196	39		
0197	5E		
0198	21		
0199	79		
019A	3A		
019B	4D		
019C	21		
019D	76		
019E	3A		
019F	4D		
01A0	21	52	PICPOINTS27 DB 410, 1710, 720, 1340, 410, 1660, 720, 1340, 410, 1710, 730, 1130, 410, 1660, 730, 1130
01A1	79		
01A2	3A		
01A3	5C		
01A4	21		
01A5	76		
01A6	3A		
01A7	5C		
01A8	21		
01A9	79		
01AA	3E		
01AB	4B		
01AC	21		
01AD	76		
01AE	2E		
01AF	4B		
01B0	21	53	PICPOINTS28 DB 410, 1710, 730, 1320, 410, 1660, 730, 1320, 410, 1710, 740, 1110, 410, 1660, 740, 1110
01B1	79		
01B2	3B		
01B3	5A		
01B4	21		
01B5	76		
01B6	3B		
01B7	5A		
01B8	21		
01B9	79		
01BA	3C		

LOC	OBJ	LINE	SOURCE
0188	49		
018C	21		
018D	76		
018E	3C		
018F	49		
01C0	21	54	PICPOINTS29 DB 410, 1710, 740, 1300, 410, 1660, 740, 1300, 410, 1710, 750, 1070, 410, 1660, 750, 1070
01C1	79		
01C2	3C		
01C3	58		
01C4	21		
01C5	76		
01C6	3C		
01C7	58		
01C8	21		
01C9	79		
01CA	3D		
01CB	47		
01CC	21		
01CD	76		
01CE	3C		
01CF	47		
01D0	21	55	PICPOINTS30 DB 410, 1710, 750, 1260, 410, 1660, 750, 1260
01D1	79		
01D2	3D		
01D3	56		
01D4	21		
01D5	76		
01D6	3D		
01D7	56		
01D8	10	56 57	PICPOINTS31 DB 350, 410, 1740, 420, 1140, 420, 1710, 420, 1140, 440, 1650, 450, 1050, 660, 1570, 450, 1310
01D9	21		
01DA	7C		
01DB	22		
01DC	4C		
01DD	22		
01DE	79		
01DF	22		
01E0	4C		
01E1	24		
01E2	75		
01E3	25		
01E4	45		
01E5	36		
01E6	6F		
01E7	25		
01E8	59		
01E9	36	58	PICPOINTS32 DB 660, 1570, 460, 1140, 440, 1650, 470, 1010, 420, 1710, 550, 1230, 410, 1740, 550, 1230
01EA	6F		
01EB	26		
01EC	4C		
01ED	24		

LOC	HEX	LINE	SOURCE
01EE	75		
01EF	27		
01F0	41		
01F1	22		
01F2	79		
01F3	20		
01F4	53		
01F5	21		
01F6	70		
01F7	20		
01F8	53		
01F9	21	59	PICPOINTS33 DB 410, 1740, 420, 1140, 350, 410, 1740, 460, 1030, 660, 1570, 460, 1030
01FA	70		
01FB	22		
01FC	40		
01FD	10		
01FE	21		
01FF	70		
0200	26		
0201	43		
0202	36		
0203	6F		
0204	2E		
0205	43		
0206	10	60	PICPOINTS34 DB 340, 640, 1640, 460, 1010, 620, 1700, 460, 1010, 600, 1740, 460, 1010, 570, 1400, 460, 1010
0207	14		
0208	74		
0209	26		
020A	41		
020B	32		
020C	78		
020D	26		
020E	41		
020F	70		
0210	70		
0211	2E		
0212	41		
0213	3F		
0214	60		
0215	26		
0216	41		
0217	30	61	PICPOINTS35 DB 550, 1440, 460, 1010, 530, 1500, 460, 1010, 510, 1540, 460, 1010, 470, 1600, 460, 1010
0218	64		
0219	26		
021A	41		
021B	20		
021C	60		
021D	26		
021E	41		
021F	20		
0220	60		
0221	26		
0222	41		

LOC	OBJ	LINE	SOURCE
0223	27		
0224	70		
0225	26		
0226	41		
0227	25	62	PICPOINTS36 DB 450, 1640, 460, 1010, 430, 1700, 460, 1010, 640, 1640, 460, 1050, 620, 170 0, 460, 1050
0228	74		
0229	26		
022A	41		
022B	23		
022C	78		
022D	26		
022E	41		
022F	34		
0230	74		
0231	26		
0232	45		
0233	32		
0234	78		
0235	26		
0236	45		
0237	30	63	PICPOINTS37 DB 600, 1740, 460, 1050, 570, 1400, 460, 1050, 550, 1440, 460, 1050, 530, 150 0, 460, 1050
0238	7C		
0239	26		
023A	45		
023B	2F		
023C	60		
023D	26		
023E	45		
023F	2D		
0240	64		
0241	26		
0242	45		
0243	28		
0244	68		
0245	26		
0246	45		
0247	29	64	PICPOINTS38 DB 510, 1540, 460, 1050, 470, 1600, 460, 1050, 450, 1640, 460, 1050, 430, 170 0, 460, 1050
0248	6C		
0249	26		
024A	45		
024B	27		
024C	70		
024D	26		
024E	45		
024F	25		
0250	74		
0251	26		
0252	45		
0253	23		
0254	78		
0255	26		
0256	45		

LINE	SOURCE	DB	410, 1710, 420, 1140, 410, 1660, 420, 1140, 410, 1710, 420, 1330, 410, 166
0257 21	65 PICPOINTS39	DB	0, 420, 1330
0258 79			
0259 22			
025A 40			
025B 21			
025C 76			
025D 22			
025E 40			
025F 21			
0260 79			
0261 22			
0262 58			
0263 21			
0264 76			
0265 22			
0266 58			
0267 21	66 PICPOINTS40	DB	410, 1710, 430, 1120, 410, 1660, 430, 1120, 410, 1710, 430, 1310, 410, 166
0268 79			0, 430, 1310
0269 23			
026A 40			
026B 21			
026C 76			
026D 23			
026E 40			
026F 21			
0270 79			
0271 23			
0272 59			
0273 21			
0274 76			
0275 23			
0276 59			
0277 21	67 PICPOINTS41	DB	410, 1710, 440, 1180, 410, 1660, 440, 1180, 410, 1710, 440, 1270, 410, 166
0278 79			0, 440, 1270
0279 24			
027A 40			
027B 21			
027C 76			
027D 24			
027E 40			
027F 21			
0280 79			
0281 24			
0282 57			
0283 21			
0284 76			
0285 24			
0286 57			
0287 21	68 PICPOINTS42	DB	410, 1710, 450, 1060, 410, 1660, 450, 1060, 410, 1710, 450, 1250, 410, 166
0288 79			0, 450, 1250
0289 25			

LOC	OBJ	LINE	SOURCE
028A	46		
028B	21		
028C	76		
028D	25		
028E	46		
028F	21		
0290	79		
0291	25		
0292	55		
0293	21		
0294	76		
0295	25		
0296	55		
0297	21	69	PICPOINTS43 DB 410, 1710, 460, 1020, 410, 1660, 460, 1020, 410, 1710, 460, 1230, 410, 1660, 460, 1230
0298	79		
0299	25		
029A	42		
029B	21		
029C	76		
029D	26		
029E	42		
029F	21		
02A0	79		
02A1	26		
02A2	55		
02A3	21		
02A4	76		
02A5	26		
02A6	55		
02A7	21	70	PICPOINTS44 DB 410, 1710, 470, 1020, 410, 1660, 470, 1020, 410, 1710, 470, 1210, 410, 1660, 470, 1210
02A8	79		
02A9	27		
02AA	42		
02AB	21		
02AC	76		
02AD	27		
02AE	42		
02AF	21		
02B0	79		
02B1	27		
02B2	51		
02B3	21		
02B4	76		
02B5	27		
02B6	51		
02B7	21	71	PICPOINTS45 DB 410, 1710, 500, 1000, 410, 1660, 500, 1000, 410, 1710, 500, 1170, 410, 1660, 500, 1170
02B8	79		
02B9	28		
02BA	40		
02BB	21		
02BC	76		
02BD	28		

LOC	OBJ	LINE	SOURCE
020E	40		
020F	21		
0210	79		
0211	28		
0212	4F		
0213	21		
0214	76		
0215	28		
0216	4F		
0217	21	72	PICPOINTS46 DB 410, 1710, 500, 1360, 410, 1660, 500, 1360, 410, 1710, 510, 1150, 410, 1660, 510, 1150
0218	79		
0219	28		
021A	5E		
021B	21		
021C	76		
021D	28		
021E	5E		
021F	21		
0220	79		
0221	29		
0222	40		
0223	21		
0224	76		
0225	29		
0226	40		
0227	21	73	PICPOINTS47 DB 410, 1710, 510, 1340, 410, 1660, 510, 1340, 410, 1710, 520, 1130, 410, 1660, 520, 1130
0228	79		
0229	29		
022A	5C		
022B	21		
022C	76		
022D	29		
022E	5C		
022F	21		
0230	79		
0231	2A		
0232	4B		
0233	21		
0234	76		
0235	2A		
0236	4B		
0237	21	74	PICPOINTS48 DB 410, 1710, 520, 1320, 410, 1660, 520, 1320, 410, 1710, 530, 1110, 410, 1660, 530, 1110
0238	79		
0239	2A		
023A	5A		
023B	21		
023C	76		
023D	2A		
023E	5A		
023F	21		
0240	79		
0241	2B		

LOC	083	LINE	SOURCE
02F2	49		
02F3	21		
02F4	76		
02F5	28		
02F6	49		
02F7	21	75	PICPOINTS49 DB 410, 1710, 530, 1380, 410, 1660, 530, 1380, 410, 1710, 540, 1870, 410, 1660, 540, 1870
02F8	79		
02F9	28		
02FA	58		
02FB	21		
02FC	76		
02FD	28		
02FE	58		
02FF	21		
0300	79		
0301	20		
0302	47		
0303	21		
0304	76		
0305	20		
0306	47		
0307	21	76	PICPOINTS50 DB 410, 1710, 540, 1260, 410, 1660, 540, 1260, 410, 1710, 550, 1850, 410, 1660, 550, 1850
0308	79		
0309	20		
030A	56		
030B	21		
030C	76		
030D	20		
030E	56		
030F	21		
0310	79		
0311	20		
0312	45		
0313	21		
0314	76		
0315	20		
0316	45		
0317	21	77	PICPOINTS51 DB 410, 1710, 550, 1230, 410, 1660, 550, 1230
0318	79		
0319	20		
031A	52		
031B	21		
031C	76		
031D	20		
031E	53		
031F	10	78	PICPOINTS52 DB 350, 440, 1660, 420, 1140, 370, 580, 1250, 1280, 510, 350, 440, 1660, 580, 1240
0320	24		
0321	76		
0322	22		
0323	40		
0324	1F		
0325	28		

```

LOC OBJ          LINE    SOURCE
0326 55
0327 50
0328 29
0329 10
032A 24
032B 76
032C 28
032D 54
032E 1F          79    PICPOINTS53    DB      370, 500, 1040, 1170, 1270, 1160, 510, 150, 300
032F 28
0330 44
0331 4F
0332 57
0333 4E
0334 29
0335 00
0336 18
                                80
                                81
                                82
0337          83    LAST    LABEL    WORD
                                84
                                85    ;*****
                                86    ;                               START VERTICAL REP DATA
                                87    ;*****
                                88
                                89    ; START VERTICAL ENVELOPE
0337 10          90    VREP1      DB      350, 410, 1740, 620, 1350, 420, 1720, 620, 1350, 440, 1660, 710,
                                1170
0338 21
0339 70
033A 02
033B 50
033C 22
033D 7A
033E 70
033F 50
0340 24
0341 76
0342 39
0343 4F
0344 76          91    VREP2      DB      660, 1570, 720, 1040, 660, 1570, 720, 1260, 440, 1660, 730,
                                1130, 420, 1720, 760, 1030
0345 6F
0346 7A
0347 44
0348 76
0349 6F
034A 3A
034B 56
034C 24
034D 76
034E 3B
034F 4B
0350 22

```

LOC	OBJ	LINE	SOURCE
0351	7A		
0352	7E		
0353	47		
0354	21	92	VREP3 DB 410, 1740, 760, 1830, 410, 1740, 620, 1350, 350, 410, 1740, 720, 1150, 660, 1570, 720, 1150
0355	7C		
0356	3E		
0357	42		
0358	21		
0359	7C		
035A	32		
035B	5D		
035C	1D		
035D	21		
035E	7C		
035F	3A		
0360	4D		
0361	36		
0362	6F		
0363	3A		
0364	4D		
		93	END VERT ENVELOPE
		94	START WORDS "UP, DOWN" ON RIGHT SIDE OF SCREEN
0365	1D	95	VREP4 DB 350, 440, 1660, 750, 1210, 370, 580, 1250, 1280, 510, 350, 440, 1660, 650, 1340, 370, 580, 1040, 1170, 1270, 1160, 510
0366	24		
0367	76		
0368	3D		
0369	51		
036A	1F		
036B	28		
036C	55		
036D	5D		
036E	29		
036F	1D		
0370	24		
0371	76		
0372	35		
0373	5C		
0374	1F		
0375	28		
0376	44		
0377	4F		
0378	57		
0379	4E		
037A	29		
		96	END
		97	START VERTICAL REP MIL TICS
037B	1C	98	VREP5 DB 340, 410, 1710, 620, 1350, 410, 1660, 620, 1350, 410, 1710, 630, 1140, 410, 1660
037C	21		
037D	79		
037E	32		
037F	5D		
0380	21		

LOC	OBJ	LINE	SOURCE
0381	76		
0382	32		
0383	50		
0384	21		
0385	79		
0386	33		
0387	40		
0388	21		
0389	76		
038A	33	99	VREP5 DB 630, 1140, 410, 1710, 630, 1330, 410, 1660, 630, 1330
038B	40		
038C	21		
038D	79		
038E	33		
038F	58		
0390	21		
0391	76		
0392	33		
0393	58		
0394	21	100	VREP6 DB 410, 1710, 640, 1120, 410, 1660, 640, 1120, 410, 1710, 640, 1310, 410, 1660, 640, 1310
0395	79		
0396	34		
0397	4A		
0398	21		
0399	76		
039A	34		
039B	4A		
039C	21		
039D	79		
039E	34		
039F	59		
03A0	21		
03A1	76		
03A2	34		
03A3	59		
03A4	21	101	VREP7 DB 410, 1710, 650, 1160, 410, 1660, 650, 1160, 410, 1710, 650, 1270, 410, 1660, 650, 1270
03A5	79		
03A6	35		
03A7	48		
03A8	21		
03A9	76		
03AA	35		
03AB	48		
03AC	21		
03AD	79		
03AE	35		
03AF	57		
03B0	21		
03B1	76		
03B2	35		
03B3	57		
03B4	21	102	VREP8 DB 410, 1710, 660, 1060, 410, 1660, 660, 1060, 410, 1710, 660, 1250, 410, 1660, 660, 1250

LOC	OBJ	LINE	SOURCE
0385	79		
0386	36		
0387	46		
0388	21		
0389	76		
038A	36		
038B	46		
038C	21		
038D	79		
038E	36		
038F	55		
03C0	21		
03C1	76		
03C2	36		
03C3	55		
03C4	21	103	VREP9 DB 410, 1710, 670, 1040, 410, 1660, 670, 1040, 410, 1710, 670, 1230, 410, 1660, 670, 1230
03C5	79		
03C6	37		
03C7	44		
03C8	21		
03C9	76		
03CA	37		
03CB	44		
03CC	21		
03CD	79		
03CE	37		
03CF	53		
03D0	21		
03D1	76		
03D2	37		
03D3	53		
03D4	21	104	VREP10 DB 410, 1710, 700, 1020, 410, 1660, 700, 1020, 410, 1710, 700, 1210, 410, 1660, 700, 1210
03D5	79		
03D6	38		
03D7	42		
03D8	21		
03D9	76		
03DA	38		
03DB	42		
03DC	21		
03DD	79		
03DE	38		
03DF	51		
03E0	21		
03E1	76		
03E2	38		
03E3	51		
03E4	21	105	VREP11 DB 410, 1710, 710, 1000, 410, 1660, 710, 1000, 410, 1710, 710, 1170, 410, 1660, 710, 1170
03E5	79		
03E6	39		
03E7	40		
03E8	21		

LOC	OBJ	LINE	SOURCE
03E9	76		
03EA	39		
03EB	40		
03EC	21		
03ED	79		
03EE	39		
03EF	4F		
03F0	21		
03F1	76		
03F2	39		
03F3	4F		
03F4	21	106	VREP12 DB 410, 1710, 710, 1360, 410, 1660, 710, 1360, 410, 1710, 720, 1150, 410, 1660, 720, 1150
03F5	79		
03F6	39		
03F7	5E		
03F8	21		
03F9	76		
03FA	39		
03FB	5E		
03FC	21		
03FD	79		
03FE	3A		
03FF	4D		
0400	21		
0401	76		
0402	3A		
0403	4D		
0404	21	107	VREP13 DB 410, 1710, 720, 1340, 410, 1660, 720, 1340, 410, 1710, 730, 1130, 410, 1660, 730, 1130
0405	79		
0406	3A		
0407	5C		
0408	21		
0409	76		
040A	3A		
040B	5C		
040C	21		
040D	79		
040E	3B		
040F	4B		
0410	21		
0411	76		
0412	3B		
0413	4B		
0414	21	108	VREP14 DB 410, 1710, 730, 1320, 410, 1660, 730, 1320, 410, 1710, 740, 1110, 410, 1660, 740, 1110
0415	79		
0416	3B		
0417	5A		
0418	21		
0419	76		
041A	3B		
041B	5A		
041C	21		

LINE	SOURCE
0410 79	
0411 70	
041F 49	
0410 21	
0421 76	
0412 70	
0421 49	
0424 21	109 VREP15 DB 410, 1710, 740, 1300, 410, 1660, 740, 1300, 410, 1710, 750, 1670
0425 79	
0426 70	
0427 50	
0428 21	
0429 76	
042A 30	
0418 58	
0420 31	
0420 79	
042E 30	
042F 47	
0430 21	110 VREP05 DB 410, 1660, 750, 1670, 410, 1710, 750, 1660, 410, 1660, 750, 1260
0431 76	
0432 30	
0433 47	
0434 21	
0435 79	
0436 30	
0437 56	
0438 21	
0439 76	
043A 30	
043B 56	
111	END
112	START TIME TICS
04 C 10	113 VREP16 DB 340, 640, 1640, 720, 1130, 620, 1700, 720, 1130, 600, 1740, 720, 1130, 570, 1400, 720, 1130
043D 74	
043E 74	
043F 3A	
0440 4F	
0441 10	
0442 78	
0443 7A	
0444 4B	
0445 30	
0446 70	
0447 3A	
0448 4B	
0449 2F	
044A 30	
044B 7A	
044C 4E	
044D 30	114 VREP17 DB 550, 1440, 720, 1130, 530, 1500, 720, 1130, 510, 1540, 720, 1130, 470, 1600, 720, 1130
044E 64	
044F 3A	

LINE	SOURCE	DB	DB
0450 4F			
0451 2B			
0452 6A			
0453 7A			
0454 4B			
0455 29			
0456 6F			
0457 7A			
0458 4B			
0459 27			
045A 7A			
045B 3A			
045C 4B			
045D 25	115 VREF18	08	450, 1640, 720, 1130, 430, 1700, 720, 1130, 640, 1640, 720, 1170, 620, 1700, 720, 1170
045E 74			
045F 3A			
0460 4B			
0461 27			
0462 7B			
0463 3A			
0464 4B			
0465 24			
0466 74			
0467 7A			
0468 4F			
0469 72			
046A 7B			
046B 7A			
046C 4F			
046D 3A	116 VREF19	08	600, 1740, 720, 1170, 570, 1400, 720, 1170, 550, 1440, 720, 1170, 530, 1500, 720, 1170
046E 7C			
046F 3A			
0470 4F			
0471 2F			
0472 6A			
0473 74			
0474 4F			
0475 2D			
0476 64			
0477 29			
0478 4F			
0479 2B			
047A 6B			
047B 3A			
047C 4F			
047D 29	117 VREF20	08	510, 1540, 720, 1170, 470, 1600, 720, 1170, 450, 1640, 720, 1170, 430, 1700, 720, 1170
047E 6F			
047F 3A			
0480 4F			
0481 27			
0482 7B			
0483 3A			

LINE	SOURCE
0484	4F
0485	2F
0486	74
0487	3A
0488	4F
0489	23
048A	72
048B	3A
048C	4F
118	.END
119	; START "TIME-SEC ARROW"
048D	1D
120	VREP21 DB 350, 570, 1640, 560, 1140, 370, 1240, 350, 560, 1660, 560, 1140, 370, 1110, 350, 550, 1700, 560, 1140, 370, 1150
048E	2F
048F	74
0490	2E
0491	4C
0492	1F
0493	54
0494	1D
0495	2E
0496	76
0497	2E
0498	4C
0499	1F
049A	44
049B	1D
049C	2D
049D	78
049E	2E
049F	4C
04A0	1F
04A1	4D
04A2	1D
121	VREP22 DB 350, 540, 1720, 560, 1140, 370, 1050, 350, 520, 1760, 560, 1140
04A3	2C
04A4	7A
04A5	2E
04A6	4C
04A7	1F
04A8	45
04A9	1D
04AA	2A
04AB	74
04AC	2E
04AD	4C
04AE	1F
122	VREP02 DB 370, 1230, 350, 520, 1400, 560, 1140, 370, 1050, 350, 510, 1420
04AF	53
04B0	1D
04B1	2A
04B2	4A
04B3	2E
04B4	4C
04B5	1F
04B6	4F
04B7	1D

LOC	OBJ	LINE	SOURCE
04B8	29		
04B9	62		
04BA	2E	123	VREP23 DB 560, 1140, 370, 1030
04BB	4F		
04BC	1F		
04BD	47		
04BE	1D	124	VREF24 DB 350, 610, 1770, 560, 1220, 630, 1440, 560, 1220, 620, 1660, 560
04BF	71		
04C0	7F		
04C1	2E		
04C2	52		
04C3	33		
04C4	64		
04C5	2E		
04C6	52		
04C7	32		
04C8	76		
04C9	2E		
04CA	58	125	VREP04 DB 1300, 350, 620, 1660, 560, 1140, 630, 1440, 560, 1220
04CB	1D		
04CC	32		
04CD	76		
04CE	2E		
04CF	4C		
04D0	32		
04D1	64		
04D2	2E		
04D3	52		
		126	:END
		127	:START LEFT ENVELOPE
04D4	1D	128	VREP25 DB 350, 410, 1740, 560, 1110, 410, 1740, 420, 1000, 660, 1570, 420, 1000
04D5	71		
04D6	7C		
04D7	2E		
04D8	43		
04D9	21		
04DA	7C		
04DB	22		
04DC	40		
04DD	36		
04DE	6F		
04DF	22		
04E0	40		
		129	:END
		130	:START "MISSILE ABOVE GROUND (FEET)"
04E1	1D	131	VREF26 DB 350, 400, 1760, 420, 1100, 370, 1150, 1110, 1230, 1230, 1110, 1140, 1050, 400, 1010, 1020, 1170, 1260, 1050
04E2	20		
04E3	7E		
04E4	22		
04E5	48		
04E6	1F		
04E7	4D		
04E8	49		

LINE	DB	SOURCE
04E9 50		
04E9 50		
04EB 43		
04EC 40		
04ED 45		
04EE 28		
04EF 41		
04F0 42		
04F1 4F		
04F2 56		
04F3 45		
04F4 28	132	VREP06 DB 480, 1870, 1220, 1170, 1250, 1160, 1040, 480, 580, 1060, 1850, 1050, 1240, 510, 350
04F5 47		
04F6 52		
04F7 4F		
04F8 55		
04F9 4E		
04FA 44		
04FB 28		
04FC 28		
04FD 46		
04FE 45		
04FF 45		
0500 54		
0501 23		
0502 10		
	133	.END
	134	.START "GROUND LEVEL"
0503 10	135	VREP06 DB 350, 630, 1440, 410, 1180, 370, 1870, 350, 620, 1460, 410, 1180, 370, 1220, 350, 610, 1580, 410, 1180, 370, 1170
0504 33		
0505 64		
0506 21		
0507 48		
0508 1F		
0509 47		
050A 10		
050B 32		
050C 66		
050D 21		
050E 48		
050F 1F		
0510 52		
0511 10		
0512 31		
0513 68		
0514 21		
0515 48		
0516 1F		
0517 4F		
0518 10	136	VREP27 DB 350, 680, 1520, 410, 1180, 370, 1250, 350, 570, 1540, 410, 1180, 370, 1160, 350, 560, 1560, 410, 1180, 370, 1040
0519 38		
051A 6A		

LOC	OBJ	LINE	SOURCE
051E	21		
051G	48		
051H	1F		
051E	55		
051F	10		
0520	2F		
0521	6C		
0522	21		
0523	48		
0524	1F		
0525	4E		
0526	10		
0527	2E		
0528	6E		
0529	21		
052A	48		
052B	1F		
052C	44		
052D	10	137	VREP28 DB 350, 540, 1620, 410, 1100, 370, 1140, 350, 530, 1640, 410, 1100, 370, 1050, 350, 520, 1660, 410, 1100, 370, 1260
052E	2C		
052F	72		
0530	21		
0531	48		
0532	1F		
0533	4C		
0534	10		
0535	28		
0536	74		
0537	21		
0538	48		
0539	1F		
053A	45		
053B	10		
053C	2A		
053D	76		
053E	21		
053F	48		
0540	1F		
0541	56		
0542	10	138	VREP29 DB 350, 510, 1700, 410, 1100, 370, 1050, 350, 580, 1720, 410, 1100, 370, 1140
0543	29		
0544	71		
0545	21		
0546	48		
0547	1F		
0548	45		
0549	10		
054A	28		
054B	7A		
054C	21		
054D	48		
054E	1F		
054F	4C		

LOC	081	LINE	SOURCE
		139	END
		140	START "FEET TICS"
0550	11	141	VREP30 DB 340, 410, 1710, 420, 1000, 410, 1660, 420, 1000, 410, 1710, 430, 1140, 410, 1660, 430, 1140
0551	21		
0552	79		
0553	22		
0554	40		
0555	21		
0556	76		
0557	22		
0558	40		
0559	21		
055A	79		
055B	23		
055C	40		
055D	21		
055E	76		
055F	23		
0560	40		
0561	21	142	VREP31 DB 410, 1710, 440, 1270, 410, 1660, 440, 1270, 410, 1710, 460, 1830, 410, 1660, 460, 1830
0562	79		
0563	24		
0564	57		
0565	21		
0566	76		
0567	24		
0568	57		
0569	21		
056A	79		
056B	26		
056C	40		
056D	21		
056E	76		
056F	26		
0570	40		
0571	21	143	VREP32 DB 410, 1710, 470, 1170, 410, 1660, 470, 1170, 410, 1710, 500, 1320, 410, 1660, 500, 1320
0572	79		
0573	27		
0574	4F		
0575	21		
0576	76		
0577	27		
0578	4F		
0579	21		
057A	79		
057B	28		
057C	5A		
057D	21		
057E	76		
057F	28		
0580	5A		
0581	21	144	VREP33 DB 410, 1710, 520, 1060, 410, 1660, 520, 1060, 410, 1710, 530, 1220,

LOC	OFF	LINE	SOURCE
			410, 1660, 530, 1220
0562	27		
0563	2A		
0564	46		
0565	21		
0566	76		
0567	2A		
0568	46		
0569	21		
056A	79		
056B	2B		
056C	52		
056D	21		
056E	76		
056F	2B		
0560	52		
0591	21	145	VREP34 DB 410, 1710, 540, 1350, 410, 1660, 540, 1350, 410, 1710, 560, 1110, 410, 1660, 560, 1110
0592	79		
0593	2C		
0594	50		
0595	21		
0596	76		
0597	2C		
0598	50		
0599	21		
059A	79		
059B	2E		
059C	49		
059D	21		
059E	76		
059F	2E		
05A0	49		
		146	
		147	*****
		148	THESE NEXT DATA ARE FOR HORIZONTAL REPRIESE
		149	*****
		150	
		151	END
		152	START "0 AND 3"
05A1	10	153	VREP35 DB 350, 420, 1410, 420, 1120, 370, 600, 350, 420, 1410, 460, 1030, 370, 630
05A2	22		
05A3	61		
05A4	22		
05A5	4A		
05A6	1F		
05A7	30		
05A8	11		
05A9	22		
05AA	61		
05AB	26		
05AC	43		
05AD	1F		
05AE	33		

```

001 001      LINE      SOURCE
                                154      .END
                                155      .START "GUNNER AIMING ERROR (MILS)"
002 002      156      VREP36      DB      350, 400, 1760, 620, 1350, 370, 1070, 1250, 1160, 1160, 1050, 1220,
                                400, 1010, 1110, 1150, 1110, 1160, 1070, 400, 1050
003 003      0580 20
004 004      0581 7F
005 005      0582 32
006 006      0583 50
007 007      0584 1F
008 008      0585 47
009 009      0586 75
010 010      0587 4E
011 011      0588 4E
012 012      0589 45
013 013      058A 52
014 014      058B 20
015 015      058C 41
016 016      058D 49
017 017      058E 40
018 018      058F 49
019 019      0590 4E
020 020      0591 47
021 021      0592 20
022 022      0593 45
023 023      0594 52      157      VREP37      DB      1220, 1220, 1170, 1220, 400, 500, 1150, 1110, 1140, 1230, 510, 350
024 024      0595 52
025 025      0596 4F
026 026      0597 52
027 027      0598 20
028 028      0599 28
029 029      059A 40
030 030      059B 49
031 031      059C 40
032 032      059D 75
033 033      059E 27
034 034      059F 10
                                158      .END
                                159
035 035      05C0      160      LAST_OF_VREP      LABEL      WORD
                                161
                                162      .START HORIZONTAL GAE ENVELOPE
                                163
036 036      05C1      164      HREP      DB      350, 410, 1740, 570, 1240, 430, 1540, 570, 1240, 440, 1440, 0650, 1270
037 037      05C2 10
038 038      05C3 21
039 039      05C4 7C
040 040      05C5 2F
041 041      05C6 54
042 042      05C7 23
043 043      05C8 6C
044 044      05C9 2F
045 045      05CA 54
046 046      05CB 24
047 047      05CC 64
048 048      05CD 35
049 049      05CE 57

```

LOC	OBJ	LINE	SOURCE
0500	36	165	HREP1 DB 0660, 1570, 0660, 1120, 0660, 1570, 0660, 1360, 440, 1440, 0670, 1230, 430, 1540, 0750, 1260, 410
050E	6F		
050F	36		
05E0	4A		
05E1	36		
05E2	6F		
05E3	36		
05E4	5E		
05E5	24		
05E6	64		
05E7	37		
05E8	53		
05E9	23		
05EA	6C		
05EB	3D		
05EC	56		
05ED	21		
05EE	7C	166	HREP2 DB 1740, 0750, 1260, 410, 1740, 570, 1240, 0350, 410, 1740, 0660, 1250, 0660, 1570, 0660
05EF	3D		
05F0	56		
05F1	21		
05F2	7C		
05F3	2F		
05F4	54		
05F5	1D		
05F6	21		
05F7	7C		
05F8	36		
05F9	55		
05FA	36		
05FB	6F		
05FC	36		
		167	END
		168	START TIME TICS
05FD	55	169	HREP3 DB 1250, 340, 640, 1640, 660, 1230, 620, 1700, 660, 1230, 600, 1740, 660, 1230, 570, 1400, 660, 1230, 550, 1440, 660, 1230, 530
05FE	1C		
05FF	34		
0600	74		
0601	36		
0602	53		
0603	12		
0604	78		
0605	36		
0606	53		
0607	30		
0608	7C		
0609	36		
060A	53		
060B	2F		
060C	60		
060D	36		
060E	57		

LOC	OBJ	LINE	SOURCE
060F	20		
0610	64		
0611	36		
0612	53		
0613	28		
0614	68	170	HREP4 DB 1500, 660, 1230, 510, 1540, 660, 1230, 470, 1600, 660, 1230, 450, 1640, 660, 1230, 430, 1700, 660, 1230, 640, 1640, 660
0615	36		
0616	53		
0617	29		
0618	60		
0619	36		
061A	53		
061B	27		
061C	70		
061D	36		
061E	53		
061F	25		
0620	74		
0621	36		
0622	53		
0623	23		
0624	78		
0625	36		
0626	53		
0627	34		
0628	74		
0629	36		
062A	57	171	HREP5 DB 1270, 620, 1700, 660
062B	32		
062C	78		
062D	36		
062E	57	172	HREP6 DB 1270, 600, 1740, 660, 1270, 570, 1400, 660, 1270, 550, 1440, 660, 1270, 530, 1500, 660, 1270, 510
062F	30		
0630	70		
0631	36		
0632	57		
0633	2F		
0634	60		
0635	36		
0636	57		
0637	20		
0638	64		
0639	36		
063A	57		
063B	28		
063C	68		
063D	36		
063E	57		
063F	29		
0640	60	173	HREP7 DB 1540, 660, 1270, 470, 1600, 660, 1270
0641	36		
0642	57		
0643	27		

LOC	HEX	LINE	SOURCE
0644	70		
0645	16		
0646	57		
		174	.END SOMEWHERE NEAR HERE
		175	.START ARROW
0647	25	176	HREP8 DB 450, 1640, 660, 1270, 430, 1700, 660, 1270, 350, 570, 1640, 560, 1140, 370, 1240
0648	74		
0649	16		
064A	57		
064B	25		
064C	70		
064D	36		
064E	57		
064F	1D		
0650	2F		
0651	74		
0652	1E		
0653	4C		
0654	1F		
0655	54		
0656	1D	177	HREP9 DB 350, 560, 1660, 560, 1140, 370, 1110, 350, 550, 1700, 560, 1140, 370, 1150
0657	2E		
0658	76		
0659	2E		
065A	4C		
065B	1F		
065C	49		
065D	1D		
065E	2D		
065F	78		
0660	2E		
0661	4C		
0662	1F		
0663	4D		
0664	1D	178	HREP10 DB 350, 540, 1720, 560, 1140, 370, 1050, 350, 520, 1760, 560, 1140, 370, 1220, 350, 520, 1400, 560, 1140
0665	2C		
0666	7A		
0667	2E		
0668	4C		
0669	1F		
066A	45		
066B	1D		
066C	2A		
066D	7E		
066E	2E		
066F	4C		
0670	1F		
0671	53		
0672	1D		
0673	2A		
0674	60		
0675	2E		
0676	4C		
0677	1F	179	HREP11 DB 370, 1050, 350, 510, 1420, 560, 1140, 370, 1030, 350, 610, 1770, 560, 1220, 630, 144

LOC	06/	LINE	SOURCE
			0, 560, 1220
0678	45		
0679	10		
067A	29		
067B	62		
067C	2E		
067D	4C		
067E	1F		
067F	43		
0680	1D		
0681	31		
0682	7F		
0683	2E		
0684	52		
0685	33		
0686	64		
0687	2E		
0688	52		
0689	32	180	HREP12 DB 620, 1660, 560, 1300, 350, 620, 1660, 560, 1140, 630, 1440, 560, 1220
068A	76		
068B	2E		
068C	58		
068D	10		
068E	32		
068F	76		
0690	2E		
0691	4C		
0692	33		
0693	64		
0694	2E		
0695	52		
0696	10	181	HREP13 DB 350, 440, 1660, 570, 1240, 370, 500, 1140, 1050, 1060, 1240, 510, 350, 440, 1660, 71 0, 1310
0697	24		
0698	76		
0699	2F		
069A	54		
069B	1F		
069C	28		
069D	4C		
069E	45		
069F	46		
06A0	54		
06A1	29		
06A2	10		
06A3	24		
06A4	76		
06A5	39		
06A6	59		
06A7	1F	182	HREP14 DB 370, 500, 1220, 1110, 1070, 1100, 1240, 510
06A8	28		
06A9	52		
06AA	49		
06AB	47		
06AC	48		

LOC	OBJ	LINE	SOURCE
0680	54		
068E	29		
		183	END
		184	START MIL TICS
068F	10	185	HREP15 DB 340, 410, 1710, 570, 1240, 410, 1660, 570, 1240, 410, 1710, 600, 1830, 410, 1660, 600, 1830
0680	21		
0681	79		
0682	2F		
0683	54		
0684	21		
0685	76		
0686	2F		
0687	54		
0688	21		
0689	79		
068A	30		
068B	43		
068C	21		
068D	76		
068E	30		
068F	43		
06C0	21	186	HREP16 DB 410, 1710, 600, 1220, 410, 1660, 600, 1220, 410, 1710, 610, 1810, 410, 1660, 610, 1810
06C1	79		
06C2	30		
06C3	52		
06C4	21		
06C5	76		
06C6	30		
06C7	52		
06C8	21		
06C9	79		
06CA	31		
06CB	41		
06CC	21		
06CD	76		
06CE	31		
06CF	41		
06D0	21	187	HREP17 DB 410, 1710, 610, 1200, 410, 1660, 610, 1200, 410, 1710, 610, 1370, 410, 1660, 610, 1370
06D1	79		
06D2	31		
06D3	50		
06D4	21		
06D5	76		
06D6	31		
06D7	50		
06D8	21		
06D9	79		
06DA	31		
06DB	5F		
06DC	21		
06DD	76		
06DE	31		

LOC	OBJ	LINE	SOURCE
06DF	5F		
06E0	21	188	HREP18 DB 410, 1710, 620, 1160, 410, 1660, 620, 1160, 410, 1710, 620, 1350, 410, 1660, 620, 1350
06E1	79		
06E2	32		
06E3	4E		
06E4	21		
06E5	76		
06E6	32		
06E7	4E		
06E8	21		
06E9	79		
06EA	32		
06EB	5D		
06EC	21		
06ED	76		
06EE	32		
06EF	5D		
06F0	21	189	HREP19 DB 410, 1710, 630, 1140, 410, 1660, 630, 1140, 410, 1710, 630, 1330, 410, 1660, 630, 1330
06F1	79		
06F2	33		
06F3	4C		
06F4	21		
06F5	76		
06F6	33		
06F7	4C		
06F8	21		
06F9	79		
06FA	33		
06FB	5B		
06FC	21		
06FD	76		
06FE	33		
06FF	5B		
0700	21	190	HREP20 DB 410, 1710, 640, 1120, 410, 1660, 640, 1120, 410, 1710, 640, 1310, 410, 1660, 640, 1310
0701	79		
0702	34		
0703	4A		
0704	21		
0705	76		
0706	34		
0707	4A		
0708	21		
0709	79		
070A	34		
070B	59		
070C	21		
070D	76		
070E	34		
070F	59		
0710	21	191	HREP21 DB 410, 1710, 650, 1100, 410, 1660, 650, 1100, 410, 1710, 650, 1270, 410, 1660, 650, 1270
0711	79		

LOC	OBJ	LINE	SOURCE
0712	35		
0713	48		
0714	21		
0715	76		
0716	35		
0717	48		
0718	21		
0719	79		
071A	35		
071B	57		
071C	21		
071D	76		
071E	35		
071F	57		
0720	21	192	HREP22 DB 410, 1710, 660, 1060, 410, 1660, 660, 1060, 410, 1710, 660, 1250, 410, 1660, 660, 12
			50
0721	79		
0722	36		
0723	46		
0724	21		
0725	76		
0726	36		
0727	46		
0728	21		
0729	79		
072A	36		
072B	55		
072C	21		
072D	76		
072E	36		
072F	55		
0730	21	193	HREP23 DB 410, 1710, 670, 1040, 410, 1660, 670, 1040, 410, 1710, 670, 1230, 410, 1660, 670, 12
			30
0731	79		
0732	37		
0733	44		
0734	21		
0735	76		
0736	37		
0737	44		
0738	21		
0739	79		
073A	57		
073B	53		
073C	21		
073D	76		
073E	57		
073F	57		
0740	21	194	HREP24 DB 410, 1710, 700, 1020, 410, 1660, 700, 1020, 410, 1710, 700, 1210, 410, 1660, 700, 12
			10
0741	79		
0742	38		
0743	42		
0744	21		
0745	76		

LOC	OBJ	LINE	SOURCE
0746	38		
0747	42		
0748	21		
0749	79		
074A	38		
074B	51		
074C	21		
074D	76		
074E	38		
074F	51		
0750	21	195	HREP25 DB 410, 1710, 710, 1000, 410, 1660, 710, 1000, 410, 1710, 710, 1170, 410, 1660, 710, 1170
0751	79		
0752	39		
0753	40		
0754	21		
0755	76		
0756	39		
0757	40		
0758	21		
0759	79		
075A	39		
075B	4F		
075C	21		
075D	76		
075E	39		
075F	4F		
0760	21	196	HREP26 DB 410, 1710, 710, 1360, 410, 1660, 710, 1360, 410, 1710, 720, 1150, 410, 1660, 720, 1150
0761	79		
0762	39		
0763	5E		
0764	21		
0765	76		
0766	39		
0767	5E		
0768	21		
0769	79		
076A	3A		
076B	40		
076C	21		
076D	7F		
076E	3A		
076F	40		
0770	21	197	HREP27 DB 410, 1710, 720, 1340, 410, 1660, 720, 1340, 410, 1710, 730, 1130, 410, 1660, 730, 1130
0771	79		
0772	3A		
0773	5C		
0774	21		
0775	76		
0776	3A		
0777	5C		
0778	21		
0779	79		

LINE	SOURCE
0774 3B	
077B 4B	
077C 21	
077D 76	
077E 3B	
077F 4B	
0780 21	198 HREP28 DB 410, 1710, 730, 1320, 410, 1660, 730, 1320, 410, 1710, 740, 1110, 410, 1660, 740, 1110
0781 79	
0782 3B	
0783 5A	
0784 21	
0785 76	
0786 3B	
0787 5A	
0788 21	
0789 79	
078A 3C	
078B 49	
078C 21	
078D 76	
078E 3C	
078F 49	
0790 21	199 HREP29 DB 410, 1710, 740, 1300, 410, 1660, 740, 1300, 410, 1710, 750, 1070, 410, 1660, 750, 1070
0791 79	
0792 3C	
0793 5B	
0794 21	
0795 76	
0796 3C	
0797 5B	
0798 21	
0799 79	
079A 3D	
079B 47	
079C 21	
079D 76	
079E 3D	
079F 47	
07A0 21	200 HREP30 DB 410, 1710, 750, 1260, 410, 1660, 750, 1260
07A1 79	
07A2 3D	
07A3 56	
07A4 21	
07A5 76	
07A6 3D	
07A7 56	
201	END MIL TICS
202	
203	START "GUNNER AIMING ERROR (MILS)"
07A8 1F	204 HREP31 DB 350, 400, 1760, 600, 1220, 370, 1070, 1250, 1160, 1160, 1050, 1220, 400, 1010, 1110, 1150, 1110, 1160, 1070, 400, 1050
07A9 20	
07AA 7E	

LOC	OBJ	LINE	SOURCE
07AB	30		
07AC	52		
07AD	1F		
07AE	47		
07AF	55		
07B0	4E		
07B1	4E		
07B2	45		
07B3	52		
07B4	20		
07B5	41		
07B6	49		
07B7	40		
07B8	49		
07B9	4E		
07BA	47		
07BB	20		
07BC	45		
07BD	52	205	HREP32 DB 1220, 1220, 1170, 1220, 400, 500, 1150, 1110, 1140, 1230, 510, 350
07BE	52		
07BF	4F		
07C0	52		
07C1	20		
07C2	28		
07C3	40		
07C4	49		
07C5	40		
07C6	53		
07C7	29		
07C8	1D		
		206	; END
		207	
		208	; START "FEET TICS"
07C9	1C	209	HREP33 DB 340, 410, 1710, 420, 1000, 410, 1660, 420, 1000, 410, 1710, 430, 1140, 410, 1660, 430, 1140
07CA	21		
07CB	79		
07CC	22		
07CD	40		
07CE	21		
07CF	76		
07D0	22		
07D1	40		
07D2	21		
07D3	79		
07D4	23		
07D5	40		
07D6	21		
07D7	76		
07D8	23		
07D9	40		
07DA	21	210	HREP34 DB 410, 1710, 440, 1270, 410, 1660, 440, 1270, 410, 1710, 460, 1030, 410, 1660, 460, 1030
07DB	79		
07DC	24		

LOC	DB1	LINE	SOURCE
0700	57		
070E	21		
070F	76		
07E0	24		
07E1	57		
07E2	21		
07E3	79		
07E4	26		
07E5	43		
07E6	21		
07E7	76		
07E8	26		
07E9	43		
07EA	21	211	HREP35 DB 410, 1710, 470, 1170, 410, 1660, 470, 1170, 410, 1710, 580, 1320, 410, 1660, 580, 1320
07EB	79		
07EC	27		
07ED	4F		
07EE	21		
07EF	76		
07F0	27		
07F1	4F		
07F2	21		
07F3	79		
07F4	28		
07F5	5A		
07F6	21		
07F7	76		
07F8	28		
07F9	5A		
07FA	21	212	HREP36 DB 410, 1710, 520, 1060, 410, 1660, 520, 1060, 410, 1710, 530, 1220, 410, 1660, 530, 1220
07FB	79		
07FC	2A		
07FD	46		
07FE	21		
07FF	76		
0800	2A		
0801	46		
0802	21		
0803	79		
0804	28		
0805	52		
0806	21		
0807	76		
0808	28		
0809	52		
080A	21	213	HREP37 DB 410, 1710, 540, 1350, 410, 1660, 540, 1350
080B	79		
080C	2C		
080D	50		
080E	21		
080F	76		
0810	2C		
0811	50		

LOC	OBJ	LINE	SOURCE
		214	:END
		215	
		216	:START LEFT ENVELOPE
		217	
0012	10	218	HREP38 DB 350, 410, 1740, 540, 1350, 410, 1740, 420, 1000, 350, 410, 1740, 470, 1170, 660, 1570, 470, 1170
0013	21		
0014	7C		
0015	2C		
0016	50		
0017	21		
0018	7C		
0019	22		
001A	40		
001B	10		
001C	21		
001D	7C		
001E	27		
001F	4F		
0020	36		
0021	6F		
0022	27		
0023	4F		
		219	:END
		220	:START "TARGET LINE"
0024	10	221	HREP38 DB 350, 640, 1520, 460, 1270, 370, 1240, 350, 630, 1540, 460, 1270, 370, 1010, 350, 620, 1600, 460, 1270, 370, 1220
0025	34		
0026	6A		
0027	26		
0028	57		
0029	1F		
002A	54		
002B	1C		
002C	32		
002D	6C		
002E	26		
002F	57		
0030	1F		
0031	41		
0032	10		
0033	32		
0034	70		
0035	26		
0036	57		
0037	1F		
0038	52		
0039	10	222	HREP39 DB 350, 610, 1600, 460, 1270, 370, 1070, 350, 600, 1620, 460, 1270, 370, 1050, 350, 570, 1640, 460, 1270, 370, 1240
003A	31		
003B	70		
003C	26		
003D	57		
003E	1F		
003F	47		

LOC	OBJ	LINE	SOURCE
0040	10		
0041	20		
0042	72		
0043	26		
0044	57		
0045	1F		
0046	45		
0047	10		
0048	2F		
0049	74		
004A	26		
004B	57		
004C	1F		
004D	54		
004E	10	223	HREP40 DB 350, 630, 1540, 470, 1320, 370, 1140, 350, 620, 1600, 470, 1320, 370, 1110, 350, 610, 1600, 470, 1320, 370, 1160
004F	33		
0050	6C		
0051	27		
0052	5A		
0053	1F		
0054	4C		
0055	10		
0056	32		
0057	70		
0058	27		
0059	5A		
005A	1F		
005B	49		
005C	10		
005D	31		
005E	70		
005F	27		
0060	5A		
0061	1F		
0062	4E		
0063	10	224	HREP41 DB 350, 600, 1620, 470, 1320, 370, 1050
0064	30		
0065	72		
0066	27		
0067	5A		
0068	1F		
0069	45		
		225	END
		226	START "(FEET)"
		227	
006A	10	228	HREP42 DB 350, 400, 1760, 460, 1150, 370, 500, 1060, 1050, 1050, 1240, 510
006B	20		
006C	7E		
006D	26		
006E	40		
006F	1F		
0070	28		
0071	46		
0072	45		


```

0007 0B/
0873 45
0874 54
0875 29
229 :END
230 :START "(LEFT),(RIGHT)"
0876 10 231 HREP43 DB 350,440,1660,420,1000,370,500,1140,1050,1060,1240,510,
350,440,1660,520,1060,370,500,1220,1110
0877 24
0878 76
0879 22
087A 40
087B 1F
087C 28
087D 4C
087E 45
087F 46
0880 54
0881 29
0882 10
0883 24
0884 76
0885 2A
0886 46
0887 1F
0888 28
0889 52
088A 49
232 HREP44 DB 1070,1100,1240,510,350
088B 47
088C 48
088D 54
088E 29
088F 10
233
0890 234 LAST_OF_HREP LABEL WORD
235
236
0890 E8600 237 GRAPH1 CALL CLEAR_SCREEN
238
0893 BE000 R 239 GRAPH MOV SI,OFFSET PICPOINTS
0896 B93703 240 MOV CX,(OFFSET LAST-OFFSET PICPOINTS)
0899 BAD000 241 MOV DX,008H
089C 2E8A04 242 AGAIN: MOV AL,CS:[SI]
089F E86400 243 CALL COUT
08A2 46 244 INC SI
08A3 E88A00 245 CALL DELAY_2
08A6 E2F4 246 LOOP AGAIN
08A8 C3 247 RET
248
08A9 E86D00 249 GRAPH_VREP: CALL CLEAR_SCREEN
08AC BE3703 R 250 MOV SI,OFFSET VREP1
08AF B99902 251 MOV CX,(OFFSET LAST_OF_VREP-OFFSET VREP1)
08B2 BAD900 252 MOV DX,008H
08B5 2E8A04 253 AGN_L_AGN MOV AL,CS:[SI]
08B8 E84000 254 CALL COUT
08BE 46 255 INC SI

```


LOC	OBJ	LINE	SOURCE		
091E	E8E5FF	311		CALL	COUT
0921	B019	312		MOV	AL,310
0923	F8E0FF	313		CALL	COUT
0926	E81100	314		CALL	DELAY_3 THE CLEAR SCREEN MODE TAKES
		315			160MS TO COMPLETE
0929	C3	316		RET	
		317			
092A	B90300	318	DELAY:	MOV	CX,3
092D	E2FE	319	TAG:	LOOP	TAG
092F	C3	320		RET	
		321			
0930	B87500	322	DELAY_2:	MOV	AX,DELAY_VAL
0933	48	323	AGAIN_AND_AGAIN:	DEC	AX
0934	3D0000	324		CMP	AX,0
0937	75FA	325		JNE	AGAIN_AND_AGAIN
0939	C3	326		RET	
		327			
093A	B850C3	328	DELAY_3:	MOV	AX,500000
093D	48	329	OVER_AND_OVER:	DEC	AX
093E	3D0000	330		CMP	AX,0
0941	75FA	331		JNE	OVER_AND_OVER
0943	B850C3	332		MOV	AX,500000
0946	48	333	ONE_MORE_TIME:	DEC	AX
0947	3D0000	334		CMP	AX,0
094A	75FA	335		JNE	ONE_MORE_TIME
094C	C3	336		RET	
		337			
----		338	CODE	ENDS	
		339			
		340		END	

ASSEMBLY COMPLETE, NO ERRORS FOUND

APPENDIX D

COMPUTER GENERATED SOUND SYSTEMS PROGRAMS

```

LOC 08.)      SEQ      SOURCE STATEMENT

1              1 SEPTEMBER 1981
2
3
4              THIS PROGRAM WRITTEN IN INTEL 8748 ASSEMBLY LANGUAGE IS THE SOURCE
5 ; FOR SOUNDS PRODUCED DURING A SIMULATED DRAGON FIRING AND RESIDES IN EPROM
6 ; OF THE SOUND SYSTEM MICROCOMPUTER (SSM).  THESE SOUNDS ARE:
7
8 ;          1.  GYRO WIND UP
9 ;          2.  LAUNCH EXPLOSION
10 ;         3.  THRUSTER FIRINGS
11 ;         4.  IMPACT EXPLOSIONS
12 ;             A.  TARGET HIT
13 ;             B.  TARGET MISSED
14
15
16 ;          THE DFS PROCESSOR SENDS A FOUR BIT WORD WHICH IS DECODED BY THE
17 ; SSM INTO ONE OF THE ABOVE SOUNDS.  THE SSM IN TURN PASSES DATA BYTES TO
18 ; A GENERAL INSTRUMENTS AY-3-8910 PROGRAMMABLE SOUND GENERATOR (PSG).  THE
19 ; PSG INTERPRETS 14 DATA BYTES STORED IN THE LOWER 14 LOCATIONS OF AN ON
20 ; CHIP 16 BYTE REGISTER ARRAY AS A SOUND, THEREBY GENERATING AN ANALOG
21 ; SIGNAL.
22
23 ;*****
24
25 ;          INITIALIZATION ROUTINE
26
27          0000      ORG      0
28          0000 0409   JMP      ANIT
29
30          0003      ORG      3
31          0003 0401   JMP      DECODE
32
33          0007      ORG      7
34          0007 1606   JTF      TIMER
35
36          0009      ORG      09H
37          0009 445D   ANIT:    JMP      CAKAP
38          0008 65     INIT:    STOP    TCNT
39          000C 27     CLR      A
40          000D 62     MOV      T,A
41          000E 25     EN       TCNTI
42
43          000F 45     EN       I
44          0010 75     ENT0     CLK
45          0011 23FF   MOV      A,#0FFH
46          0013 39     OUTL     P1,A
47          0014 3A     OUTL     P2,A
48
49          0015 30B8   MOV      A,#0BH
50          0017 3C     MOVD     P4,A
51          0018 27     CLR      A
52          0019 3D     MOVD     P5,A

```

; INITIALIZE TIMER AND ENABLE INTERRUPT

; ENABLE INTERRUPT
; ENABLE CLOCK ON T0

; INITIALIZE PORTS 1 & 2

; INITIALIZE PORTS 4 & 5

LOC	HEX	SEQ	SOURCE STATEMENT
		53	
001A	996F	54	RESPG: ANL P1, #06FH ; RESET PSG'S
001C	8990	55	ORL F1, #090H
		56	
		57	
001E	80BF	58	FLIP: ANL P2, #0BFH ; SET FLIP/FLOPS
0020	8A40	59	ORL P2, #040H
		60	
		61	
		62	*****
		63	
		64	LOOP ROUTINE I.E. WAIT FOR INTERRUPT
		65	
0027	85	66	CLR F0
0028	27	67	CLR A
0024	893E	68	MOV P1, #03EH
0026	882F	69	MOV R0, #02FH
0028	80	70	MOV @R0, A
0029	0E	71	DEC R0
002A	80	72	MOV @R0, A
002B	06	73	DEC R0
002C	80	74	MOV @R0, A
002D	81	75	MOV @R1, A
002E	19	76	INC R1
002F	81	77	MOV @R1, A
0030	48	78	MOV R3, A
0031	81	79	MOV R4, A
0032	80	80	MOV R5, A
0033	05	81	SEL RB1
0034	86	82	MOV R0, A
0035	89	83	MOV R1, A
0036	8A	84	MOV R2, A
0037	8B	85	MOV R3, A
0038	8C	86	MOV R4, A
0039	8D	87	MOV R5, A
003A	8E	88	MOV R6, A
003B	8F	89	MOV R7, A
003C	05	90	SEL RB0
		91	
003D	882F	92	DRANG MOV R0, #02FH
003F	FA	93	MOV A, @R0
0040	0E3D	94	JZ DRANG
0041	27	95	CLR A
0042	80	96	MOV @R0, A
0044	5428	97	CALL DRAGON
		98	
0045	882F	99	INFIN MOV R0, #02FH
0047	FA	100	MOV A, @R0
0049	0E4E	101	JZ INFIN
		102	
004B	1434	103	CALL CHECK
		104	
004D	8820	105	MOV R0, #020H
004F	F0	106	MOV A, @R0
0050	81	107	MOV R4, A ; R4 GETS TIME

LOC	OBJ	SEQ	SOURCE STATEMENT
0051	5488	108	CALL ROPOP
0052	0676	109	JZ SINFIN
		110	
0055	AF	111	MOV R7, A ; R7 GETS COUNT
0056	B921	112	MOV R1, #021H
0058	F1	113	MOV A, R1
0059	AA	114	MOV R2, A
005A	14B4	115	CALL DELAY
005C	AA	116	MOV R2, A
005D	14B4	117	CALL DELAY
005F	B820	118	MOV R0, #020H
0061	B921	119	MOV R1, #021H
		120	
0062	F1	121 UNFIN	MOV A, R1
0064	20	122	XCH A, R0
0065	EF72	123	DJNZ R7, ANFIN
0067	B646	124	JF0 INFIN
0069	05	125	SEL RB1
006A	27	126	CLR A
006B	A6	127	MOV R0, A
006C	AE	128	MOV R3, A
006D	05	129	SEL RB0
006E	85	130	CLR F0
006F	45	131	CPL F0
0070	0446	132	JMP INFIN
		133	
0072	18	134 ANFIN	INC R0
0073	19	135	INC R1
0074	0463	136	JMP UNFIN
		137	
0076	B82E	138 SINFIN	MOV R0, #02EH ; LOCATION OF RB1R3 PREVIOUS
0078	F0	139	MOV A, R0
0079	067E	140	JZ SAFON
007B	AA	141	MOV R2, A
007C	14BF	142	CALL DALAY
007E	B820	143 SAFON	MOV R0, #020H ; LOCATION OF RB1R0 PREVIOUS
0080	F0	144	MOV A, R0
0081	0687	145	JZ SAVOB
0083	B8FF	146	MOV R2, #0FFH
0085	14BF	147	CALL DALAY
0087	05	148 SAVOB	SEL RB1
0088	FB	149	MOV A, R3
0089	05	150	SEL RB0
008A	B82E	151	MOV R0, #02EH
008C	AA	152	MOV R0, A
008D	05	153	SEL RB1
008E	FB	154	MOV A, R0
008F	05	155	SEL RB0
0090	08	156	DEC R0
0091	AA	157	MOV R0, A
0092	0446	158	JMP INFIN
		159	
0094	07	160 CHECK	DEC A
0095	0687	161	JNZ CHAK
0097	077F	162	MOV R0, #03EH

LOC	OBJ	SEQ	SOURCE STATEMENT
0099	FA	163	MOV A, @R0
009A	9FA	164	INZ DEX0
009C	16	165	INC R0
009D	FA	166	MOV A, @R0
009E	96E	167	INZ HEX0
009A	97	168	CHAK RETR
		169	
00A1	18	170	DEX0 INC R0
00A2	FA	171	MOV A, @R0
00A3	1A7	172	IZ DEXAA
00A5	446D	173	JMP CHAKP
00A7	14AF	174	DEXAA CALL GETTA
00A9	4477	175	JMP DUDEX
		176	
00AB	14AF	177	HEX0 CALL GETTA
00AD	443A	178	JMP HITEX
		179	
00AF	B820	180	GETTA MOV R0, #020H
00B1	FA	181	MOV A, @R0
00B2	AC	182	MOV R4, A
00B3	93	183	RETR
		184	
		185	
		186	*****
		187	
		188	DELAY SUBROUTINES
		189	
		190	
00B4	B908	191	DELAY: MOV R1, #8 ; DELAY = R2 X .01 SEC
00B6	B8FF	192	LOOP1 MOV R0, #0FFH
00B8	E8B8	193	LOOP2 DJNZ R0, LOOP2
00BA	E9B6	194	DJNZ R1, LOOP1
00BC	EAB4	195	DJNZ R2, DELAY
00BE	93	196	RETR
		197	
00EF	B8C8	198	DALAY: MOV R0, #0C8H ; DALAY = R2 X .001 SEC
00C1	E8C1	199	DLY DJNZ R0, DLY
00C3	EAEF	200	DJNZ R2, DALAY
00C5	93	201	RETR
		202	
		203	
		204	*****
		205	
		206	TIMER INTERRUPT SERVICE ROUTINE
		207	
		208	THE TIMER INCREMENTS EVERY 80USEC (T)
		209	R4 INCREMENTS EVERY 20MSEC
		210	R5 INCREMENTS EVERY 5.24 SEC
		211	
		212	
00C6	05	213	TIMER: SEL PB1
00C7	AD	214	MOV R5, A
00C8	1C	215	INC R4
		216	
00C9	1F	217	INC R6

	PC	SOURCE STATEMENT		
207	MOV	R1, R5		
208	JNZ	00E0		
209	INC	R7		
210	00E0	MOV	R1, R5	
211	SEL	R0, R0		
212	REF			
213				
214				
215	*****			
216				
217				
218	EXTERNAL INTERRUPT SERVICE ROUTINE	DECODE LOWER 3 BITS OF 4 BIT		
219	WORD FROM DFS PROCESSOR	FLIP/FLOP'S LATCH WORD ONTO PORT 1		
220				
221				
222	DECODE	SEL	R0, R1	
223		MOV	R5, R1	
224		IN	R1, P1	
225		ANL	R1, #7	
226				
227		JZ	0000	INTI BANG
228		DEC	R1	
229		MOV	R1, #03EH	
230		JZ	0001	GND DUD
231		DEC	R1	
232		JZ	0010	GND EXPLO
233		DEC	R1	
234		JZ	0011	MISS EXPLO
235		DEC	R1	
236		JZ	1000	HIT EXPLO
237		DEC	R1	
238		JZ	1001	ROCK POP
239				
240		JMP	PUPP	
241				
242		MOV	R1, #0000	STOP TIMER
243		JMP	0000	
244		MOV	R1, #0000	STOP TIMER
245		JMP	HITE	
246		JMP	ROP0	
247				
248		MOV	R1, #02FH	PSG#1
249		INC	@R1	
250		JMP	PUPPET	
251		INC	@R1	
252		INC	R1	
253		INC	@R1	
254		MOV	R1, #02FH	PSG#1
255		INC	@R1	
256		JMP	PUPP	PSG#2
257		INC	@R1	
258		JMP	ROP0	PSG#2
259		INC	R1	
260		INC	@R1	PSG#2
261		MOV	R1, #02FH	
262		INC	@R1	
263		JMP	PUPP	
264		INC	@R1	
265		JMP	ROP0	
266		INC	R1	
267		INC	@R1	PSG#2
268		MOV	R1, #02FH	
269		INC	@R1	

LOC	HEX	SEQ	SOURCE STATEMENT
		273	
0106 F1		274	MOV A, R01
0109 AA		275	MOV R2, A ; R2 GETS COUNT
010A B920		276	MOV R1, #020H ; R1 GETS ADDRESS
010C FC		277	MOV A, R4 ; ACC GETS TIME
		278	
010D E812		279	POSS: DJNZ R2, POSS
010F A1		280	MOV @R1, A
0110 2415		281	JMP PASS
		282	
0112 14		283	POSS: INC P1
0113 2400		284	JMP PASS
		285	
0115 B000		286	PASS: MOV R4, #0
0117 FD		287	PUPP: MOV A, R5
0118 05		288	SEL R00
0119 43		289	RETR
		290	
011A 801E		291	FUPPET: JMI POKER
011C 2417		292	JMP PUPP
011E 2708		293	POKER: MOV A, #8
0120 07		294	MOV PSW, A
0121 15		295	DISE I
0122 E864		296	MOV R2, #1000
0124 14B4		297	CALL DELAY
0126 040E		298	JMP INIT
		299	
		300	
		301	*****
		302	
		303	SUBROUTINE TO CHECK TIMER AND GIVE ASSOCIATED DELAY AND AMPLITUDE
		304	DECAY
		305	
0128 05		306	TSTR45: SEL R00
0129 B000		307	MOV R3, #0
012B BE0F		308	MOV R6, #0FFH
012D BF00		309	MOV R7, #0
012F 05		310	SEL PB1 ; CUMULATIVE DELAY SO FAR
0130 FB		311	MOV A, R3
0131 05		312	SEL R00
0132 0637		313	JZ TARC
0134 AA		314	MOV R2, A
0135 146F		315	CALL DELAY
0137 05		316	TARC: SEL RB1
0138 FB		317	MOV A, R0
0139 05		318	SEL R00
013A 064C		319	JZ TESTR4
013C B0FF		320	MOV R2, #0FFH
013E 146F		321	CALL DELAY
0140 244C		322	JMP TESTR4
		323	
		324	IF R5 = 1 THEN FLIGHT TIME = 5 243SEC
		325	AT LEAST THEN DELAY = 1 352SEC
		326	
		327	IF R5 = 2 THEN FLIGHT TIME = 10 406SEC
			AT LEAST THEN DELAY = 2 704SEC

LOC	SEQ	SOURCE STATEMENT	
	328		
	329		
M142 47	330	CLR C	
M144 FE	331	MOV A,R3	POBRS KEEPS INCREMENTAL DELAY
M146 10	332	SEL RB1	
M148 66	333	ADD A,R3	
M148 66	334	MOV R3,A	RB1R3 HOLDS CUMULATIVE DELAY
M148 66	335	INC TABR	
M148 66	336	INC PR	
M148 66	337	SEL RB0	
M148 66	338	RETF	
	339		
	340		
M148 66	341	TESTR4 SEL RB0	
M148 66	342	MOV A,R4	
M148 66	343	JB7 BIT7	
M148 66	344	JB6 BIT6	
M148 66	345	JB5 BIT5	
M148 66	346	JB4 BIT4	
M148 66	347	JB3 BIT3	
M148 66	348	JB2 BIT2	
M148 66	349	JB1 BIT1	
M148 66	350	JB0 BIT0	
M148 66	351	IMP TABAP	
	352		
M148 66	353	BIT7 MOV R2,#670	FOR BIT 7 TRAVEL = 2.621SEC
M148 66	354	CALL DELAY	THEREFORE DELAY = 676SEC
M148 66	355	MOV R2,#6	
M148 66	356	CALL DALAY	
M148 66	357	MOV R3,#680	
M148 66	358	IMP JP6	
	359		
M148 66	360	BIT6 MOV R2,#330	FOR BIT 6 TRAVEL = 1.311SEC
M148 66	361		THEREFORE DELAY = 338SEC
M148 66	362	CALL DELAY	
M148 66	363	MOV R2,#8	
M148 66	364	CALL DALAY	
M148 66	365	MOV A,R3	
M148 66	366	ADD A,#340	
M148 66	367	MOV R3,A	
M148 66	368	MOV A,R4	
M148 66	369	IMP JP5	
	370		
M148 66	371	BIT5 MOV R2,#1690	FOR BIT 5 TRAVEL = 655SEC
M148 66	372		THEREFORE DELAY = 1695SEC
M148 66	373	CALL DALAY	
M148 66	374	MOV A,R3	
M148 66	375	ADD A,#170	
M148 66	376	MOV R3,A	
M148 66	377	MOV A,R4	
M148 66	378	IMP JP4	
	379		
M148 66	380	BIT4 MOV R2,#840	TRAVEL = 228SEC DELAY = 884SEC
M148 66	381	CALL DALAY	
M148 66	382	MOV A,R3	

LOC	OBJ	SEQ	SOURCE STATEMENT
0176 4509	381	ADD	R, #90
0180 46	384	MOV	R3, R
018E FC	385	MOV	R, R4
018F 2456	386	JMP	J73
	387		
0191 842A	388	MOV	R2, #420
0193 146F	389	CALL	DALAY
0195 F6	390	MOV	R, R1
0196 0304	391	ADD	R, #4
0198 46	392	MOV	R3, R
0199 FC	393	MOV	R, R4
019A 2456	394	JMP	J72
	395		
019C 6415	396	MOV	R2, #210
019E 146F	397	CALL	DALAY
01A0 16	398	INC	R3
01A1 16	399	INC	R3
01A2 FC	400	MOV	R, R4
01A3 245A	401	JMP	JF1
	402		
01A5 840B	403	MOV	R2, #110
01A7 146F	404	CALL	DALAY
01A9 16	405	INC	R3
01AA FC	406	MOV	R, R4
01AB 245C	407	JMP	JF0
	408		
01AD 6405	409	MOV	R2, #50
01AF 146F	410	CALL	DALAY
01B1 16	411	INC	R3
	412		
	413		
	414		AMPLITUDE DECAY IS DEPENDENT ON THE TOTAL TIME STORED
	415		IN REGISTERS RB1R6 (20 MSEC PER BIT) AND PB1P7.
	416		
	417		
01B2 05	418	TARAP: SEL	RB1
01B3 FF	419	MOV	R, R7
01B4 C5	420	SEL	RB0
01B5 C6C0	421	JZ	TRAP
01B7 07	422	DEC	R
01B8 C6BE	423	JZ	TRIP
01EA 6E02	424	MOV	R6, #2
01EA 2442	425	JMP	TAR
01BE BE0E	426	TRIP: MOV	R6, #8
01C0 05	427	TRAP: SEL	RB1
01C1 FE	428	MOV	R, R6
01C2 C5	429	SEL	RB0
01C3 F20F	430	JB7	BAT7
01C5 02E6	431	PB6: JB6	BAT6
01C6 02EF	432	PB5: JB5	BAT5
01C7 02F7	433	PB4: JB4	BAT4
01C8 02FF	434	PB3: JB3	BAT3
01C9 5205	435	PB2: JB2	BAT21
01CF 32D7	436	PB1: JB1	BAT11
01D1 12D9	437	PB0: JB0	BAT01

, TRAVEL = 1645SEC DELAY = .042SEC

, TRAVEL = .002SEC DELAY = .021SEC

, TRAVEL = .041SEC DELAY = .011SEC

, TRAVEL = .020SEC DELAY = .005SEC

, TRAVEL=10 486 SEC

LOC	HEX	OP	STMT
438		IMF	TRAMP
439			
440 BAT21		IMF	BAT2
441 BAT11		IMF	BAT1
442 BAT01		IMF	BAT0
443			
444 PBV		SEL	RB1
445		MOV	R.P6
446		SEL	PB0
447		PETR	
448			
449 BAT7		DEC	R6
450		DEC	R6
451		DEC	R6
452		MOV	R7 #420
453		IMF	PB6
454			
455 BAT6		DEC	R6
456		MOV	R.#570
457		ADD	R.P7
458		MOV	R7.A
459		CALL	PBY
460		IMF	PB5
461			
462 BAT5		MOV	R.#660
463		ADD	R.P7
464		MOV	R7.A
465		CALL	PBY
466		JMP	PB4
467			
468 BAT4		MOV	R.#330
469		ADD	R.P7
470		MOV	R7.A
471		CALL	PBY
472		IMF	PB3
473			
474 BAT3		MOV	R.#160
475		ADD	R.P7
476		MOV	R7.A
477		CALL	PBY
478		JMP	PB2
479			
480 BAT2		MOV	R.#8
481		ADD	R.P7
482		MOV	R7.A
483		CALL	PBY
484		IMF	PB1
485			
486 BAT1		INC	R7
487		INC	R7
488		INC	R7
489		INC	R7
490		JMP	PB0
491			
492 BAT0		INC	R7

LOC	HEX	SEQ	SOURCE STATEMENT
0210 1F	493	INC	R7
	494		
	495		
0211 FF	496	TRAMP	MOV A, R7
	497		
	498		FOR FURTHER AMPLITUDE CONTROL R7 IS NOW TESTED
	499		
0218 F21E	500	JB7	BEB
021A 0225	501	TAP1	BEB
021C 2442	502	JMP	TAR
	503		
021E 0E	504	BEA	DEC R6
021F 537F	505	ANL	A, #07FH ; - 1280MSEC
0221 0336	506	ADD	A, #54D ; + 540MSEC
0223 441A	507	JMP	TAP1
	508		
0225 0E	509	BEB	DEC R6
0226 2442	510	JMP	TAR
	511		
	512		
	513	*****	
	514		
	515		ROUTINE TO INITIATE INTERNAL TIMER & GIVE
	516		INITIAL LAUNCH EXPLOSION
	517		
	518		
0228 55	519	DRAGON	STPT T
	520		
0229 00	521	MOVX	A, @R0 ; START TIMER
	522		
022A 996F	523	ANL	P1, #06FH
022C 8990	524	ORL	P1, #090H ; RESET PSG'S
	525		
022E 9A0F	526	ANL	P2, #0DFH ; SELECT NO. 1
	527		
	528	LOAD	PSG #1
	529		
	530		
0230 8820	531	MOV	R0, #020H
0232 5F00	532	MOV	R7, #0300H ; BANG ON CHANNELS A, B & C OF PSG#1
	533		
0234 5438	534	CALL	LODRAM
	535		
0236 7400	536	CALL	LOADP1
	537		
0238 8A30	538	ORL	P2, #030H ; TRI-STATE
	539		
023A 91	540	RETR	
	541		
023B 2570	542	LODRAM	MOV A, #1350
023D 00	543	MOV	@R0, A ; R0
023E 18	544	INC	R0
023F 1100	545	MOV	A, #150
0241 00	546	MOV	@R0, A ; R1
0243 1F	547	INC	R0

LOC	HEX	REG	SOURCE STATEMENT
0240	7 50	548	MOV R, #1350
0241	00	549	MOV @R0, A ;R2
0242	18	550	INC R0
0243	2300	551	MOV R, #150
0244	00	552	MOV @R0, A ;R3
0245	18	553	INC R0
0246	2750	554	MOV R, #1250
0247	00	555	MOV @R0, A ;R4
0248	18	556	INC R0
0249	2000	557	MOV R, #150
0250	00	558	MOV @R0, A ;R5
0251	18	559	INC R0
0252	231F	560	MOV R, #370
0253	00	561	MOV @R0, A ;R6
0254	18	562	INC R0
0255	4F	563	MOV R, #7
0256	00	564	MOV @R0, A ;R7
0257	18	565	INC R0
0258	2010	566	MOV R, #200
0259	00	567	MOV @R0, A ;R8
0260	18	568	INC R0
0261	00	569	MOV @R0, A ;R9
0262	18	570	INC R0
0263	00	571	MOV @R0, A ;R10
0264	18	572	INC R0
0265	2 4F	573	MOV R, #0FFH
0266	00	574	MOV @R0, A ;R11
0267	18	575	INC R0
0268	233F	576	MOV R, #0770
0269	00	577	MOV @R0, A ;R12
0270	18	578	INC R0
0271	27	579	CLR A
0272	00	580	MOV @R0, A ;R13
0273	37	581	PETR
		582	
		583	
		584	*****
		585	
		586	THIS ROUTINE WAITS FOR A SYSTEM RESET TO START A NEW FLIGHT.
		587	
0274	2106	588	LAHF MOV R, #8
0275	07	589	MOV PSW, A
0276	13	590	DIS I
0277	8675	591	BRAVE INT COKOP
0278	4471	592	IMF BRAVE
0279	0408	593	COKOF IMP INIT
		594	
		595	
		596	*****
		597	
		598	THIS ROUTINE PRODUCES A DOUBLE EXPLOSION WHEN MISSILE
		599	HAS MISSED THE TARGET
		600	
0280	00EF	601	LDXEX ANL P2, #0EFH .SELECT PSG #2
		602	

LOC	OBJ	SEQ	SOURCE STATEMENT
0279	3420	603	CALL TSTR45 ;CALL DELAY AND AMPLITUDE
		604	
027B	8042	605	MOV R5, #2 ;LOOP COUNTER FOR AMP DECAY
		606	
027D	A5	607	CLR F1
		608	
027E	997F	609	ANL P1, #07FH
0280	8980	610	ORL P1, #080H ;RESET PSG #2
		611	
0282	8830	612	MOV R0, #030H
0284	8F03	613	MOV R7, #3110 ;MISS ON CHANNEL B & C ONLY (PSG#2)
		614	
0286	543B	615	CALL LODRAM
0288	7492	616	CALL HITAMP
028A	7423	617	CALL LOADP2
		618	
028C	8AFF	619	MOV R2, #0FFH
028E	146F	620	CALL DALAY
		621	
0290	7696	622	JF1 JIERT
0292	85	623	CPL F1
0293	0D	624	DEC P5
0294	447E	625	JMP CAKET
		626	
0296	8A20	627	JIERT ORL P2, #030H ;TRI-STATE
		628	
0298	446D	629	JMP CAKAP
		630	
		631	
		632	*****
		633	
		634	THIS ROUTINE PRODUCES A TRIPLE EXPLOSION WHEN MISSILE
		635	HITS THE TARGET.
		636	
029H	8003	637	HITEX MOV R5, #3 ;LOOP COUNTER
		638	
029H	420	639	CALL TSTR45 ;CALL DELAY AND AMPLITUDE
		640	
029E	7HEF	641	KAKOT ANL P2, #0EFH ;SELECT PSG #2
		642	
02A0	997F	643	ANL P1, #07FH
02A2	8980	644	ORL P1, #080H ;RESET PSG #2
		645	
02A4	8830	646	MOV R0, #030H
02A6	EF03	647	MOV R7, #3110 ;HIT ON CHANNEL B & C ONLY (PSG#2)
		648	
02A8	543B	649	CALL LODRAM
02AA	7492	650	CALL HITAMP
02AC	7423	651	CALL LOADP2
		652	
02AE	A5	653	ORL P2, #030H
		654	
02B0	8AFF	655	MOV R2, #0FFH
02B2	146F	656	CALL DALAY
		657	

LOC	ORG	SEQ	SOURCE STATEMENT
02E4	014E	658	DNZ P5,KAKOT
02E5	014E	659	
02E6	014E	660	JMP OAKAP
		661	
		662	
		663	*****
		664	
		665	THIS ROUTINE PRODUCES A SOUND SIMULATING THE IGNITION OF A
		666	SIDE ROCKET THRUSTER PAIR.
		667	
02E8	014E	668	ROPOP CALL TSTF45
		669	
02E9	014E	670	ANL P1,#07FH
02EA	014E	671	ORL P1,#080H
		672	RESET PSG #2
02EB	014E	673	ANL P2,#0EFH
		674	SELECT PSG #2
02EC	014E	675	MOV P0,#030H
02ED	014E	676	MOV A,#1350
02EE	014E	677	MOV @P0,A
02EF	014E	678	INC P0
02F0	014E	679	MOV A,#150
02F1	014E	680	MOV @R0,A
02F2	014E	681	INC R0
02F3	014E	682	MOV A,#1350
02F4	014E	683	MOV @P0,A
02F5	014E	684	INC P0
02F6	014E	685	MOV A,#150
02F7	014E	686	MOV @R0,A
02F8	014E	687	INC R0
02F9	014E	688	MOV A,#1350
02FA	014E	689	MOV @R0,A
02FB	014E	690	INC R0
02FC	014E	691	MOV A,#150
02FD	014E	692	MOV @R0,A
02FE	014E	693	INC R0
02FF	014E	694	MOV A,#370
0300	014E	695	MOV @R0,A
0301	014E	696	INC R0
0302	014E	697	MOV A,#3660
0303	014E	698	MOV @R0,A
0304	014E	699	INC R0
0305	014E	700	MOV A,#010H
0306	014E	701	MOV @R0,A
0307	014E	702	INC R0
0308	014E	703	MOV @R0,A
0309	014E	704	INC R0
030A	014E	705	MOV @R0,A
030B	014E	706	INC R0
030C	014E	707	MOV A,#1610
030D	014E	708	MOV @R0,A
030E	014E	709	INC R0
030F	014E	710	MOV A,#30
0310	014E	711	MOV @R0,A
0311	014E	712	INC R0

LOC	OBJ	SEQ	SOURCE STATEMENT
02F2 37	717	CLR	A
02F3 80	718	MOV	@R0, A ; P13
	719		
02F4 744H	716	CALL	POFAMP
02F6 7425	717	CALL	LOADP2
	718		
02FA 8A00	719	ORL	P2, #030H
	720		
02FB 60CF	721	MOV	R0, #02FH
02FC 80	722	MOV	A, @R0
02FD 0	723	DEC	A
02FE 80	724	MOV	@R0, A
	725		
02FF 93	726	RETR	
	727		
	728		
	729	*****	
	730		
	731	SUBROUTINE TO LOAD PSG#1 FROM MEMORY LOCATIONS	
	732	20H TO 20H CORRESPONDING TO REGISTERS 0 TO 13 OF PSG#1.	
	733		
0300 741F	734	LOADP1	ANL P2, #07FH
	735		
0302 03	736	SEL	R00
0303 8920	737	MOV	R1, #020H
0305 8A00	738	MOV	R2, #0
0307 8B0E	739	MOV	R3, #140
	740		
0309 741H	741	JACKO	CALL LADP1
030B EB16	742	DJNZ	R3, THERE
030D 8A00	743	ORL	P2, #050H
030F 8920	744	MOV	R1, #020H
0311 27	745	CLF	A
0312 A1	746	MOV	@R1, A
0313 19	747	INC	R1
0314 A1	748	MOV	@R1, A
	749		
0315 93	750	RETR	
	751		
0316 19	752	THERE	INC R1
0317 1A	753	INC	R2
0318 6405	754	JMP	JACKO
	755		
031A 8920	756	LADP1	ORL P1, #020H
031C FH	757	MOV	A, R2
031E 90	758	MOVX	@R0, A
031E 990F	759	ANL	P1, #0DFH
0320 F1	760	MOV	A, @R1
0321 90	761	MOVX	@R0, A
0322 97	762	RETR	
	763		
	764		
	765	*****	
	766		
	767	SUBROUTINE TO LOAD PSG#2 FROM MEMORY LOCATIONS	

LOC	DEF	SEQ	SOURCE STATEMENT
		768	30 TO 30 CORRESPONDING TO REGISTERS 0 TO 14 OF P5042
		769	
0023	49F7	770	LOADP2 ANL P1, #0F7H
		771	
0024	05	772	SEL RB0
0026	89D0	773	MOV R1, #030H
0028	8A00	774	MOV R2, #0
002A	8B0E	775	MOV R3, #140
		776	
002C	74 7	777	LAPOR: CALL LADP2
002E	EB01	778	DJNZ R3, HERE
0030	8A0E	779	ORL P1, #08H
		780	
0032	90	781	RETP
		782	
0034	19	783	HEPE INC R1
0034	1A	784	INC R2
0035	8421	785	JMP LAPOR
		786	
0037	8340	787	LADP2: ORL P1, #040H
0039	FA	788	MOV A, R2
003A	90	789	MOVX @R0, A
003B	946F	790	ANL P1, #0BFH
003D	F1	791	MOV A, @R1
003E	90	792	MOVX @R0, A
003F	4	793	RETP
		794	
		795	
		796	*****
		797	
		798	DECODE REGISTER R6 TO DETERMINE PROPER AMPLITUDE FOR A
		799	THRUSTER ROCKET SOUND. 1 OF 13 POSSIBLE AMPLITUDES DECREAYING
		800	LOGARITHMICALLY
		801	
0040	78	802	POPANF JEL P60
0041	FE	803	MOV A, R6
0042	520F	804	ANL A, #0FH
0044	7268	805	JB3 POPA
0046	5252	806	JB2 POPB
0048	124E	807	JB0 POPC
004A	23B8	808	MOV A, #088H
004C	648E	809	JMP CAMPO
004E	13B1	810	POPC MOV A, #0B1H
0050	648E	811	JMP CAMPO
		812	
0052	325E	813	ROPB JEL POPD
0054	125A	814	JB0 POPE
0056	20A4	815	MOV A, #0A4H
0058	648E	816	JMP CAMFO
005A	23A7	817	POPE MOV A, #0A2H
005C	648E	818	JMP CAMFO
005E	1264	819	POPD JEL POPF
0060	23A1	820	MOV A, #0A1H
0062	648E	821	JMP CAMFO
0064	219F	822	ROPF MOV A, #098H

LOC	OP	SEP	SOURCE STATEMENT
0360 648E		823	JMP CAMPO
		824	
0361 548H		825 ROPH	JB2 ROPG
0362 728E		826	JB1 ROPH
0363 728E		827	JB0 ROPI
0364 2394		828	MOV A, #094H ; R6=8, LEVEL=9
0365 648E		829	JMP CAMPO
0366 2392		830 ROPI	MOV A, #092H ; =9, =10
0367 648E		831	JMP CAMPO
0368 1270		832 ROPH	JB0 ROPI
0369 2391		833	MOV A, #091H ; =10, =11
0370 648E		834	JMP CAMPO
0371 2388		835 ROPI	MOV A, #088H ; =11, =12
0372 648E		836	JMP CAMPO
		837	
0373 1260		838 ROPG	JB1 ROPK
0374 1288		839	JB0 POPL
0375 2784		840	MOV A, #084H ; R6=12, LEVEL=13
0376 648E		841	JMP CAMPO
0377 2382		842 POPL	MOV A, #082H ; =13, =14
0378 648E		843	JMP CAMPO
0379 0381		844 ROPK	MOV A, #081H ; =14, 15, =15
		845	
0380 30		846 CAMPO	MOV P5, A
0381 47		847	SWAP A
0382 30		848	MOV P4, A
0383 30		849 CHIK	RETR
		850	
		851	
		852	*****
		853	
		854	THIS ROUTINE DECODES REGISTER R6 TO DETERMINE IF THE MISSILE
		855	IS IN THE LOW RANGE (LESS THAN 333 METERS), MID RANGE (333 TO
		856	666 METERS), OR HIGH RANGE (GREATER THAN 666 METERS).
		857	
		858	THE AMPLITUDES OF 3 SUCCESSIVE EXPLOSIONS ARE SET FOR A TARGET
		859	HIT. A MISSED TARGET PRODUCES ONLY THE FIRST TWO EXPLOSIONS.
		860	
0390 05		861 HITAMP	SEL R00
0391 FE		862	MOV A, R6
0392 728E		863	JB3 HADU
0393 5281		864	JB2 HITU
		865	
0394 40		866 MARY	MOV A, R5
0395 40		867	DEC A
0396 038E		868	JZ JOHN3 ; R6=2, 3, 4, 5 3RD EXPL0 HIGH RANGE
0397 40		869	DEC A
0398 0385		870	JZ JOHN2 ; 2ND EXPL0
0399 4041		871	JMP JOHN1 ; 1ST EXPL0
		872	
0400 038E		873 HITU	JB1 HOAX
0401 448E		874	JMP MARY
		875	
0402 40		876 HOAX	MOV A, R5
0403 40		877	DEC A

LOC	OBJ	SEQ	SOURCE STATEMENT					
03A7	060D	878	JZ	JOHN4	, R6=6, .10	3RD EXPLO	MID RANGE	
03A8	07	879	DEC	A				
03A9	060D	880	JZ	JOHN2		2ND EXPLO		
03AC	040C1	881	JMP	JOHN1		1ST EXPLO		
		882						
03BE	52E8	883	HARDU	JB2	HOPE			
03B0	32E4	884	JB1	HADE				
03B2	64A5	885	JMP	HORAX				
03B4	12B8	886	HADE	JB0	HOPE			
03B6	64A5	887	JMP	HORAX				
		888						
03E8	07	889	HOPE	MOV	A, R5			
03E9	07	890	DEC	A				
03BA	060D	891	JZ	JOHN4	, R6=11, .15	3RD EXPLO	LOW RANGE	
03BC	07	892	DEC	A				
03BD	060D	893	JZ	JOHN3		2ND EXPLO		
03BF	64C5	894	JMP	JOHN2		1ST EXPLO		
		895						
03C1	230F	896	JOHN1	MOV	A, #0FH		SOUND LEVEL 1 (LOWEST)	
03C2	3C	897	MOV	P4, A				
03C4	91	898		RETR				
03C5	230E	899	JOHN2	MOV	A, #0EH		SOUND LEVEL 2	
03C7	3C	900		MOV	P4, A			
03C8	93	901		RETR				
03C9	230D	902	JOHN3	MOV	A, #0CH		SOUND LEVEL 3	
03CB	3C	903		MOV	P4, A			
03CC	91	904		RETR				
03CD	230C	905	JOHN4	MOV	A, #0CH		SOUND LEVEL 4 (LOUDEST)	
03CE	3C	906		MOV	P4, A			
03D0	91	907		RETR				
		908						
		909						
		910						
		911						
		912						
		913						
		914						
		915		END				

USER SYMBOLS

ANFIN	0072	ANIT	0009	BAT0	0215	BAT01	01D9	BAT1	020F	BAT11	01D7	BAT2	0207	BAT21	01D5
BAT3	01FF	BAT4	01F7	BAT5	01EF	BAT6	01E6	BAT7	01DF	BEA	021E	BEB	0225	BIT0	01F0
BIT1	01A5	BIT2	019C	BIT3	0191	BIT4	0186	BIT5	017E	BIT6	016C	BIT7	0160	BRAVE	0271
CANAF	026D	CAKET	027E	CAMP0	038E	CHAK	00A0	CHECK	0094	CHIK	0391	COKOP	0275	DELAY	00EF
DECODE	00D1	DELAY	00B4	DEXAA	00A7	DEX0	00A1	DLY	00C1	DRAGO	00F3	DRAGON	0228	DRANG	003D
DUEF	00F8	DUDEX	0277	DUDEX1	00EB	DUDEX0	0100	FLIP	001E	GETTA	00AF	HADE	0384	HARDU	02FE
HAFE	0373	HEX0	00AB	HITAMP	0392	HITE	0103	HITE1	00EE	HITEX	029A	HITU	03A1	HORAX	03A5
HUFE	0368	INFIN	0046	INIT	0008	JACK0	0309	JIERT	029E	JOHN1	03C1	JOHN2	03C5	JOHN3	03C9
JOHN4	01C0	JP0	015C	JP1	015A	JP2	0158	JP3	0156	JP4	0154	JP5	0152	JP6	0150
LAUT	029E	LADP1	031A	LADP2	0337	LAPOR	032C	LOADP1	0300	LOADP2	0323	LOADP3	0238	LOOP1	00B6
LOOP2	00E8	MARY	0398	OBLO	00CE	PASS	0115	PB0	01D1	PB1	01CF	PB2	01C0	PB3	01CB
PB4	01C9	PB5	01C7	PB6	01C5	PBY	01DB	PKER	011E	POSS	0112	PUPP	0117	PUPPET	011A
POSS	0100	RESPG	001A	POPA	0368	POPAMP	0340	ROPE	0352	ROPC	034E	ROPD	035E	ROPE	025A
ROPI	0364	ROPG	0380	ROPH	0376	ROPI	0372	ROPI	037C	ROPI	038C	ROPL	0388	ROPO	0105
ROPI1	00F1	ROPOP	02B8	SAFON	007E	SAVOB	0087	SINFIN	0076	TAP1	021A	TAP	0142	TAPAP	01B2

TAPE 0140 TARC 0137 TESTR4 0140 THERE 0316 TIMER 0006 TRAMP 0217 TRAP 0100 TRIP 01BE
TR45 0128 UNFIN 0063

ASSEMBLY COMPLETE. NO ERRORS

LOC	SEQ	SOURCE STATEMENT
	1	
	2	
	3	16 SEPTEMBER 1981
	4	
	5	
	6	THIS IS A PROGRAM TO TURN THE TURPET ON A TANK MODEL
	7	90 DEGREES, HOLD IT THERE FOR 1.5 SECONDS, AND RETURN IT
	8	
	9	
	10	INITIALIZATION
	11	
0000	12	ORG 0
0000 0409	13	JMP INIT
0000	14	ORG 3
0000 0419	15	JMP TURN
0009	16	ORG 9
0000 00FF	17	MOV A, #0FFH
0000	18	OUTL P1, A
0000 00FF	19	ANL P1, #0F7H ; RESET PSG
0000 0000	20	ORL P1, #0
0010 00	21	ENT0 CLK
0011 00	22	EN I
0012 00	23	TRIG IN A, P1
0013 9212	24	JB4 TRIG ; TEST P14 FOR TRIGGER PULSE
0015 14E8	25	CALL GYRO
0017 0412	26	JMP TRIG
	27	
	28	
	29	RUN TURPET FORWARD
	30	
0019 00FD	31	TURN ANL P1, #0FDH ; 1111/1101 = PORT 1
001B 0A00	32	MOV R2, #2000
001D 1404	33	CALL DELAY
001F 561F	34	WHITE1 JT1 WHITE1
0021 0900	35	ORL P1, #00
	36	
0023 1440	37	CALL SOUND
	38	
0025 0000	39	MOV R2, #1000
0027 1404	40	CALL DELAY
	41	
	42	
	43	RUN TURPET REVERSE
	44	
	45	
	46	
	47	
	48	
	49	
	50	
	51	
	52	
	53	
	54	
	55	
	56	
	57	
	58	
	59	
	60	
	61	
	62	
	63	
	64	
	65	
	66	
	67	
	68	
	69	
	70	
	71	
	72	
	73	
	74	
	75	
	76	
	77	
	78	
	79	
	80	
	81	
	82	
	83	
	84	
	85	
	86	
	87	
	88	
	89	
	90	
	91	
	92	
	93	
	94	
	95	
	96	
	97	
	98	
	99	
	100	

LOC	OBJ	SEQ	SOURCE STATEMENT	
0014 B905		51	DELAY MOV R1, #8	: DELAY = R2 X .01 SEC
0015 B8FF		54	LOOP1 MOV R0, #0FFH	
0016 E838		55	LOOP2 DJNZ R0, LOOP2	
001A E916		56	DJNZ R1, LOOP1	
0020 E814		57	DJNZ R2, DELAY	
003E 83		58	RET	
		59		
003F B808		60	DELAY MOV R0, #008H	: DELAY = R2 X .001 SEC
0041 E841		61	DAY DJNZ R0, DAY	
0043 E83F		62	DJNZ R2, DELAY	
0045 83		63	RET	
		64		
		65		
		66	THIS IS THE SOUND MAKING ROUTINE	
		67		
0046 99F7		68	SOUND ANL P1, #0F7H	: ALL PSG REGISTERS GET 0
0048 8908		69	ORL P1, #8	
		70		
004A B832		71	MOV R2, #500	
004C 1434		72	CALL DELAY	
		73		
004E B830		74	MOV R0, #030H	
0050 2000		75	MOV A, #0	
0052 80		76	MOV @R0, A	: R0
0054 18		77	INC R0	
0056 2336		78	MOV A, #0660	
0058 80		79	MOV @R0, A	: R7
005A 18		80	INC R0	
005C 2307		81	MOV A, #07H	
005E 80		82	MOV @R0, A	: R10
		83		
005B 8F48		84	MOV R7, #048H	: LOOP COUNTER
005D B830		85	MOV R0, #030H	
		86		
005F 8901		87	WHISTL ORL P1, #1	
0061 27		88	CLP A	
0062 90		89	MOVX @R0, A	
0064 99FE		90	ANL P1, #0FEH	
0066 FA		91	MOV A, @R0	
0068 90		92	MOVX @R0, A	: WRITE TO REGISTER R0
		93		
0067 8901		94	ORL P1, #1	
0069 2301		95	MOV A, #1	
006B 90		96	MOVX @R0, A	
006E 99FE		97	ANL P1, #0FEH	
006E 2301		98	MOV A, #1	
0070 90		99	MOVX @R0, A	: R1
		100		
0071 8901		101	ORL P1, #1	
0073 2306		102	MOV A, #6	
0075 90		103	MOVX @R0, A	
0076 99FF		104	ANL P1, #0FFH	
0078 170F		105	MOV A, #170	
007A 90		106	MOVX @R0, A	: R6
		107		

LOC	OBJ	SEQ	SOURCE STATEMENT
007B 8901	108	OPL	P1. #1
007D 2307	109	MOV	R. #7
007F 90	110	MOVX	@R0, R
0080 99FE	111	ANL	P1. #0FEH
0082 18	112	INC	R0
0083 F0	113	MOV	R. @R0
0084 90	114	MOV	@R0, R
	115		
0085 8901	116	OPL	P1. #1
0087 2308	117	MOV	R. #100
0089 90	118	MOVX	@R0, R
008A 99FE	119	ANL	P1. #0FEH
008C 18	120	INC	R0
008D F0	121	MOV	R. @R0
008E 90	122	MOVX	@R0, R
	123		
008F 8A07	124	MOV	R2. #7
0091 143F	125	CALL	DELAY
	126		
0092 EF97	127	DJNZ	R7. CONT
0095 849C	128	JMP	EXPLO
0097 8830	129 CONT	MOV	R0. #030H
0099 18	130	INC	@R0
009A 045F	131	JMP	WHITSL
	132		
009C 8901	133 EXPLO	OPL	P1. #1
009E 27	134	CLR	R
009F 90	135	MOVX	@R0, R
00A0 99FE	136	ANL	P1. #0FEH
00A2 2150	137	MOV	R. #1350
00A4 90	138	MOVX	@R0, R
	139		
00A5 8901	140	OPL	P1. #1
00A7 2301	141	MOV	R. #1
00A9 90	142	MOVX	@R0, R
00AA 99FE	143	ANL	P1. #0FEH
00AC 2300	144	MOV	R. #150
00AE 90	145	MOVX	@R0, R
	146		
00AF 8901	147	OPL	P1. #1
00B1 2306	148	MOV	R. #6
00B3 90	149	MOVX	@R0, R
00B4 99FE	150	ANL	P1. #0FEH
00B6 231F	151	MOV	R. #370
00B8 90	152	MOVX	@R0, R
	153		
00B9 8901	154	OPL	P1. #1
00BB 2307	155	MOV	R. #7
00BD 90	156	MOVX	@R0, R
00BE 99FE	157	ANL	P1. #0FEH
00C0 2316	158	MOV	R. #0560
00C2 90	159	MOVX	@R0, R
	160		
00C3 8901	161	OPL	P1. #1
00C5 2308	162	MOV	R. #8

P7

P10

7 MSEC PER STEP

WRITE TO REGISTER R0

P1

P6

P7

LOC	OBJ	SEQ	SOURCE STATEMENT	
0007	90	163	MOVX @R0, A	
0008	99FE	164	ANL P1, #0FEH	
0009	2310	165	MOV A, #0200	
000C	90	166	MOVX @R0, A	R10
		167		
000D	8901	168	ORL P1, #1	
000F	2308	169	MOV A, #120	
0001	90	170	MOVX @R0, A	
0002	99FE	171	ANL P1, #0FEH	
0004	23FF	172	MOV A, #0FFH	
0006	90	173	MOVX @R0, A	R13
		174		
0007	8901	175	ORL P1, #1	
0009	230C	176	MOV A, #140	
000B	90	177	MOVX @R0, A	
000C	99FE	178	ANL P1, #0FEH	
000E	233F	179	MOV A, #0770	
0009	90	180	MOVX @R0, A	R14
		181		
000E	8901	182	ORL P1, #1	
000F	230C	183	MOV A, #150	
0005	90	184	MOVX @R0, A	
0006	99FE	185	ANL P1, #0FEH	
0008	27	186	CLR A	
0009	90	187	MOVX @R0, A	R15
		188		
000A	83	189	RET	
		190		
		191		
000B	8A0A	192	GYRO MOV R2, #100	
000D	1434	193	CALL DELAY	
		194		
000F	8901	195	ORL P1, #1	
0001	2302	196	MOV A, #2	
0003	90	197	MOVX @R0, A	
0004	99FE	198	ANL P1, #0FEH	
0006	23FF	199	MOV A, #0FFH	
0008	90	200	MOVX @R0, A	R2
		201		
0009	8901	202	ORL P1, #1	
000B	2303	203	MOV A, #3	
000D	90	204	MOVX @R0, A	
000E	99FE	205	ANL P1, #0FEH	
0100	2303	206	MOV A, #3	
0102	90	207	MOVX @R0, A	R3
		208		
0103	8901	209	ORL P1, #1	
0105	2304	210	MOV A, #4	
0107	90	211	MOVX @R0, A	
0108	99FE	212	ANL P1, #0FEH	
010A	23FF	213	MOV A, #0FFH	
010C	90	214	MOVX @R0, A	R4
		215		
010D	8901	216	ORL P1, #1	
010F	2305	217	MOV A, #5	

B = 4X FREQ

LOC	OBJ	SEQ	SOURCE STATEMENT
0111	90	218	MOVX @R0, A
0112	99FE	219	ANL P1, #0FEH
0114	230F	220	MOV A, #0FH
0116	90	221	MOVX @R0, A
		222	
0117	8901	223	ORL P1, #1
0119	2306	224	MOV A, #6
011B	90	225	MOVX @R0, A
011C	99FE	226	ANL P1, #0FEH
011E	230F	227	MOV A, #0FH
0120	90	228	MOVX @R0, A
		229	
0121	8901	230	ORL P1, #1
0123	2307	231	MOV A, #7
0125	90	232	MOVX @R0, A
0126	99FE	233	ANL P1, #0FEH
0128	2309	234	MOV A, #3110
012A	90	235	MOVX @R0, A
		236	
012B	8901	237	ORL P1, #1
012D	2309	238	MOV A, #110
012F	90	239	MOVX @R0, A
0130	99FE	240	ANL P1, #0FEH
0132	230F	241	MOV A, #0FH
0134	90	242	MOVX @R0, A
		243	
0135	8901	244	ORL P1, #1
0137	230A	245	MOV A, #120
0139	90	246	MOVX @R0, A
013A	99FE	247	ANL P1, #0FEH
013C	230F	248	MOV A, #0FH
013E	90	249	MOVX @R0, A
		250	
013F	BA32	251	MOV R2, #500
0141	1434	252	CALL DELAY
		253	
0143	99F7	254	ANL P1, #0F7H
0145	8908	255	ORL P1, #8
		256	
0147	83	257	PET
		258	
		259	
		260	
		261	
		262	
		263	END

USER SYMBOLS

CONT	0097	DELAY	003F	DAY	0041	DELAY	0034	EXPLO	009C	GYRO	00EB	INIT	0009	LOOP1	0036
LOOP2	0038	SOUND	0046	TRIG	0012	TURN	0019	WHISTL	005F	WHITE1	001F	WHITE2	002F		

ASSEMBLY COMPLETE, NO ERRORS